On WW2 Propagation of deep water waves

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Lausanne, April 29, 2022

Joint work with Benjamin Melinand (Paris Dauphine)

where |D|

Instabilities 00000 Rectification 0000000

The model

$$\begin{cases} \partial_t \zeta - |D|\psi + \epsilon |D|(\zeta |D|\psi) + \epsilon \nabla \cdot (\zeta \nabla \psi) = 0, \\ \partial_t \psi + \zeta + \frac{\epsilon}{2} \left(|\nabla \psi|^2 - (|D|\psi)^2 \right) = 0, \\ = (-\Delta_{\mathbf{x}})^{1/2}, \, \mathbf{x} \in \mathbb{R}^d, \, d \in \{1, 2\}. \end{cases}$$
(WW2)

- (WW2) is a model for water waves in infinite depth, assuming small steepness, $\epsilon \ll 1$.
- (WW2) enjoys a Hamiltonian structure. In particular, it preserves

$$\int \zeta \, \mathrm{d}\mathbf{x}, \quad \int \zeta \nabla \psi \, \mathrm{d}\mathbf{x},$$

$$\mathcal{H}_1(\zeta,\psi) \stackrel{\text{def}}{=} \frac{1}{2} \int_{\mathbb{R}^d} \zeta^2 + \psi |D| \psi + \epsilon \zeta \left(|\nabla \psi|^2 - (|D|\psi)^2 \right) \, \mathsf{d} \mathbf{x}.$$

• (WW2) belongs to a hierarchy of models [Craig&Sulem '93] based on the converging asymptotic expansion

$$\mathcal{H}(\zeta,\psi) \stackrel{\text{def}}{=} \mathcal{H}_1(\zeta,\psi) + \frac{1}{2} \int_{\mathbb{R}^d} \epsilon^2 \psi \mathcal{G}_2[\zeta,\zeta] \psi + \epsilon^3 \psi \mathcal{G}_3[\zeta,\zeta,\zeta] \psi + \dots_{1/1}$$

Numerical instabilities

Numerical integration of the systems in the hierarchy are easily and efficiently implemented using Fourier spectral methods (as done in e.g. [Guyenne&Nicholls '07-08])

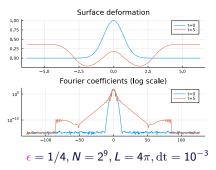
In the computations [...] it was observed that <u>spurious oscillations</u> can develop in the wave profile, due to the onset of an instability related to the growth of numerical errors at high wavenumbers. [...] Similar <u>high-wavenumber instabilities</u> were observed by other authors [...] who used smoothing techniques to circumvent this difficulty.

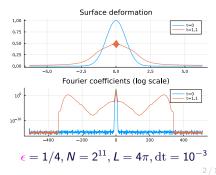
Instabilities 00000 Rectification

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In the computations [...] it was observed that <u>spurious oscillations</u> can develop in the wave profile, due to the onset of an instability related to the growth of numerical errors at high wavenumbers. [...] Similar <u>high-wavenumber instabilities</u> were observed by other authors [...] who used smoothing techniques to circumvent this difficulty.





Proposed instability mechanism

[Ambrose,Bona&Nicholls '14] suggest that

$$\partial_t \zeta - |D|\psi + \epsilon |D|(\zeta |D|\psi) + \epsilon \nabla \cdot (\zeta \nabla \psi) = 0,$$

$$\partial_t \psi + \zeta + \frac{\epsilon}{2} \left(|\nabla \psi|^2 - (|D|\psi)^2 \right) = 0,$$

[and also (WW3)] is ill-posed in Sobolev spaces, based on

- tailored numerical experiments;
- the toy model

$$\partial_t \psi + \frac{\epsilon}{2} \left(|\nabla \psi|^2 - (|D|\psi)^2 \right) = 0.$$
 (toy)

[Ambrose,Bona&Nicholls '14]

For all $s \in [0, 3)$, the Cauchy problem associated with (toy) is ill-posed^a in $H^{s}(\mathbb{T})$.

