

PSEUDO-AUTOMORPHISMS WITH NO INVARIANT FOLIATION

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ABSTRACT. We construct an example of a birational transformation of a rational threefold for which the first and second dynamical degrees coincide and are > 1 , but which does not preserve any holomorphic (singular) foliation. In particular, this provides a negative answer to a question of Guedj. On our way, we develop several techniques to study foliations which are invariant under birational transformations.

1. INTRODUCTION

We are interested in smooth complex projective varieties M or, more generally, compact Kähler manifolds which carry invertible holomorphic or meromorphic transformations h such that (i) h has “rich” dynamics, and (ii) h is not “integrable”.

To formalize property (i), we will ask for positive topological entropy ; as explained below, finer requirements can be formulated in terms of dynamical degrees.

For property (ii), we will say that h is integrable if it preserves a holomorphic (singular) foliation of M of dimension $0 < d < \dim_{\mathbb{C}}(M)$; this includes the case of invariant meromorphic fibrations, hence the notion of reducible or non-primitive birational transformations (see [22], [6]). There are several alternative notions of integrability. In [20], a transformation $f: M \dashrightarrow M$ is integrable if there is a transformation $g: M \rightarrow M$ such that $g \circ f = f \circ g$ but $f^k \neq g^l$ for all $(k, l) \neq (0, 0)$. In [18, 16, 17], tools from differential Galois theory are developed to measure the level of integrability of various dynamical systems; heuristically, a transformation is “more integrable” than another if it preserves a richer geometric structure: foliations, volume forms, affine structures, are examples of possible invariant geometric structure in this context (see [9, 10] for instance). Here we focus on invariant foliations.

The main goal of this paper is to describe a new family of birational transformations on certain rational threefolds. These examples have three interesting

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properties: They are pseudo-automorphisms, which means that they are isomorphisms on the complement of Zariski closed subsets of codimension 2; they are not integrable in the sense that they do not preserve any non-trivial foliation; their dynamical degrees exhibit a resonance (namely $\lambda_1(f) = \lambda_2(f) > 1$). In particular, these transformations provide

- the first examples of pseudo-automorphisms of threefolds which are (proved to be) non-integrable;
- a negative answer to a question raised by Guedj.

Before giving the precise statement of our results, we describe property (i) and Guedj's question in more detail. On our way, we summarize the main known results in dimension ≤ 2 .

1.1. Entropy and dynamical degrees.

1.1.1. Let $h: M \dashrightarrow M$ be a rational transformation of a complex projective variety or, more generally, a meromorphic transformation of a compact kähler manifold. It may have indeterminacy points, at which it does not extend continuously; this indeterminacy set $\text{Ind}(h)$ is a Zariski-closed subset of M of codimension ≥ 2 .

Let $H^{p,q}(M; \mathbf{C})$ denote the Dolbeault cohomology groups of M . The groups $H^{p,p}(M; \mathbf{C})$ inherit a natural real structure, and the subgroups $H^{p,p}(M; \mathbf{R})$ contain the cap products of the kähler classes. This is the main reason why it is sufficient, in what follows, to focus on these cohomology groups (see [14]).

Although h may not be continuous, it determines a linear operator h_p^* on $H^{p,p}(M; \mathbf{R})$; however, $(h_p^*)^n$ may differ from $(h^n)_p^*$ for some values of n and p . The exponential growth rate of the sequence of linear transformations $(h^n)_p^*$ is defined by

$$\lambda_p(h) = \lim_{n \rightarrow +\infty} \|(h^n)_p^*\|^{1/n}$$

and is called the **dynamical degree** of h of codimension p ; this real number does not depend on the choice of the norm $\|\cdot\|$ on $\text{End}(H^{p,p}(M; \mathbf{R}))$, and remains invariant if one conjugates h by a birational map $\varphi: M' \dashrightarrow M$ (see [14]). For $p = 0$, one gets $\lambda_0(h) = 1$, and for $p = \dim(M)$ the dynamical degree $\lambda_{\dim(M)}(h)$ coincides with the topological degree of h .

We may think of the p th dynamical degree as giving the growth rate of cohomology in bidegree (p, p) , or volume growth in complex codimension p . The growth of the iterates on the total cohomology group $H^*(M)$ will be dominated by the restrictions to $H^{p,p}(M)$ for $1 \leq p \leq \dim(M)$.

1.1.2. When h is a regular endomorphism of M , Gromov and Yomdin proved that the topological entropy $h_{top}(h)$ of $h: M \rightarrow M$ coincides with the maximum

of the numbers $\log(\lambda_p(h))$, $0 \leq p \leq \dim(M)$; Dinh and Sibony proved that Gromov's upper bound

$$h_{top}(h) \leq \max_p \log(\lambda_p(h))$$

remains valid for dominant meromorphic transformations of compact kähler manifolds (see [13, 21, 12]). Thus, the dynamical degrees provide an upper bound for the complexity of the dynamics of h .

One says that h is **cohomologically hyperbolic** if the dynamical degrees $\lambda_p(h)$ have a unique maximum. Since the function $p \mapsto \log(\lambda_p(h))$ is concave, this is equivalent to the condition $\lambda_p(h) \neq \lambda_{p+1}(h)$ for all $0 \leq p \leq \dim(M) - 1$ (see [14]). Thus, cohomological hyperbolicity is a kind of non-resonance condition for dynamical degrees.

Example 1.1. a.– If f is a birational transformation of a projective surface and $\lambda_1(f) > 1$, then f is cohomologically hyperbolic.

b.– A paradigmatic example is given by linear endomorphisms of tori. More specifically, consider an elliptic curve $E = \mathbf{C}/\Lambda$, a positive integer d , and the complex torus $A = E^d = \mathbf{C}^d/\Lambda^d$. Let B be a $d \times d$ matrix with integer entries. Since the linear transformation $B: \mathbf{C}^d \rightarrow \mathbf{C}^d$ preserves the lattice Λ^d , it induces an endomorphism f_B of A . The number $\lambda_p(f)$ coincides with the square of the spectral radius of B acting on the space $\wedge^p(\mathbf{C}^d)$. For instance, if B is diagonalizable (over \mathbf{C}), with non-zero eigenvalues $\alpha_1, \dots, \alpha_d$, then f_B is cohomologically hyperbolic if and only if the moduli $|\alpha_i|$ are pairwise distinct.

1.2. Low dimensions. In the case of dimension 1, M is a compact Riemann surface. When the genus is ≥ 2 , the automorphism group is finite, and when the genus is 0 or 1, an automorphism is essentially linear or affine. Thus the holomorphic dynamics of a single invertible transformation in dimension 1 is quite simple.

Assume now that M is a compact complex surface. If M carries bimeromorphic transformations with positive entropy, then M is bimeromorphically equivalent to (1) a torus, (2) a K3 surface or an Enriques surface, or (3) the projective plane (see [7]), and there are strategies to construct examples of automorphisms with positive entropy in all three cases.

Concerning integrability, Diller and Favre proved that the existence of an invariant fibration is not compatible with positive entropy; Cantat and Favre [8] showed that if f is an infinite order bimeromorphic transformation of a compact kähler surface M that preserves a foliation then, up to a bimeromorphic conjugacy and finite ramified covers, f comes from a monomial transformation of the plane or an affine transformation of a torus (two cases for which there

are always invariant foliations). Thus the surfaces which can carry maps with invariant foliations, as well as the maps themselves, are special and explicit.

1.3. Guedj's question. *If h is a birational transformation of a compact kähler manifold that is not cohomologically hyperbolic, does it necessarily preserve a non-trivial fibration or (singular) holomorphic foliation ?* (see [14], page 103).

The idea behind this conjecture is that a resonance between dynamical degrees should be explained by the existence of an invariant algebraic or analytic structure. For instance Gizatullin's Theorem states that a birational transformation f of a surface S which is not cohomologically hyperbolic preserves a meromorphic fibration: there is a rational fibration $\pi: S \dashrightarrow B$ and an automorphism \bar{f} of the curve B such that $\pi \circ f = \bar{f} \circ \pi$ (see [11] and the references therein). We shall prove that Guedj's question has a negative answer in dimension 3; the answer is also negative in dimension 2 for non-invertible rational transformations (see §1.5.3 below).

1.4. The example.

1.4.1. Let J be the Cremona involution of $\mathbb{P}_{\mathbf{C}}^3$, defined in homogeneous coordinates by

$$J: [x_0 : x_1 : x_2 : x_3] \mapsto [x_0^{-1} : x_1^{-1} : x_2^{-1} : x_3^{-1}].$$

Given a and c in $\mathbf{C} \setminus \{0\}$, let L be the projective linear transformation

$$L: [x_0 : x_1 : x_2 : x_3] \mapsto [x_3 : x_0 + ax_3 : x_1 : x_2 + cx_3].$$

Let $f_{a,c}$ be the composition $L \circ J$. We shall prove that $f_{a,c}$ lifts to a pseudo-automorphism of a rational threefold $X_{a,c}$ after a finite sequence of blow-ups of points if

$$\ell a^2 + (\ell + 1)ac + \ell c^2 = 0 \tag{1.1}$$

for some $\ell > 1$. In what follows, fix such parameters (ℓ, a, c) , and denote by f the pseudo-automorphism $f_{a,c}: X_{a,c} \dashrightarrow X_{a,c}$.