^athere exists a sequence $(\psi_n)_{n\in\mathbb{N}}$ of smooth solutions to (toy) defined on $t\in[0, T_n)$ and such that $|\psi_n(0; \cdot)|_{H^s}\searrow 0$, $T_n\searrow 0$ as $n\to\infty$ and $|\psi_n(t, \cdot)|_{L^2}\to\infty$ as $t\nearrow T_n$.

Outline

Context

2 Instabilities

- Quasi-linearization
- Toy model
- Numerics
- 3 Rectification
 - Construction
 - Justification

Instabilities ••••• Rectification

Quasi-linearization

$$egin{aligned} &\partial_t \zeta - |D|\psi + \epsilon |D|(\zeta |D|\psi) + \epsilon
abla \cdot (\zeta
abla \psi) &= 0, \ &\partial_t \psi + \zeta + rac{\epsilon}{2} \left(|
abla \psi|^2 - (|D|\psi)^2
ight) &= 0, \end{aligned}$$

(WW2)

Compensation Lemma [Saut&Xu '12]

Let $d \in \{1,2\}$, $t_0 > d/2$. For all $r \leq 1$ and $s \geq t_0 + r$,

 $\left| |D|(f|D|g) + \nabla \cdot (f \nabla g) \right|_{H^s} \lesssim \left| \nabla f \right|_{H^s} \left| \nabla g \right|_{H^{s-r}}.$

Proof (d = 1). Denote $a = |D|(f|D|g) + \partial_x(f\partial_x g)$. For $\xi \ge 0$,

 $\widehat{a}(\xi) = \int_{\mathbb{R}} \left(|\xi| |\xi - \eta| - \xi(\xi - \eta) \right) \widehat{f}(\eta) \widehat{g}(\xi - \eta) \, \mathrm{d}\eta = 2 \int_{\xi}^{\infty} \xi(\eta - \xi) \widehat{f}(\eta) \widehat{g}(\xi - \eta) \, \mathrm{d}\eta.$ Since $|\xi| < |\eta|$ and $|\eta - \xi| < |\eta|$, one has for all s > 0 and r' > 0

 $|\langle \xi
angle^s | \widehat{a}(\xi)| \leq 2 \int_{\mathbb{R}} \langle \eta
angle^{s+r'} |\eta| | \widehat{f}(\eta) | \langle \xi - \eta
angle^{-r'} | \xi - \eta| | \widehat{g}(\xi - \eta)| \, \, \mathrm{d}\eta.$

By Young's inequality and since $\langle \cdot
angle^{-t_0} \in L^2(\mathbb{R})$, with r' = 0,

 $\left| |D|(f|D|g) + \nabla \cdot (f \nabla g) \right|_{H^s} \lesssim \left| \partial_x f \right|_{H^s} \left| \partial_x g \right|_{H^{t_0}}.$

This shows the result, without restriction on r when d = 1.

Instabilities 00000

Quasi-linearization

$$\partial_t \zeta - |D|\psi + \epsilon |D|(\zeta |D|\psi) + \epsilon \nabla \cdot (\zeta \nabla \psi) = 0,$$

$$\partial_t \psi + \zeta + \frac{\epsilon}{2} \left(|\nabla \psi|^2 - (|D|\psi)^2 \right) = 0.$$

The principle part of the first equation is

$$\partial_t \dot{\zeta} - |D| \dot{\psi} + \epsilon |D| (\dot{\zeta} |D| \underline{\psi}) + \epsilon \nabla \cdot (\dot{\zeta} \nabla \underline{\psi}) = 0.$$

The principle part of the second equation is

 $\partial_t \dot{\psi} + \dot{\zeta} + \epsilon (\nabla \underline{\psi}) \cdot (\nabla \dot{\psi}) - \epsilon (|D|\underline{\psi}) (|D|\dot{\psi}) = 0.$

One recognizes Alinhac's good unknown: $\check{\psi} \stackrel{\text{def}}{=} \dot{\psi} - \epsilon(|D|\psi)\dot{\zeta}$:

$$\begin{cases} \partial_t \dot{\zeta} - |D| \check{\psi} + \epsilon \nabla \cdot (\dot{\zeta} \nabla \underline{\psi}) = 0, \\ \partial_t \check{\psi} + \mathfrak{a}[\underline{\zeta}, \underline{\psi}] \dot{\zeta} + \epsilon (\nabla \underline{\psi} \cdot \nabla \check{\psi}) = 0, \end{cases}$$
(Q-WW2)

$$\mathfrak{a}[\underline{\zeta},\underline{\psi}]f \stackrel{\text{def}}{=} \underbrace{f - \epsilon(|D|\underline{\zeta})f}_{a(\underline{\zeta})f} - \epsilon^2 \underbrace{(|D|\underline{\psi})|D|\{(|D|\underline{\psi})f\}}_{\underline{z}}.$$

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Quasi-linearization

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$$\mathfrak{a}[\underline{\zeta},\underline{\psi}]f \stackrel{\text{def}}{=} \underbrace{f - \epsilon(|D|\underline{\zeta})f}_{\mathfrak{a}(\underline{\zeta})f} - \epsilon^2 \underbrace{(|D|\underline{\psi})|D|\{(|D|\underline{\psi})f\}}_{\underline{\mathfrak{a}}(\underline{\zeta})f}.$$

Instabilities ○○○●○

Toy model

Rectification

We mimic

$$\begin{cases} \partial_t \dot{\zeta} - |D| \check{\psi} + \epsilon \nabla \cdot (\dot{\zeta} \nabla \underline{\psi}) = 0, \\ \partial_t \check{\psi} + \mathfrak{a}[\underline{\zeta}, \underline{\psi}] \dot{\zeta} + \epsilon (\nabla \underline{\psi} \cdot \nabla \check{\psi}) = 0, \end{cases}$$
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$$\begin{cases} \partial_t \zeta - |D|\psi = 0, \\ \partial_t \psi + (1 - \alpha[\psi]|D|)\zeta = 0, \end{cases}$$

$$\alpha[\psi] \stackrel{\text{def}}{=} \epsilon^2 \int (|D|\psi)^2 \, \mathrm{d}\mathbf{x}.$$
 (toy)

Instabilities

Toy model

Rectification 0000000

$$\begin{cases} \partial_t \zeta - |D|\psi = 0, \\ \partial_t \psi + (1 - \alpha[\psi]|D|)\zeta = 0, \end{cases} \qquad \alpha[\psi] \stackrel{\text{def}}{=} \epsilon^2 \int (|D|\psi)^2 \, \mathrm{d}\mathbf{x}. \quad (\text{toy})$$

Ill-posedness in $H^{\infty}(\mathbb{T}^d)$ [D-Melinand] For all $\epsilon > 0$, there exists $(\zeta_n, \psi_n)_{n \in \mathbb{N}}$ smooth solutions to (toy) defined on $[0, T_n)$ with

$$\forall s \in \mathbb{R}, \ \left| \zeta_n \right|_{t=0} \left|_{H^s(\mathbb{T}^d)} + \left| \psi_n \right|_{t=0} \right|_{H^s(\mathbb{T}^d)} \searrow 0 \quad \text{and} \quad T_n \searrow 0 \quad (n \to \infty),$$

and

$$\forall s' \in \mathbb{R}, \qquad \left| \psi^n(t, \cdot) \right|_{H^{s'}(\mathbb{T}^d)} \to \infty \quad (t \nearrow T_n).$$