1.4.2. First, we prove that f^* is **reversible**: $(f)_1^*$ and $(f^{-1})_1^*$ are conjugate linear transformations of $H^{1,1}(X_{a,c}; \mathbf{R})$. Since f is a pseudo-automorphism, it satisfies $(f_1^*)^{-1} = (f^{-1})_1^*$, and we deduce from the reversibility and the duality between $H^{1,1}(X_{a,c}; \mathbf{R})$ and $H^{2,2}(X_{a,c}; \mathbf{R})$ that $\lambda_1(f) = \lambda_2(f)$. Thus, f is not cohomologically hyperbolic. On the other hand, $\lambda_1(f) > 1$ if $\ell > 1$.

Theorem 1.2. *Let ℓ be an integer ≥ 2 . Let f be the birational transformation $L \circ J$, with parameters (a, c) that satisfy Equation (1.1). Then f lifts to a pseudo-automorphism of a rational threefold $X_{a,c}$, obtained from $\mathbb{P}_{\mathbf{C}}^3$ by a finite sequence of blow-ups of points. Moreover*

- (1) $\lambda_1(f) = \lambda_2(f) > 1$;
- (2) f preserves a hypersurface of $X_{a,c}$ on which it induces a birational transformation which is not conjugate to an automorphism;
- (3) f is not birationally conjugate to an automorphism of a manifold;
- (4) Neither f nor any of its iterates f^n for $n > 0$, preserves any (singular) foliation of dimension 1 or 2; in particular, there is no non-trivial invariant fibration.

Thus, the same construction gives, indeed, infinitely many examples. New techniques are required to understand their dynamical behavior more precisely. For instance, it is not clear whether the cohomological equality $\lambda_1(f) = \lambda_2(f)$ forces some dynamical resonance: Does f preserve a unique measure of maximal entropy? Are there unusual equalities between the Lyapunov exponents of such a measure? (see [14])

1.5. Comments.

1.5.1. If X is the iterated blow-up of \mathbb{P}^3 along a finite sequence of points, then by Truong's Theorem [19] (see also [1]) every automorphism has dynamical degree 1 and thus entropy zero. Thus, the best one could hope is to construct pseudo-automorphisms.

1.5.2. This paper is an expanded version of [4], in which the pseudo-automorphisms $f_{a,c}$ were constructed, their dynamical degrees were computed, and the non-existence of invariant fibration was proved. See also [2] for related constructions of pseudo-automorphisms.

1.5.3. Kaschner, Pérez, and Roeder found recently a rational transformation f of the projective plane $\mathbb{P}^2(\mathbb{C})$ with dynamical degrees $\lambda_2(f) = \lambda_1(f)$ that does not preserve any foliation [15]. Thus, Guedj's question has a negative answer for non-invertible maps in dimension 2, and for invertible maps in dimension 3, and a positive answer for invertible maps in dimension 2.

2. PSEUDO-AUTOMORPHISMS : CONSTRUCTION

2.1. Pseudo-automorphisms in dimension 3. Let M be a smooth complex projective variety of dimension 3. Let f be a birational transformation of M . The indeterminacy locus $\text{Ind}(f)$ is a Zariski closed subset of M of dimension ≤ 1 (it may have components of dimension 0 and of dimension 1). One says that an irreducible subvariety V of M is exceptional for f if V is not contained in $\text{Ind}(f)$ and

$$\dim(f(V \setminus \text{Ind}(f))) < \dim(V).$$

Let p be a point of $V \setminus \text{Ind}(f)$. Using local coordinates near p and $f(p)$, V is exceptional if and only if it is contained in the zero locus of the jacobian determinant of f . Thus, the union $\text{Exc}(f)$ of the exceptional subvarieties is either empty or a subvariety of M of codimension 1.

One says that f is a **pseudo-automorphism** if $\text{Exc}(f)$ and $\text{Exc}(f^{-1})$ are both empty. All pseudo-automorphisms share the following nice properties (see [3]):

- $\text{Ind}(f)$ and $\text{Ind}(f^{-1})$ do not contain isolated points (all their components have dimension 1);
- $(f^*)_p^n = (f^n)_p^*$ for all $0 \leq p \leq 3$ and for all integers $n \in \mathbf{Z}$;
- in particular $(f^*)_p^{-1} = (f^{-1})_p^*$.

Lemma 2.1. *Let f be a pseudo-automorphism of a smooth complex projective threefold M . If f_1^* and $(f^*)_1^{-1}$ are conjugate linear transformations of $H^{1,1}(M; \mathbf{C})$ then $\lambda_1(f) = \lambda_2(f)$.*

Proof. Since f_1^* and $(f_2^{-1})^*$ are conjugate linear operators with respect to the intersection pairing, i.e.

$$f_1^*(v) \cdot w = v \cdot (f_2^*)^{-1}(w) \quad \forall (u, v) \in H^{1,1}(M; \mathbf{R}) \times H^{2,2}(M; \mathbf{R}),$$

one gets $\lambda_1(f) = \lambda_2(f^{-1})$. If f_1^* is conjugate to its inverse, one has $\lambda_1(f) = \lambda_1(f^{-1})$. The conclusion follows. \square

2.2. A family of examples.

2.2.1. *Definition.* As explained in Section 1.4.1, we consider the birational transformations $f = L \circ J: \mathbb{P}_{\mathbf{C}}^3 \dashrightarrow \mathbb{P}_{\mathbf{C}}^3$ with

$$\begin{aligned} J: [x_0 : x_1 : x_2 : x_3] &\mapsto [x_0^{-1} : x_1^{-1} : x_2^{-1} : x_3^{-1}], \\ L: [x_0 : x_1 : x_2 : x_3] &\mapsto [x_3 : x_0 + ax_3 : x_1 : x_2 + cx_3]. \end{aligned}$$

Here, a and c are non-zero complex parameters. The inverse of L is the projective linear transformation

$$L^{-1}: [x_0 : x_1 : x_2 : x_3] \mapsto [x_1 - ax_0 : x_2 : x_3 - cx_0 : x_0].$$

2.2.2. *Geometry of J .* The indeterminacy locus $\text{Ind}(J)$ is the union of the six edges

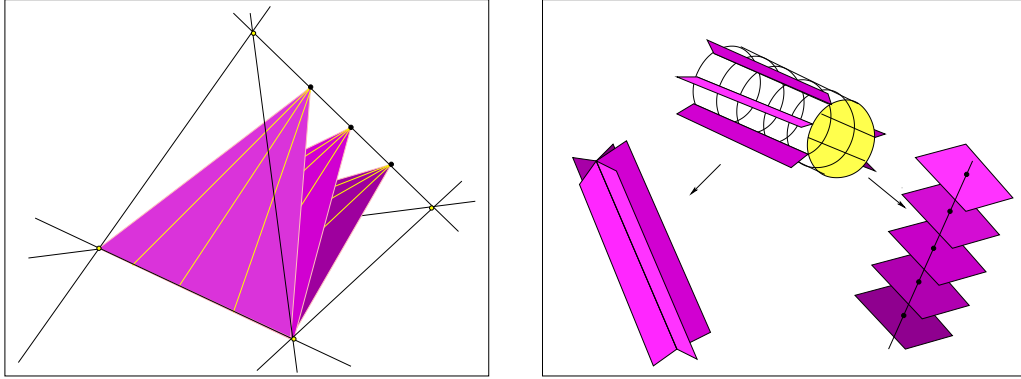
$$\Sigma_{i,j} = \{x_i = x_j = 0\} \subset \mathbb{P}_{\mathbf{C}}^3$$

of the tetrahedron $\Delta = \{x_0x_1x_2x_3 = 0\}$. The exceptional locus $\text{Exc}(J)$ is the union of the four faces

$$\Sigma_i = \{x_i = 0\};$$

each plane Σ_i is mapped to the opposite vertex

$$e_i = \{x_l = 0, \forall l \neq i\}.$$


 FIGURE 1. ACTION OF J

Since J is an involution, it blows up each e_i to the opposite face Σ_i .

To describe how J acts on a neighborhood of an edge of Δ , consider the edge $\Sigma_{0,1}$. The family of hyperplanes of \mathbb{P}^3 containing the line $\Sigma_{0,1}$ is the family $\{sx_0 = tx_1\}$. It is globally invariant under the action of J : The plane $\{sx_0 = tx_1\}$ is transformed into the plane $\{tx_0 = sx_1\}$; in particular, the plane $\Pi = \{x_0 = x_1\}$ is invariant.