<u>Proof.</u> We put $\zeta_n|_{t=0} = 0$ and $\psi_n|_{t=0} = b_n \cos(\mathbf{k}_0 \cdot \mathbf{x}) + c_n \cos(\mathbf{k}_n \cdot \mathbf{x})$ where $\mathbf{k}_0 \neq \mathbf{0}, \ |\mathbf{k}_n| \nearrow \infty, \ b_n = |\mathbf{k}_n|^{-1/4}, \ c_n = \exp(-|\mathbf{k}_n|^{1/4}).$

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Instabilities

Toy model

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Ill-posedness in $H^{\infty}(\mathbb{T}^d)$ [D-Melinand]

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$$\mathbf{k}_0 \neq \mathbf{0}, \; |\mathbf{k}_n| \nearrow \infty, \; b_n = |\mathbf{k}_n|^{-1/4}, \; c_n = \exp(-|\mathbf{k}_n|^{1/4}).$$

By studying the system of ODEs on Fourier coefficients, we observe successively

- low-high instabilities: $\alpha[\psi]|\mathbf{k}_0| < 1$ but $\alpha[\psi_0]|\mathbf{k}_n| > 2 \Rightarrow c_n(t) \geq \frac{c_n}{8}e^{|\mathbf{k}_n|^{1/2}t}$,
- high-high instabilities: $c_n(t) \gtrsim |\mathbf{k}_n|^{-1} \Rightarrow \alpha[\psi_n] |\mathbf{k}_n| > 2 \Rightarrow c_n(t) \geq \frac{c_n}{8} e^{|\mathbf{k}_n|^{1/2}t}$
- high-high blow-up: $c_n(t) \gtrsim 1 \Rightarrow \frac{d}{dt} \widehat{\psi}_{\mathbf{k}_n}^n \geq \frac{1}{4} |\mathbf{k}_n|^{1/2} \widehat{\psi}_{\mathbf{k}_n}^n(t)^2 \Rightarrow \text{blow-up.}$

Instabilities

Rectification

Numerical validation

Numerical integration of (WW2) initial data

 $\zeta(t=0,x)=0$ et $\psi'(t=0,x)=\left(\sin(x)+rac{\sin(\mathcal{K}x)}{\mathcal{K}^2}
ight)\exp(-|x|^2).$

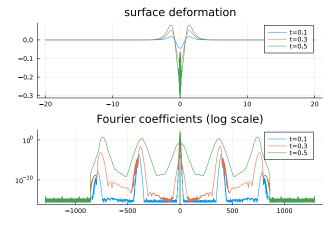


Figure: Time integration with $\epsilon = 1/5$, K = 400.

Instabilities

Rectification

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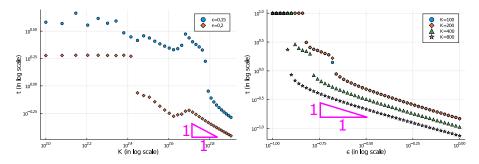


Figure: Blow-up time T^* depending on K and ϵ . The toy model predicts $T^* \propto (\epsilon K)^{-1}$ if $\epsilon^2 K \gg 1$.

Outline

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Instabilitie

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- Numerics



- Construction
- Justification

Quasi-linearization

$$\begin{cases} \partial_t \zeta - |D|\psi + \epsilon |D|(\zeta |D|\psi) + \epsilon \nabla \cdot (\zeta \nabla \psi) = 0, \\ \partial_t \psi + \zeta + \frac{\epsilon}{2} \left(|\nabla \psi|^2 - (|D|\psi)^2 \right) = 0. \end{cases}$$

Rectification

The principle part of the first equation is

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(Q-WW2)

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Quasi-linearization

$$\begin{split} \partial_t \zeta - |D|\psi + \epsilon |D|((\mathsf{J}\zeta)|D|\psi) + \epsilon \nabla \cdot ((\mathsf{J}\zeta)\nabla\psi) &= 0, \\ \partial_t \psi + \zeta + \frac{\epsilon}{2} \left(|\nabla \psi|^2 - (|D|\psi)^2 \right) &= 0. \end{split}$$

Rectification

The principle part of the first equation is

 $\partial_t \dot{\zeta} - |D| \dot{\psi} + \epsilon |D| ((\mathsf{J}\dot{\zeta})|D|\underline{\psi}) + \epsilon \nabla \cdot ((\mathsf{J}\dot{\zeta})\nabla \underline{\psi}) = \mathbf{0}.$

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$$\begin{cases} \partial_t \dot{\zeta} - |D| \check{\psi} + \epsilon \nabla \cdot ((\mathbf{J} \dot{\zeta}) \nabla \underline{\psi}) = \mathbf{0}, \\ \partial_t \check{\psi} + \mathfrak{a}_{\mathbf{J}}[\underline{\zeta}, \underline{\psi}] \dot{\zeta} + \epsilon (\nabla \underline{\psi} \cdot \nabla \check{\psi}) = \mathbf{0}, \end{cases}$$
(Q-WW2)

with

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$$\mathfrak{a}_{\mathsf{J}}[\underline{\zeta},\underline{\psi}]f \stackrel{\text{def}}{=} \underbrace{f - \epsilon(|D|\underline{\zeta})\mathsf{J}f}_{a(\underline{\zeta})\mathsf{J}f} - \epsilon^{2}\underbrace{(|D|\underline{\psi})\mathsf{J}|D|\{(|D|\underline{\psi})\mathsf{J}f\}}_{\odot}.$$

The regularized sysem

By plugging J = J(D) self-adjoint,

$$\begin{cases} \partial_t \zeta - |D|\psi + \epsilon |D|((\mathsf{J}\zeta)|D|\psi) + \epsilon \nabla \cdot ((\mathsf{J}\zeta)\nabla\psi) = 0, \\ \partial_t \psi + \zeta + \frac{\epsilon}{2}\mathsf{J}\left(|\nabla\psi|^2 - (|D|\psi)^2\right) = 0, \end{cases}$$
(RWW2)

enjoys a canonical hamiltonian structure, with

$$\mathcal{H}_{1}^{\mathsf{J}}(\zeta,\psi) \stackrel{\text{def}}{=} \frac{1}{2} \int_{\mathbb{R}^{d}} \zeta^{2} + \psi |D|\psi + \epsilon(\mathsf{J}\zeta) \left(|\nabla\psi|^{2} - (|D|\psi)^{2} \right) \, \mathsf{d}\mathbf{x}$$

Well-posedness [D-Melinand]

Let J = J(D) with $J \leq \langle \cdot \rangle^{-1}$. Let $s \geq d/2 + 1/2$. For all $(\zeta_0, \psi_0) \in H^s(\mathbb{R}^d) \times H^{s+1/2}(\mathbb{R}^d)$, there exists a unique maximal solution $(\zeta, \psi) \in \mathcal{C}((-T_\star, T^\star); H^s(\mathbb{R}^d) \times H^{s+1/2}(\mathbb{R}^d))$ to (RWW2), $(\zeta, \psi)|_{t=0} = (\zeta_0, \psi_0)$. Moreover, if $J \leq \langle \cdot \rangle^{-m}$, m > d/2 + 3/2 and ϵ small enough, then $T_\star = T^\star = +\infty$.

<u>Proof.</u> Compensation lemma [Saut&Xu'12] + Duhamel formula. For ϵ small enough, $\mathcal{H}_{1}^{\mathsf{J}}(\zeta, \psi) \approx |\zeta|_{L^{2}}^{2} + ||D|^{1/2}\psi|_{L^{2}}^{2}$ is preserved. Rectification

The cost of regularizing

Rectification

Consistency [D-Melinand]