On Π , J acts as a standard quadratic involution of \mathbb{P}^2 , mapping $[x_1 : x_1 : x_2 : x_3]$ to $[x_2x_3 : x_2x_3 : x_3x_1 : x_1x_2]$; the line $\Sigma_{0,1} \subset \Pi$ is mapped to the point $[1 : 1 : 0 : 0]$ and the family of lines $\{s'x_2 = t'x_3\}$ is globally invariant. The action of J from $\Pi_{s,t} = \{sx_0 = tx_1\}$ to $\Pi_{t,s} = \{tx_0 = sx_1\}$ is similar. Thus, locally, J transforms the family of planes $\Pi_{s,t}$ containing $\Sigma_{0,1}$ to the family of planes $\Pi_{t,s}$ transverse to $\Sigma_{2,3}$.

Another way to describe the same picture is as follows. Blow-up the line $\Sigma_{0,1}$. The exceptional divisor E is a product $\mathbb{P}^1 \times \mathbb{P}^1$ and the blow-down map π contracts the fibers $\{\star\} \times \mathbb{P}^1$ of the first projection. The strict transform of the pencil of planes $\Pi_{s,t}$ intersect E on the family of horizontal curves $\mathbb{P}^1 \times \{\star\} \subset E$. Similarly, the fibers of π can be identified to the intersection of E with the strict transforms of the planes $\{s'x_2 = t'x_3\}$. Then, $J \circ \pi$ maps E onto $\Sigma_{2,3}$: It contracts the horizontal curves $\mathbb{P}^1 \times \{\star\}$ to $\Sigma_{2,3}$.

2.2.3. *Back to f .* Since L is an automorphism, $\text{Ind}(f)$ and $\text{Exc}(f)$ coincide with $\text{Ind}(J)$ and $\text{Exc}(J)$. On the other hand, $\text{Ind}(f^{-1})$ and $\text{Exc}(f^{-1})$ are respectively equal to $L(\text{Ind}(J))$ and $L(\text{Exc}(J))$; these sets correspond to the edges and faces of the tetrahedron $L(\Delta) = \{x_3(x_0 + ax_3)x_1(x_2 + cx_3) = 0\}$.

The images of the four planes Σ_i under the action of f are the vertices of the tetrahedron $L(\Delta)$; more precisely,

$$f(\Sigma'_0) = e_1, \quad f(\Sigma'_1) = e_2, \quad f(\Sigma'_2) = e_3, \quad \text{and} \quad f(\Sigma'_3) = p_1,$$

where

$$p_1 = [1 : a : 0 : c]$$

and $f(\Sigma'_i)$ stands for $f(\Sigma_i \setminus \text{Ind}(f))$. Since J blows up e_i to Σ_i , f blows up e_i to $L(\Sigma_i)$, i.e.

$$f: e_0 \rightsquigarrow \{x_1 = ax_0\}, \quad e_1 \rightsquigarrow \Sigma_2, \quad e_2 \rightsquigarrow \{x_3 = cx_0\}, \quad e_3 \rightsquigarrow \Sigma_0.$$

2.2.4. An intermediate threefold Y . Blowing up the projective space $\mathbb{P}_{\mathbb{C}}^3$ at the three points e_1, e_2 , and e_3 , we get a rational threefold Y , together with a birational morphism $\pi: Y \rightarrow \mathbb{P}_{\mathbb{C}}^3$. We denote by E_1^Y, E_2^Y, E_3^Y the three exceptional divisors: Each E_j^Y is blown down to e_j by π . Then, we lift f to a birational transformation $f_Y := \pi^{-1} \circ f \circ \pi$ of Y .

Denote by Σ_j^Y the strict transform of Σ_j inside Y . It is easily verified that f_Y induces a birational transformation from Σ_j^Y to E_{j+1}^Y for $j = 0, 1, 2$, and that f_Y blows down Σ_3^Y onto the point $\pi^{-1}(p_1)$. Similarly, f_Y maps each exceptional divisor E_j^Y , $1 \leq j \leq 3$, onto the strict transform of the plane $L(\Sigma_j)$ birationally. Thus, the exceptional locus of f_Y coincides with Σ_3^Y . Moreover f_Y preserves the divisor

$$\Gamma^Y := \Sigma_0^Y \cup E_1^Y \cup \Sigma_2^Y \cup E_3^Y,$$

permuting the four irreducible components as follows;

$$\Sigma_0^Y \dashrightarrow E_1^Y \dashrightarrow \Sigma_2^Y \dashrightarrow E_3^Y \dashrightarrow \Sigma_0^Y.$$

2.2.5. An invariant cycle of curves contained in Γ^Y . Let us consider the restriction of f_Y to the invariant divisor Γ^Y . We define four curves $\beta_i \subset Y$ as follows.

$$\begin{aligned} \beta_0 & \text{ is the strict transform of } \Sigma_0 \cap \{ax_1 = cx_3\}, \\ \beta_1 & \text{ is the strict transform of } E_1^Y \cap \{ax_0 = cx_2\}, \\ \beta_2 & \text{ is the strict transform of } \Sigma_2 \cap \{cx_1 = ax_3\}, \\ \beta_3 & \text{ is the strict transform of } E_3^Y \cap \{cx_0 = ax_2\}. \end{aligned}$$

The curve β_2 is the (strict transform) of the line through e_0 and p_1 . An explicit computation shows that $f_Y|_{\Gamma^Y}$ permutes the β_i cyclically. Moreover, none of these curves is contained in $\text{Ind}(f_Y)$.

Example 2.2. To describe the kind of calculation that leads to this remark, consider the curve β_2 . It can be parametrized by $t \in \mathbb{P}_{\mathbb{C}}^1 \mapsto \pi^{-1} \circ \eta(t)$ where

$$\eta(t) = [1 : t : 0 : ct/a].$$

In $\mathbb{P}_{\mathbb{C}}^3$, the point $f \circ \eta(t)$ coincides with e_3 . In local coordinates near E_3^Y , the blow down map π may be written as $(s, u_1, u_2) \mapsto [s : su_1 : su_2 : 1]$. In these coordinates, the equation that determines β_3 , namely $cx_0 = ax_2$, corresponds to

the equation $c = au_2$ (once one divides both sides by s). Then, one shows that $f_Y \circ \pi^{-1} \circ \eta(t)$ corresponds to $(0, (a^2 + ct)/a, c/a)$ when $t \neq 0$. This is a point of β_3 .

2.2.6. The ℓ -condition. The exceptional locus Σ_3^Y of f_Y is blown down to the point $p_1 \subset \beta_2 \subset \Sigma_2^Y$. The forward orbit of this point is contained in the invariant cycle of curves $\beta_0 \cup \beta_1 \cup \beta_2 \cup \beta_3$, until it reaches an indeterminacy point of f_Y (this may never occur, depending on the values of the parameters a and c). We define the sequence (p_k) inductively by $p_{k+1} = f_Y^k(p_k)$ for all $k \geq 1$ such that p_1, \dots, p_k does not intersect $\text{Ind}(f_Y)$. If p_k is well defined, one says that the (forward) orbit of p_1 is well defined up to time $k - 1$. For instance, the orbit of p_1 is well defined up to time 1 if p_1 is not a point of indeterminacy of f_Y .

Given an integer $\ell \geq 0$, consider the following two steps condition

- the orbit of p_1 is well defined up to time 4ℓ ,
- $f_Y^{4\ell}(p_1) = e_0$.

This condition is referred to as the **ℓ -condition** in what follows. The ℓ -condition is just a precise formulation of $f_Y^k(p_1) = e_0$ for some $k > 0$, taking into account indeterminacy problems and the fact that k must be of the form 4ℓ for some $\ell \geq 0$.

Since p_1 is not equal to e_0 , the 0-condition is never satisfied.

The curve β_2 is parametrized by $t \in \mathbb{P}_{\mathbf{C}}^1 \mapsto \pi^{-1} \circ \eta(t)$ where

$$\eta(t) = [1 : t : 0 : ct/a].$$

The point p_1 corresponds to the parameter $t = a$, while e_0 corresponds to $t = 0$. An explicit computation, similar to the one described in Example 2.2, shows that the restriction of f_Y^4 to β_2 is induced by the following translation of the t variable:

$$h: t \mapsto t + \frac{a^2 + c^2 + ac}{c}.$$

Lemma 2.3. *The parameters $(a, c) \in \mathbf{C}^* \times \mathbf{C}^*$ satisfy the ℓ -condition if and only if*

$$\ell a^2 + (\ell + 1)ac + \ell c^2 = 0. \quad (2.1)$$

Proof. The ℓ condition means that $f_Y^{4\ell}(p_1) = e_0$; this is equivalent to $h^\ell(a) = 0$, hence to $\ell a^2 + (\ell + 1)ac + \ell c^2 = 0$. The only thing that remains to be shown is that the orbit of p_1 is well defined up to time 4ℓ if the parameters (a, c) satisfy Equation (2.1).

For this purpose, let us come back to the computation done in Example 2.2. One sees that the point of β_2 corresponding to the parameter $t \neq 0$ is mapped to the point of β_3 with coordinates $(s, u_1, u_2) = (0, (a^2 + ct)/a, c/a)$. Thus, if

$t \neq 0$ (i.e. $\eta(t) \neq e_0$), the image is not an indeterminacy point of f_Y . Hence, if $h^k(p_1) \neq e_0$ then $f_Y(h^k(p_1))$ is not an indeterminacy point of f_Y .

A similar computation along β_3 , β_0 , and β_1 concludes the proof. \square

Remark 2.4. Assume that (a, c) satisfies the ℓ -condition. Then $\alpha = a/c$ is a root of $\ell\alpha^2 + (\ell + 1)\alpha + \ell$. The discriminant of this quadratic polynomial is

$$\delta_\ell = (\ell + 1)^2 - 4\ell^2 = -3\ell^2 + 2\ell + 1.$$

It is positive for $\ell = 0$, vanishes for $\ell = 1$, and is negative for $\ell \geq 2$. Thus, a/c is not a real number if $\ell \geq 2$.

2.2.7. *The threefold X .* Assume that the ℓ -condition is satisfied, and blow up the points $p_1, p_2, \dots, p_{4\ell}$, and $p_{4\ell+1} = e_0$. This defines a new rational threefold X together with a birational morphism $\tau: X \rightarrow Y$. The exceptional divisor are denoted by $P_1, \dots, P_{4\ell}$ and $P_{4\ell+1}$. We shall also use the notation E_0 for the divisor $P_{4\ell+1}$ because $p_{4\ell+1} = e_0$. By construction, one gets:

Proposition 2.5. *Let ℓ be a positive integer and (a, c) be a pair of non-zero complex numbers that satisfies the ℓ -condition. Then, the birational transformation f_Y lifts to a pseudo-automorphism $f_X = \tau^{-1} \circ f \circ \tau$ of the smooth rational variety X .*

2.2.8. *Action of f_X on $\text{Pic}(X)$.* One denotes by Σ_i^X the strict transform of Σ_i^Y in X . Then, by definition,

- E_i , $1 \leq i \leq 3$, is the strict transform of E_i^Y in X ;
- \hat{E}_1 and \hat{E}_3 are the total transforms of E_1^Y and E_3^Y respectively. As divisors, they are equal to

$$\begin{aligned} \hat{E}_1 &= E_1 + P_4 + P_8 + \dots + P_{4\ell} \\ \hat{E}_3 &= E_3 + P_2 + P_6 + \dots + P_{4\ell-2}. \end{aligned}$$

Let H be the total transform of a hyperplane of $\mathbb{P}_{\mathbb{C}}^3$ under $\pi \circ \tau$. Then, the classes of H , \hat{E}_1 , E_2 , \hat{E}_3 , and the P_j , $4\ell + 1 \geq j \geq 1$, determine a basis of $\text{Pic}(X)$. We denote by $\Gamma \subset X$ the strict transform of Γ^Y : the divisor Γ is the sum $\Sigma_0^X + E_1 + \Sigma_2^X + E_3$.

Proposition 2.6. *The linear transformations f_X^* and $(f_X^{-1})^*$ of $\text{Pic}(X)$ are given by*

$$(f_X)^* : \begin{cases} [H] & \mapsto 3[H] - 2[\hat{E}_1] - 2[E_2] - 2[\hat{E}_3] - 2[P_{4\ell+1}] \\ [\hat{E}_1] & \mapsto [H] - [\hat{E}_1] - [E_2] - [\hat{E}_3] \\ [E_2] & \mapsto [H] - [E_2] - [\hat{E}_3] - [P_{4\ell+1}] \\ [\hat{E}_3] & \mapsto [H] - [\hat{E}_1] - [\hat{E}_3] - [P_{4\ell+1}] \\ [P_j] & \mapsto [P_{j-1}] \quad 2 \leq j \leq 4\ell + 1 \\ [P_1] & \mapsto [H] - [\hat{E}_1] - [E_2] - [P_{4\ell+1}] \end{cases}$$

and

$$(f_X^{-1})^* : \begin{cases} [H] & \mapsto 3[H] - 2[\hat{E}_1] - 2[E_2] - 2[\hat{E}_3] - 2[P_1] \\ [\hat{E}_1] & \mapsto [H] - [\hat{E}_1] - [\hat{E}_3] - [P_1] \\ [E_2] & \mapsto [H] - [\hat{E}_1] - [E_2] - [P_1] \\ [\hat{E}_3] & \mapsto [H] - [\hat{E}_1] - [E_2] - [\hat{E}_3] \\ [P_j] & \mapsto [P_{j+1}] \quad 1 \leq j \leq 4\ell \\ [P_{4\ell+1}] & \mapsto [H] - [E_2] - [\hat{E}_3] - [P_1] \end{cases}$$

Proof. Let us start with the basis of $\text{Pic}(X)$ consisting of $[H]$, the $[E_j]$'s and the $[P_k]$'s, which are the prime blow-up divisors. Let B be a divisor corresponding to one of these basis elements. Since f_X is a pseudo-automorphism, f_X^{-1} will be a local diffeomorphism in a neighborhood of the generic point of B . Thus $f_X^{-1}B$ will be an irreducible hypersurface, and we will have $f_X^*[B] = [f_X^{-1}B]$. It now remains to express the divisor $[f_X^{-1}B]$ in terms of our basis.

There are two cases. First, suppose that $f_X^{-1}B$ lies over a point $p \in \mathbf{P}^3$. Then it will be one of the basis divisors B' , and we have $[f_X^{-1}B] = [B']$.

The other case is that $f_X^{-1}B$ projects to an irreducible hypersurface $\pi(f_X^{-1}B) \subset \mathbf{P}^3$ of some degree δ . We will then have $[f_X^{-1}B] = \delta[H] - \sum \mu_S[S]$, where the sum is taken over all basis elements $[S]$ which project to a point of $\pi(f_X^{-1}B)$. The multiplicities μ_S will be nonnegative integers, which remain to be determined. The procedure of determining the multiplicity is relatively routine; an example is given in the Appendix.

This then gives f_X^* in terms of the basis described in the first line of the proof. We now change basis, replacing $[E_j]$ by $[\hat{E}_j]$, and find the formula above. \square

Corollary 2.7. *If the ℓ -condition is satisfied, then:*

- (1) *The characteristic polynomials of f_X^* and $(f_X^{-1})^*$ are both equal to*

$$\chi_\ell(x) = x^{4\ell+1}(x^4 - x^2 - x - 1) + x^4 + x^3 + x^2 - 1.$$

- (2) *The factor $(x^4 - 1)$ divides $\chi_\ell(x)$, and $x = 1$ is a simple root of χ_ℓ .*
(3) *$\lambda_1(f) = \lambda_2(f) = 1$ if $\ell = 1$, and $\lambda_1(f) = \lambda_2(f) > 1$ is a Salem number if $\ell \geq 2$.*

In particular, the pseudo-automorphism f_X is not cohomologically hyperbolic.

Proof. The characteristic polynomial is easily obtained from the previous proposition. It is divisible by $(x + 1)$, and

$$\frac{\chi_\ell(x)}{x+1} = x^{4\ell+1}T(x) - x^3T(x^{-1})$$

with $T(x) = x^3 - x^2 - 1$. The cubic polynomial T has one real root $\alpha_T > 1$ and two complex conjugate roots of modulus < 1 . Thus, $\alpha_T \simeq 1.46$ is a Pisot number of degree 3. This implies that (i) the largest root of χ_ℓ is a Salem

number λ_ℓ as soon as $4\ell + 1 > 2\frac{\alpha_T + 1}{\alpha_T - 1} \simeq 10.7$, hence as soon as $\ell \geq 3$, and that (ii) λ_ℓ converges towards α_T when ℓ goes to $+\infty$. (see [5], Theorem 1.1.1, page 16)

For $\ell = 2$, one checks directly that λ_ℓ is a Salem number of degree 8, solution of the equation $x^8 - x^7 - x^5 + x^4 - x^3 - x + 1 = 0$. \square

2.2.9. Invariant hypersurfaces. In $\text{Pic}(X)$, the eigenspace of f_X^* for the eigenvalue 1 coincides with the line generated by the class of Γ , i.e. by

$$[\Gamma] = 2H - \hat{E}_1 - E_2 - \hat{E}_3 - P_{4\ell+1} - \dots - P_1.$$

It follows that if $S \subset \mathbb{P}^3$ is an f -invariant hypersurface and P is a homogeneous equation of S , then P is a polynomial of degree $2m$, for some $m > 0$, and vanishes with multiplicity m at each e_i ; moreover, the f -invariance is equivalent to

$$P \circ F = \lambda(\text{Jac}(F))^m P$$

for some $\lambda \in \mathbf{C}^*$, where F is the lift of f to \mathbf{C}^4 defined by

$$F(x_0, x_1, x_2, x_3) = (x_0x_1x_2, x_1x_2x_3 + ax_0x_1x_2, x_0x_2x_3, x_0x_1x_3 + cx_0x_1x_2).$$

and $\text{Jac}(F) = x_0x_1x_2x_3$ is its jacobian determinant.