If $J = J_0(\delta D)$ with $J_0 \in L^{\infty}(\mathbb{R}^d)$ and $|\cdot|^{-\ell}(1 - J_0) \in L^{\infty}(\mathbb{R}^d)$, then for all $\delta > 0$, s > d/2 and $(\zeta, \psi) \in C([0, T]; H^{\max(s+\ell+1,s+2)}(\mathbb{R}^d) \times H^{\max(s+\ell+\frac{3}{2})}(\mathbb{R}^d))$ solution to (RWW2), (ζ, ψ) satisfies (WW) up to remainder terms

$$\begin{split} & \left| R_0 \right|_{H^s \times H^{s+\frac{1}{2}}} \lesssim \epsilon^2 \left(\left| \zeta \right|_{H^{s+2}} + \left| \left| D \right|^{1/2} \psi \right|_{H^{s+1}} \right), \\ & \left| R_\mathsf{J} \right|_{H^s \times H^{s+\frac{1}{2}}} \lesssim \epsilon \, \delta^\ell \left(\left| \zeta \right|_{H^{s+\ell+1}} + \left| \nabla \psi \right|_{H^{s+\ell+\frac{1}{2}}} \right). \end{split}$$

Proof.

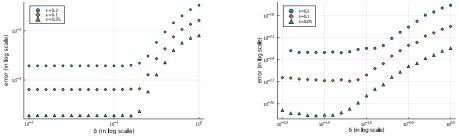
For R_0 , [Alvarez-Samaniego&Lannes'08]. For R_J , $|f - Jf|_{H^s} \leq C_\ell \delta^\ell |f|_{H^s}$, with $C_\ell = || \cdot |^{-\ell} (1 - J_0)|_{L^{\infty}}$.

The cost of regularizing

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Error between (RWW2) and (WW): smooth i.d. (left) and non-smooth i.d. (right).

Rectification

The gain of regularizing

Rectification

Large time well-posedness [D-Melinand]

Let $J_0 = J_0(|D|)$ with $\langle \cdot \rangle^{-1} J_0 \in L^{\infty}$, $\langle \cdot \rangle \nabla J \in L^{\infty}$. Let s > d/2 + 2, $s \in \mathbb{N}$, C > 1and M > 0. There exists $T_0 > 0$ such that for all $\epsilon > 0$, for all $(\zeta_0, \psi_0) \in H^s(\mathbb{R}^d) \times H^{s+\frac{1}{2}}(\mathbb{R}^d)$ with

$$0 < \epsilon M_0 \stackrel{\text{def}}{=} \epsilon \left(\left| \zeta_0 \right|_{H^s} + \left| |D|^{1/2} \psi_0 \right|_{H^s} \right) \le M,$$

and for all $\delta \geq \epsilon M_0$, one has: for all $J = J_0(\delta D)$, there exists a unique $(\zeta, \psi) \in C([0, T_0/(\epsilon M_0)]; H^s \times H^{s+\frac{1}{2}})$ solution to (RWW2), $(\zeta, \psi)|_{t=0} = (\zeta_0, \psi_0)$, with

 $\sup_{t\in [-T_0/(\epsilon M_0), T_0/(\epsilon M_0)]} \left(\left| \zeta(t, \cdot) \right|_{H^s}^2 + \left| |D|^{1/2} \psi(t, \cdot) \right|_{H^s}^2 \right) \leq C \left(\left| \zeta_0 \right|_{H^s}^2 + \left| |D|^{1/2} \psi_0 \right|_{H^s}^2 \right).$

Proof.

- If $\epsilon \gtrsim 1$, Duhamel formula $\Rightarrow T_0 \approx \delta$.
- If $\epsilon \ll 1$, energy method $\Rightarrow T_0 \approx \min(\{1, \delta/\epsilon\})$.