The class $[\Gamma]$ coincides with $-(1/2)[K_X]$, where K_X is the canonical divisor. Consider, on the projective space $\mathbb{P}_{\mathbf{C}}^3$, the rational volume form

$$\Omega := d\left(\frac{1}{x_0}\right) \wedge dx_1 \wedge d\left(\frac{1}{x_2}\right).$$

This form does not vanish, and its poles are the two faces Σ_0 and Σ_2 of the tetrahedron Δ . Moreover, $L^*\Omega = dx_2 \wedge dx_0 \wedge d(1/x_1)$. Hence,

$$f^*\Omega = \Omega.$$

Defining $\Omega_X = \tau^*(\pi^*(\Omega))$, one gets a rational section of K_X with poles along Γ (of multiplicity 2) and no zeros.

Remark 2.8. Let M be a smooth projective variety and f be a pseudo-automorphism of M . Since the Jacobian determinant of f does not vanish on the complement of $\text{Ind}(f)$, the linear operator f^* preserves the canonical class.

3. BEHAVIOR ON THE INVARIANT SURFACE

3.1. The action of f_X on Γ . Let g be the restriction of f^4 to the invariant plane Σ_0 . In coordinates, we have

$$\begin{aligned} g: [x_1 : x_2 : x_3] &\mapsto [(cx_1x_2 + x_1x_3 + cx_2x_3) \times (cx_1x_2 + x_1x_3 + ax_2x_3 + cx_2x_3) \\ &\quad : x_2x_3 \times (cx_1x_2 + x_1x_3 + cx_2x_3) \\ &\quad : x_3 \times (ax_2 + cx_2 + x_3) \times (cx_1x_2 + x_1x_3 + ax_2x_3 + cx_2x_3)] \end{aligned}$$

Hence

$$g[x_1 : x_2 : x_3] = [Q(Q + ax_2x_3) : x_2x_3Q : x_3(x_3 + (a+c)x_2)(Q + ax_2x_3)]$$

where Q denotes the quadratic polynomial function $Q = cx_1x_2 + x_1x_3 + cx_2x_3$. In particular, the degree of g is 4 (i.e., the pre-image of a line is a curve of degree 4).

The inverse of g is the birational map

$$g^{-1} : [x_1 : x_2 : x_3] \mapsto [x_1(x_1 - (a+c)x_2)(N - cx_1x_2) : x_1x_2N : N(N - cx_1x_2)]$$

with $N = x_1x_3 - ax_2x_3 - ax_1x_2$.

3.1.1. *Exceptional locus.* The exceptional locus $\text{Exc}(g) \subset \Sigma_0$ is the union of 4 curves L_1, L_2, L_3 , and L_4 , defined as follows:

- L_1 is the line $\{x_3 = 0\}$ through the two points e_1 and e_2 ; hence $L_1 = \Sigma_{03}$ is an edge of the tetrahedron Δ ; its image under the action of g is e_1 .
- L_2 is the line $\{cx_2 + x_3 = 0\}$; it is mapped onto the point $p_3 = [1 : (a+c)^{-1} : a/c]$ (this point is on β_0 and is the image of p_1 by f_Y^2).
- L_3 is the conic $\{cx_1x_2 + x_1x_3 + cx_2x_3 = 0\}$; its image is the point e_3 .
- L_4 is the conic $\{cx_1x_2 + x_1x_3 + cx_2x_3 + ax_2x_3 = 0\}$; its image is e_2 (the intersection point of β_0 and $L_1 = \Sigma_{03}$).

Remark 3.1. In affine coordinates (x_2, x_3) near the point $e_1 = [1 : 0 : 0]$, the equations of L_2, L_3, L_4 have the same 1-jet $cx_2 + x_3$. This means that their strict transforms intersect the blow-up E_1 of e_1 at the same point.

3.1.2. *Indeterminacies.* The indeterminacy locus of g is

$$\text{Ind}(g) = \{e_1, e_2, e_3, p_{4\ell-1}\},$$

with $p_{4\ell-1} = [c(a+c) : -a : a(a+c)]$. These points are equal to the strict transforms of $\{N = 0\}$, $\{N - cx_1x_2 = 0\}$, $\{x_1 = 0\}$, and $\{x_1 = ax_2\}$ under the action of g^{-1} .

3.1.3. *The surface W .* Let us blow up Γ at the $\ell + 3$ points e_1, e_2, e_3 and p_3, p_7, p_{11}, \dots , up to $p_{4\ell-1}$. We obtain a new surface W , together with a birational morphism $\varepsilon : W \rightarrow \Sigma_0$. We denote by E_i the exceptional divisor above e_i , for $1 \leq i \leq 3$, and by F_j the exceptional divisor above p_{4j-1} , for $1 \leq j \leq \ell$. The transformation g lifts to a birational transformation g_W of W , which acts as follows on these curves:

- g_W maps E_1 onto E_1 and E_3 onto E_3 ;
- it maps L_1 to a point of E_1 , and L_3 to a point of E_3 . Moreover, the forward orbit of these points form a sequence of points of E_1 (resp. E_3) that do not intersect $\text{Ind}(g_W)$.

- g_W maps L_4 onto E_2 and then E_2 onto the strict transform of the conic $\{ax_1x_2 + cx_1x_2 - x_1x_3 + ax_2x_3 = 0\}$.
- it maps L_2 onto F_1 , then onto F_2, \dots , onto F_ℓ and then onto the strict transform of the line $\{ax_2 - x_1 = 0\}$.

Proof. Let us prove the two assertions concerning E_1 and L_1 ; the remaining ones are proved along similar lines.

There are local coordinates (u, v) near E_1 such that $\varepsilon(u, v) = [1 : u : uv]$, with $E_1 = \{u = 0\}$. In these coordinates, $g \circ \varepsilon(u, v)$ is equal to

$$\left[1 : \frac{uv}{c + v + cuv + auv} : \frac{uv}{c + v + cuv + auv} \frac{(a + c + v)(c + v + cu + auv)}{c + v + cuv} \right].$$

This implies that g_W maps E_1 onto E_1 , as mentioned above, transforming the v -coordinate into $v' = v + (a + c)$. There is a unique indeterminacy point of g_W on the curve E_1 ; it corresponds to the coordinates $(u, v) = (0, -c)$, and coincides with the common intersection point of E_1 with the strict transforms of the curves $L_2, L_3, L_4 \subset \text{Exc}(g)$ (see Remark 3.1). The strict transform of the line L_1 intersects E_1 at the point $(u, v) = (0, 0)$; at that point, g_W is regular, and behaves like $(u, v) \mapsto (uv/c + \text{h.o.t.}, uv(a + c)/c + \text{h.o.t.})$.

Moreover, $g[x_1 : x_2 : x_3]$ is equal to

$$\left[1 : \frac{x_2x_3}{Q + ax_2x_3} : \frac{x_3((a + c)x_2 + x_3)}{Q} \right]$$

where $Q = cx_1x_2 + x_1x_3 + cx_2x_3$. This means that $\pi^{-1} \circ g$ maps the point $[x_1 : x_2 : x_3]$ to the point (u, v) with

$$u = \frac{x_2x_3}{Q + ax_2x_3}, \quad v = \frac{((a + c)x_2 + x_3)(Q + ax_2x_3)}{x_2Q}.$$

Parametrizing the line L_1 by $[s : t : 0]$, with $[s : t]$ in the projective line, we obtain $Q(s, t, 0) = cst$ and

$$u = 0, \quad v = \frac{((a + c)x_2 + x_3)(Q + ax_2x_3)}{x_2Q} = \frac{(a + c)t}{t} = a + c.$$

This means that the strict transform L'_1 is mapped onto the point $(u, v) = (0, a + c)$ of E_1 . Then, its orbit is contained in E_1 and corresponds to the infinite sequence of points with coordinates $v_n = n(a + c)$, $n \geq 1$.

Since (a, c) satisfies the ℓ -condition, we have $\ell a^2 + (\ell + 1)ac + \ell c^2 = 0$; in particular, a/c is not a real number (see Remark 2.4). If, for some $n > 0$, v_n coincides with the unique indeterminacy point $\{v = -c\}$, then $na + (n + 1)c = 0$ and a/c is the rational number $-(n + 1)/n$. Thus, g_W is well defined all along the positive orbit (v_n) . This means that none of the points $g_W^n(L'_1)$, $n \geq 1$, is indeterminate; thus, if algebraic stability fails for g_W , this is not because L'_1 is eventually mapped to an indeterminacy point. \square

Similarly, one proves that g_W^{-1} preserves the curve E_1 , acts by a translation $v \mapsto v - (a + c)$ on E_1 , and has a unique indeterminacy point on E_1 , namely $v = a + c$. In particular, the backward orbit of the curve L_1 is a sequence of curves that intersect E_1 along the points of parameters $-n(a + c)$. This implies, that the curves $g^n(L_1)$, $n \geq 1$ are pairwise distinct, and that none of them is contained in $\text{Ind}(f^{\pm k})$, $k \leq 4$.

3.1.4. *Action on $\text{Pic}(W)$.* Recall that a birational transformation h of a surface Z is **algebraically stable** if $(h^*)^n = (h^n)^*$ on $\text{Pic}(Z)$ for all integer n or, equivalently, h^n does not contract a curve of $\text{Exc}(h)$ on an indeterminacy point of h for all $n \geq 1$ (see [11]).

To describe the action of g_W on the Picard group of W , we make use of the basis given by the class L of (the total transform of) a line, and the classes of the exceptional divisors E_i and F_j . We denote by L'_i the strict transform of L_i in W . From the previous description of the action of g_W , and similar properties for g_W^{-1} , one gets the following lemma.

Lemma 3.2. *The transformation $g_W: W \dashrightarrow W$ is algebraically stable. Its action on $\text{Pic}(W)$ is given by*

$$(g_W)^*: \begin{cases} [L] & \mapsto 4[L] - 2[E_1] - 2[E_2] - [E_3] - [F_\ell] \\ [E_1] & \mapsto [L'_1] + [E_1] = [L] - [E_2] \\ [E_2] & \mapsto [L'_4] = 2[L] - [E_1] - [E_2] - [E_3] \\ [E_3] & \mapsto [L'_3] + [E_3] = 2[L] - [E_1] - [E_2] - [F_\ell] \\ [F_j] & \mapsto [F_{j-1}], \text{ for } \ell \geq j \geq 2 \\ [F_1] & \mapsto [L'_2] = [L] - [E_1] \end{cases}$$

3.1.5. *g_W -invariant curves.* The eigenspace of $(g_W)^*$ with eigenvalue 1 is spanned by $[\Sigma_{0,2}] = [L] - [E_1] - [E_3]$ and $[\beta_0] = [L] - [E_2] - \sum_{j=1}^{\ell} [F_j]$. The indeterminacy locus of g_W^{-1} is $\{\hat{e}_1 = g_W(L'_1) \in E_1, \hat{e}_3 = g_W(L'_3) \in E_3\}$. It follows that if C is g_W -invariant, then

$$(g_W)^*[C] = [C] + \kappa_1[L'_1] + \kappa_3[L'_3]$$

where κ_1, κ_2 are the multiplicities of \hat{e}_1 and \hat{e}_3 in C . From the above equation, we see that there is a solution if and only if $\kappa_1 + \kappa_3 = 0$. Since both κ_1 and κ_3 are non-negative integers, we have $\kappa_1 = \kappa_3 = 0$ and $[C] = m_1[\Sigma_{0,2}] + m_2[\beta_0]$; therefore

$$[C] \cdot [\Sigma_{0,2}] = m_2 - m_1 \quad \text{and} \quad [C] \cdot [\beta_0] = m_1 - \ell m_2.$$

If none of the irreducible components of C is equal to $\Sigma_{0,2}$ or β_0 , we have $m_2 \geq m_1 \geq \ell m_2$, and we get a contradiction with $\ell \geq 2$. Thus, we obtain the following lemma.

Lemma 3.3. *Any g_W -invariant curve C is contained in $\Sigma_{0,2} \cup \beta_0$.*

3.1.6. *Dynamical degree.* Assuming, as above, that (a, c) satisfies the ℓ -condition, one gets the following description of the characteristic polynomial of g_W^* .

Proposition 3.4. *The dynamical degree $\lambda_1(g)$ of $g = f_{\Sigma_0}^4$ is the largest root of the polynomial*

$$x^\ell - x^{\ell-1} - x^{\ell-2} - \dots - x - 1.$$

If $\ell = 1$, then $\lambda_1(g_W) = 1$ and the degree growth of g is linear. If $\ell \geq 2$ then $\lambda_1(g_W) > 1$ is a Pisot number.

In both cases, g_W and its iterates g_W^n , $n \neq 0$, are not birationally conjugate to an automorphism of a rational surface.

Proof. Since g_W is algebraically stable, its dynamical degree is equal to the largest root of the characteristic polynomial of g_W^* . From Lemma 3.2 we see that the characteristic polynomial is

$$x^2(x-1)^2(x^\ell - x^{\ell-1} - x^{\ell-2} - \dots - x - 1).$$

If $\ell = 1$, the roots of this polynomial are equal to 0 or 1; hence, $\lambda_1(g) = 1$. Moreover, the matrix of g_W^* contains a Jordan block of size 2 with eigenvalue 1; it follows that the sequence $\| (g_W^n)^* \|$ grows linearly with n . Hence, g_W is conjugate to a Jonquières transformation and neither g_W nor any iterate g_W^n , $n \neq 0$, is conjugate to an automorphism (see [11]).

If $\ell \geq 2$, the unique eigenvalue $\lambda_\ell > 1$ is a root of

$$\chi_g(t) = t^\ell - t^{\ell-1} - t^{\ell-2} - \dots - t - 1$$

This is not a reciprocal polynomial. Hence g is not conjugate to an automorphism. Indeed, if h is an automorphism of a projective surface Z , then h^* preserves the intersection form and the ample cone on the Néron-Severi group; since this intersection form is non-degenerate, of signature $(1, m)$, the characteristic polynomial of h^* is a reciprocal polynomial.

More precisely, if $\ell \geq 3$, then λ_ℓ is a Pisot number of degree ≥ 3 . As such, all its powers λ_ℓ^n , $n \geq 1$, are Pisot numbers of degree ≥ 3 . Hence, they are not Salem or quadratic integer and, as such, cannot be the dynamical degree of an automorphism.

If $\ell = 2$, then $\lambda_2 = (1 + \sqrt{5})/2$ is the golden mean and $\lambda_2^2 = (3 + \sqrt{5})/2$ is reciprocal. Thus, a priori, g^2 could be birationally conjugate to an automorphism. On the other hand, the eigenvectors of g_W^* corresponding to the eigenvalue λ_2 are all proportional to

$$u := (2 + \sqrt{5})[L] - (3/2 + \sqrt{5}/2)[E_1] - (1/2 + \sqrt{5}/2)[E_2 + E_3 + F_2] - [F_1],$$

and one verifies that $u \cdot u > 0$. This implies that g_W^n is not birationally conjugate to an automorphism for any $n \neq 0$ (see [11], Theorem 0.4). \square

Corollary 3.5. *No iterate f_X^n , $n \neq 0$, of the pseudo-automorphism f_X of X is conjugate, by any birational transformation $\varphi: Z \dashrightarrow X$, to an automorphism of a smooth rational threefold Z .*

Proof. Since g^n is not birationally conjugate to an automorphism, Corollary 1.6 of [3] shows that f^{4n} is not birationally conjugate to an automorphism. \square

3.1.7. No g -invariant foliation.

Theorem 3.6. *The surface W does not carry any g^k -invariant foliation of dimension 1 if $k \neq 0$.*

Proof. We refer to Section 4.1 for the definitions concerning foliations, and their invariance under the action of a birational mapping. Assume that a non-trivial iterate of g preserves a foliation \mathcal{F} .

Since $\ell \geq 2$, we know that $\lambda_1(g) > 1$. The classification theorem obtained by Cantat and Favre (see [8]) implies that a non-trivial iterate g^m is conjugate to one of the following:

- (a) a monomial transformation $(x, y) \mapsto (x^a y^b, x^c y^d)$ where a, b, c , and d are the coefficients of an element of $\mathrm{GL}_2(\mathbf{Z})$;
- (a') a quotient of case (a) by the involution $(x, y) \mapsto (x^{-1}, y^{-1})$;
- (b) a Kummer example, i.e. an automorphism h of a rational surface which "comes from" a linear automorphism of a torus \mathbf{C}^2/Λ after a finite cover and a contraction of finitely many invariant exceptional divisors.

In cases (a) and (a'), the dynamical degree is a quadratic integer. In case (b), g^m would be conjugate to an automorphism. Thus, Proposition 3.4 provides a contradiction when $\ell \geq 3$.

Now let us consider the case $\ell = 2$. We have seen that g is not conjugate to an automorphism, so we need to consider only cases (a) and (a'); we assume that property (a) is satisfied: There exists a monomial map $M: \mathbb{P}^2 \dashrightarrow \mathbb{P}^2$ and a conjugacy $\psi: \mathbb{P}^2 \rightarrow W$ such $\psi \circ M = g^m \circ \psi$. (case (a') is dealt with similar arguments). Since $\ell = 2$, the dynamical degree $\lambda_1(g)$ is the golden mean $\mu = (1 + \sqrt{5})/2$. This implies that M is a hyperbolic element of $\mathrm{GL}_2(\mathbf{Z})$: its spectral radius λ_M is a quadratic integer > 1 ; this the dynamical degree is invariant under conjugacy, and λ_M is the dynamical degree of M , one gets $\lambda_M = \mu^m$.

If q is a periodic point of M of period k , the eigenvalues of the differential $D(M^k)_q$ has two eigenvalues, $\mu_1 = \pm \mu^{mk}$ and $\mu_2 \pm = (\mu')^{mk}$, with $\mu' = (1 - \sqrt{5})/2$. In particular, these eigenvalues are not equal to 1; more precisely $\mu_1^{n_1} / \mu_2^{n_2} \neq 1$ for all pairs of positive integers (n_1, n_2) . We shall use this property to derive a contradiction. For this, we start by an easy observation about blow-ups.

Suppose that p is a fixed point of a local surface diffeomorphism h . Suppose that (X_1, X_2) is local coordinate system with $p = X_1 \cap X_2$ and that Dh_p is diagonal, with multiplier μ_j along the X_j -axis.