The gain of regularizing

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 $\sup_{t\in [-T_0/(\epsilon M_0), T_0/(\epsilon M_0)]} \left(\left| \zeta(t, \cdot) \right|_{H^s}^2 + \left| |D|^{1/2} \psi(t, \cdot) \right|_{H^s}^2 \right) \leq C \left(\left| \zeta_0 \right|_{H^s}^2 + \left| |D|^{1/2} \psi_0 \right|_{H^s}^2 \right).$

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Instabilities 00000 Rectification

Energy method

$$\begin{cases} \partial_t \zeta - |D|\psi + \epsilon |D|(\mathsf{J}\zeta)|D|\psi) + \epsilon \nabla \cdot ((\mathsf{J}\zeta)\nabla\psi) = 0, \\ \partial_t \psi + \zeta + \frac{\epsilon}{2}\mathsf{J}\left(|\nabla\psi|^2 - (|D|\psi)^2\right) = 0. \end{cases}$$

The principle part of the first equation is

 $\partial_t \dot{\zeta} - |D| \dot{\psi} + \epsilon |D| ((\mathsf{J}\dot{\zeta})|D|\underline{\psi}) + \epsilon \nabla \cdot ((\mathsf{J}\dot{\zeta})\nabla \underline{\psi}) = 0.$

The principle part of the second equation is

$$\partial_t \dot{\psi} + \dot{\zeta} + \epsilon(\nabla \underline{\psi}) \cdot \mathsf{J}(\nabla \dot{\psi}) - \epsilon(|D|\underline{\psi})\mathsf{J}(|D|\dot{\psi}) = 0.$$

One recognizes Alinhac's good unknown: $\check{\psi} \stackrel{\text{def}}{=} \dot{\psi} - \epsilon(|D|\psi)(\mathsf{J}\dot{\zeta})$:

$$\begin{cases} \partial_t \dot{\zeta} - |D| \check{\psi} + \epsilon \nabla \cdot ((\mathsf{J}\dot{\zeta}) \nabla \underline{\psi}) = \mathsf{0}, \\ \partial_t \check{\psi} + \mathfrak{a}_{\mathsf{J}}[\underline{\zeta}, \underline{\psi}] \dot{\zeta} + \epsilon (\nabla \underline{\psi} \cdot \mathsf{J} \nabla \check{\psi}) = \mathsf{0}, \end{cases}$$
(Q-RWW2)

with

$$\mathfrak{a}_{\mathsf{J}}[\underline{\zeta},\underline{\psi}]f \stackrel{\text{def}}{=} f - \epsilon(|D|\underline{\zeta})\mathsf{J}f - \epsilon^{2}(|D|\underline{\psi})\mathsf{J}^{2}|D|\{(|D|\underline{\psi})f\}.$$

and one has

 $\min(\epsilon, \epsilon^2 \delta^{-1}) \ll 1 \implies \left(\mathfrak{a}_{\mathsf{J}}[\underline{\zeta}, \underline{\psi}] f, f\right)_{L^2} \geq \frac{1}{2} |f|_{L^2}^2.$

Numerical validation

In numerical simulations, we observe a dichotomy:

- If $\delta > \delta_{\rm crit.}$, then large time stability.
- If $\delta < \delta_{\rm crit.}$, then rapid blow-up.

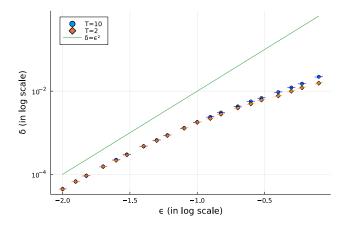


Figure: Critical value $\delta_{\rm crit.}$, depending on ϵ .

Rectification

Conclusion and perspectives

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We exhibited the instability mechanism induced by (WW2), and proposed a "rectification" which (for δ well-chosen)

- does not harm the precision (in the sense of consistency) of the model;
- restores large time well-posedness (and hence convergence);
- is costless form the point of view of numerical discretization.

Perspectives

- Results are proved in deep but finite depth, not in shallow water.
- We have not proved ill-posedness.
- We would like to extend the analysis to (WWN) with N arbitrary.

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Thank you for your attention