Lemma 3.7. *Let Z denote the space obtained by blowing up the point p , and let E_p denote the exceptional blow-up divisor. Then h lifts to a diffeomorphism \hat{h} of a neighborhood of E_p inside Z , $E_p \cap X_j$ is a fixed point of \hat{h} , and the local multipliers at this point are μ_j and μ_i/μ_j , where $i \neq j$.*

Blow up one of the fixed points of $E_p \cap X_j$. Continue this way and blow up fixed points over p several times. Again let \hat{h} denote the resulting diffeomorphism. If E' and E'' are exceptional blow-up divisors, the intersection points of the form $E' \cap E''$ will be fixed by \hat{h} . The following is an easy observation about the induced maps on blowups:

Lemma 3.8. *The diffeomorphism \hat{h} fixes the blow-up divisors E' and E'' . The multipliers of \hat{h} at $E' \cap E''$ are of the form $\mu_i^{n_i}/\mu_j^{n_j}$ for positive integers n_1, n_2 . If the multiplier at the fixed point(s) of the restricted map $\hat{h}|_{E'}$ is not equal to 1, then $\hat{h}|_{E'}$ has exactly two fixed points.*

Now to continue the proof of the Theorem, we recall that the only invariant curves of g^m are $\Sigma_{0,2}$ and β_0 . The curve $\Sigma_{0,2}$ consists of fixed points, all of which are parabolic; and the only fixed point on β_0 is $\beta_0 \cap \Sigma_{0,2}$. Let φ denote ψ^{-1} . Two cases may occur.

First, assume that φ is biregular from a neighborhood \mathcal{U} of a point $p \in \Sigma_{0,2}$ to a neighborhood \mathcal{V} of the point $q = \varphi(p)$; changing p into a nearby point if necessary, we can assume that p and q are not indeterminacy points of g^m and M . Then, q is a fixed point of M , and $D\varphi_p$ conjugates Dg_p^m to DM_q ; this contradicts the fact that p is a parabolic fixed point of g^m while all fixed points of M are saddle points.

The alternative is that φ blows down $\Sigma_{0,2}$ to an indeterminacy point q of ψ . Let $\varepsilon: Z \rightarrow \mathbb{P}^2$ be a sequence of blow-ups of points above q such that $\psi \circ \varepsilon$ is regular in a neighborhood of $\varepsilon^{-1}(q)$. Denote by \hat{M} the transformation $\varepsilon^{-1} \circ M \circ \varepsilon$ of the surface Z . Let C be an irreducible component of the exceptional divisor of ε which is mapped to $\Sigma_{0,2}$ by $\psi \circ \varepsilon$. Then, $\psi \circ \varepsilon$ is biregular in a neighborhood of the generic point of C . If q is not an indeterminacy point of M , one gets a contradiction because $\psi \circ \varepsilon$ should conjugate g^m to \hat{M} and, by Lemma 3.7, \hat{M} has no parabolic fixed point on C . If q is an indeterminacy point of M , one easily verifies that C cannot be \hat{M} -invariant, because M is a hyperbolic monomial mapping. Again, one gets a contradiction.

Case (a') is dealt with similarly. □

4. NO INVARIANT FOLIATIONS: FOLIATIONS BY CURVES

In this section we prove that the non-trivial iterates of f_X do not preserve any foliation of X of dimension 1.

4.1. Invariant foliations. Let M be a complex projective variety. A foliation \mathcal{F} of dimension 1 on M is given by an open cover $\{\mathcal{U}_i\}$ of M and holomorphic vector fields V_i on each \mathcal{U}_i such that

- (i) on the intersections $\mathcal{U}_i \cap \mathcal{U}_j$, the vector fields V_i and V_j determine the same tangent directions: There is a holomorphic function $\alpha_{i,j}: \mathcal{U}_i \cap \mathcal{U}_j \rightarrow \mathbb{C}^*$ such that

$$V_i = \alpha_{i,j} V_j.$$

(the functions $\alpha_{i,j}$ form a cocycle, i.e. an element of the Čech cohomology group $H^1(M, \mathcal{O}_M^*)$)

- (ii) the vector fields do not vanish in codimension 1; in other words, the **singular locus** $\text{Sing}(\mathcal{F})$ of the foliation, which is the set of points locally defined by the equation $V_i = 0$, has codimension ≥ 2 .

The **local leaves** of \mathcal{F} are defined in $\mathcal{U}_i \setminus \text{Sing}(\mathcal{F})$ by integration of the vector field V_i ; property (i) shows that they glue together to define the **global leaves** of \mathcal{F} (in the complement of $\text{Sing}(\mathcal{F})$). An algebraic curve $C \subset M$ is called an **algebraic leaf** if the defining vector fields V_i are tangent to C ; thus, an algebraic leaf may include singularities of \mathcal{F} and it may even be contained in the singular locus of \mathcal{F} .

If the second assumption is not satisfied, one can divide each V_i by a local equation f_i of the codimension 1 part of $\text{Sing}(\mathcal{F})$; one then gets a new family of vector fields V'_i and a new cocycle $\alpha_{i,j}(f_j/f_i)$, but the leaves of \mathcal{F} remain locally the same (see below).

Let f be a birational transformation of M . One says that f preserves the foliation \mathcal{F} if f maps local leaves to local leaves. More precisely, for x in $\mathcal{U}_i \setminus \text{Ind}(f)$ and \mathcal{U}_j an open set that contains $f(x)$, one wants $Df_x(V_i(x))$ to be proportional to $V_j(f(x))$. According to property (i), this does not depend on the choices of the open sets \mathcal{U}_i and \mathcal{U}_j .

4.2. Action of J on foliations. Recall that J flips $\Sigma_{0,1}$ into $\Sigma_{2,3}$, as described in Section 2.2.2. The following lemma describes the action of J on foliations of dimension 1 that are transverse to the edge $\Sigma_{0,1}$ of the tetrahedron Δ . By symmetry, the action of J is the same near all six edges $\Sigma_{i,j}$ of Δ .

Lemma 4.1. *If \mathcal{F} is a one-dimensional foliation near a point q of $\Sigma_{0,1} \setminus \{e_2, e_3\}$ that is transverse to $\Sigma_{0,1}$, its image under the action of J determines a foliation of dimension 1 that is tangent to $\Sigma_{2,3}$ (i.e. $\Sigma_{2,3}$ is an algebraic leaf of $J^*\mathcal{F}$).*

Proof. Consider J as a birational mapping from the open set $x_3 \neq 0$ to the open set $x_0 \neq 0$. We set $x_3 = 1$ in the first open set and denote the coordinates by $[x_0 : x_1 : x_2 : 1]$; in the second open set, we set $x_0 = 1$ and use coordinates $[1 : u : v : w]$. The map J can be written as

$$J[x_0 : x_1 : x_2 : 1] = \left[1 : \frac{x_0}{x_1} : \frac{x_0}{x_2} : x_0 \right]$$

and its differential is

$$DJ_{(x_0, x_1, x_2)} = \begin{pmatrix} 1/x_1 & -x_0/x_1^2 & 0 \\ 1/x_2 & 0 & -x_0/x_2^2 \\ 1 & 0 & 0 \end{pmatrix}.$$

The pre-image of a point $[1 : u : v : w]$ is the point with coordinates $[w : w/u : w/v : 1]$. Thus, given a local holomorphic vector fields V near a point q of $\Sigma_{0,1}$ in the open set $x_3 \neq 0$,

$$V(x_0, x_1, x_2) = a\partial_{x_0} + b\partial_{x_1} + c\partial_{x_2},$$

one gets

$$\begin{aligned} J_*V(u, v, w) &= \left(\frac{u}{w}a(w, w/u, w/v) - \frac{u^2}{w}b(w, w/u, w/v) \right) \partial_u \\ &+ \left(\frac{v}{w}a(w, w/u, w/v) - \frac{v^2}{w}c(w, w/u, w/v) \right) \partial_v \\ &+ a(w, w/u, w/v)\partial_w. \end{aligned}$$

We want to understand what happens to the foliation defined by J_*V when (u, v, w) approaches the line $\Sigma_{2,3}$, i.e. when v and w vanish simultaneously. For this, one needs, first, to multiply J_*V by a holomorphic function that vanishes along the poles of J_*V , so as to kill the poles of this meromorphic vector fields.

By assumption, V is transverse to $\Sigma_{0,1}$ near the point q : Which means that the functions a and b do not vanish simultaneously along $\Sigma_{0,1}$ in a neighborhood of q . Assume that $a(q) \neq 0$ (the case $b(q) \neq 0$ is dealt with similarly). Then, a is a unit in a neighborhood of q , and dividing V by a , we can (and do) assume that a is a non-zero constant in a neighborhood of q . Thus, J_*V has a pole along $w = 0$, and the local holomorphic vector fields defining $J_*\mathcal{F}$ are multiples of

$$wJ_*V = (ua - u^2b(w, w/u, w/v)) \partial_u + (va - v^2c(w, w/u, w/v)) \partial_v + wa\partial_w.$$

Either wJ_*V is already holomorphic, or we have to multiply it by a function $\varphi(u, v, w)$ that vanishes along its poles. In any case, wa and va vanish along $\Sigma_{2,3}$, and so does $\varphi(u, v, w)v^2c(w, w/u, w/v)$ if it is holomorphic. Thus, once J_*V is multiplied by a holomorphic function in order to compensate for its poles, its second and third coordinates vanish along $\Sigma_{2,3}$. This implies that

$\Sigma_{2,3}$ is a leaf of $J_*\mathcal{F}$ (which includes the case that $\Sigma_{2,3}$ may be contained in $\text{Sing}(J_*\mathcal{F})$). \square

4.3. No invariant foliation. In what follows, we assume that there is a foliation \mathcal{F} of dimension 1 on X that is invariant under the action of f_X^k for some $k \geq 1$. We fix a family of local vector fields (\mathcal{U}_i, V_i) defining \mathcal{F} that satisfy the two properties (i) and (ii), and seek for a contradiction.

4.3.1. Induced foliation along Σ_0 . Two cases may occur. Either \mathcal{F} is tangent to Σ_0^X at the generic point of Σ_0^X , or it is generically transverse to Σ_0^X . In this section, we assume that \mathcal{F} is tangent to Σ_0^X . Thus, Σ_0^X is endowed with the codimension 1 foliation \mathcal{F}_0 that is induced by \mathcal{F} . Local vector fields defining \mathcal{F}_0 are obtained by restricting the V_i to Σ_0 and then dividing $V_i|_{\Sigma_0}$ by the equation of the codimension 1 part of $\{V_i = 0\}$ if necessary.

Since \mathcal{F} is f_X^k -invariant, \mathcal{F}_0 is g^k -invariant; more precisely, the projection of \mathcal{F}_0 onto Σ_0 is g^k -invariant. But this is not possible by Theorem 3.6. Since f_X permutes the four irreducible components of the invariant cycle Γ , we have proved the following lemma.

Lemma 4.2. *If $\ell \geq 2$ and $k \neq 0$, any f_X^k -invariant foliation \mathcal{F} is transverse to Σ_0^X , E_1 , Σ_2^X , and E_3 at the generic point of these four surfaces.*

In what follows, we assume that the invariant foliation \mathcal{F} is transverse to Σ_0^X , E_1 , Σ_2^X , and E_3 at the generic point, and we derive a contradiction. For simplicity, the proof is given for f_X -invariant foliations, but it applies directly to f_X^k -invariant foliations.

4.3.2. Behavior along indeterminacies. Consider the line $L_1 = \Sigma_{0,3} \subset \Sigma_0$. Its “image” by J is the opposite edge $\Sigma_{1,2}$ of the tetrahedron Δ . Then, its image by the linear projective transformation L is the line $L(\Sigma_{1,2})$; it contains the points e_1 and p_1 , and it can be defined by the equations $x_2 = x_3 - cx_0 = 0$. This line is transverse to the plane Σ_0 and intersects it in e_1 .

Under the action of f_X^2 this line $L(\Sigma_{1,2})$, or more precisely its strict transform in X , is mapped regularly to the curve $L_5 \subset \Sigma_0$ defined by the equations

$$x_0 = 0, \quad x_1 = (a + c)x_2.$$

Lemma 4.3. *The negative orbit of the curve L_1 under the action of g is an infinite collection of curves $g^{-n}(L_1)$. None of these curves $g^{-n}(L_1)$, $n \geq 1$, is contained in the indeterminacy locus of f^k for $k \leq 4$.*

Similarly, the positive orbit of the line L_5 is an infinite collection of curves, and none of the curves $g^n(L_5)$ is contained in the indeterminacy locus of f^{-k} for $k \leq 4$.

Proof. The first assertion is proved at the very end of Section 3.1.3.

The second assertion is proved along the same lines, but instead of using the invariant curve E_1 of W , we use the curve β_0 . The line L_5 intersects the curve β_0 at $q_0 = [0 : a + c : 1 : \frac{a}{c}(a + c)]$. The curve β_0 is mapped to β_1 , then to β_2 , β_3 , and back to β_0 under the action of f . If one parametrizes β_0 by $[0 : t : 1 : \frac{a}{c}t]$ then f^4 acts as $t \mapsto t + (a^2 + ac + c^2)/a$ and q_0 corresponds to the parameter $t_0 = a + c$. The orbit of q_0 under the action of f^4 is the sequence of points $q_{4n} \in \beta_0$ with parameters $(a + c) + n(a^2 + ac + c^2)/a$. None of them is an indeterminacy point of f .

Similarly, if (u, v, w) are local coordinates of the exceptional divisor $E_1 \subset Y$, and $\pi(u, v, w) = [uv : 1 : uw : u]$ is the blow down map, then β_1 is the curve of the exceptional divisor $E_1 = \{u = 0\}$ parametrized by $(u = 0, v = \frac{c}{a}s, w = s)$. Using this parametrization, the point q_{4n} is mapped by f to the point $q_{4n+1} \in \beta_1$ corresponding to the parameter s defined by

$$s^{-1} = \frac{a^2 + ac + c^2}{c} \cdot \frac{(a/c)^{n+1} - 1}{(a/c) - 1}.$$

Since a/c is not a root of unity, none of these points is an indeterminacy point of f_X . The proof is similar for the points $q_{4n+j} = f^j(q_{4n})$, $j = 2, 3$. \square

Now, consider the foliation \mathcal{F} along the family of curves $g^{-n}(L_1)$, $n \geq 1$. The tangency locus of \mathcal{F} with Σ_0^X is a Zariski closed set. Therefore, \mathcal{F} is transverse to Σ_0 along the generic point of $g^{-n}(L_1)$ for large enough n . Since g and f are regular near the generic point of $g^{-n}(L_1)$ (because $n \geq 1$) and f preserves both Σ_0 and \mathcal{F} , we deduce that \mathcal{F} is transverse to Σ_0 at the generic point of L_1 .

Lemma 4.4. *The curve $L(\Sigma_{1,2})$ is an algebraic leaf of the foliation \mathcal{F} .*

Proof. Since the foliation \mathcal{F} is transverse to $L_1 = \Sigma_{0,3}$, Lemma 4.1 shows that J transforms \mathcal{F} into a foliation that is tangent to $\Sigma_{1,2}$. The conclusion follows from the definition of f as $L \circ J$. \square

4.3.3. *Conclusion.* The curve $L(\Sigma_{1,2})$ is a leaf of \mathcal{F} that is contained in Σ_2 . Its image L_5 under f^2 is a leaf of \mathcal{F} that is contained in Σ_0 , because f^2 is regular at the generic point of $L(\Sigma_{1,2})$. Thus, L_5 is contained in the tangency locus of \mathcal{F} and Σ_0 . Moreover, L_5 is not contained in the exceptional set of f^n and g^n , nor in their indeterminacy sets, for $n > 0$, hence the foliation \mathcal{F} is tangent to Σ_0 along the g -orbit of L_5 . Since this orbit is infinite, the tangency locus between \mathcal{F} and Σ_0 contains infinitely many curves and is not a proper Zariski closed subset of Σ_0 . This contradiction shows that f_X does not preserve any foliation of dimension 1.

The same strategy applies verbatim to rule out f_X^k -invariant foliations of dimension 1.

Proposition 4.5. *If $\ell \geq 2$ and (a, c) satisfies the ℓ -condition, then $f_X : X \dashrightarrow X$ and its non-trivial iterates do not preserve any dimension 1 foliation on X .*

5. NO INVARIANT FOLIATIONS: CO-DIMENSION 1 FOLIATIONS

In this section we prove that the pseudo-automorphism f_X and its iterates f_X^k , $k \neq 0$, do not preserve any foliation of codimension 1. We proceed in three steps. First, we exclude the existence of periodic but non invariant foliations. Then, we show that there is no invariant algebraic fibration. The third step excludes the existence of f -invariant foliation.

5.1. Foliations of codimension 1.

5.1.1. *Local 1-forms.* Let M be a smooth complex projective threefold. A codimension 1 (singular) holomorphic foliation \mathcal{G} of M is determined by a covering \mathcal{U}_i of M together with holomorphic 1-forms $\omega_i \in H^0(\mathcal{U}_i, \Omega_M^1)$ such that

- (i) ω_i does not vanish in codimension 1;
- (ii) $\omega_i \wedge d\omega_i = 0$ on \mathcal{U}_i ;
- (iii) $\omega_i = g_{i,j}\omega_j$ on $\mathcal{U}_i \cap \mathcal{U}_j$ for some $g_{i,j} \in \mathcal{O}^*(\mathcal{U}_i \cap \mathcal{U}_j)$.

The integrability condition (ii) assures that the distribution of planes $\ker(\omega_x) \subset T_x M$ is integrable: The integral submanifolds are the **local leaves** of the foliation \mathcal{G} . Condition (iii) means that the local leaves defined on \mathcal{U}_i by ω_i patch together with the local leaves defined on \mathcal{U}_j by ω_j . Condition (i) can always be achieved by dividing ω_i by the equation of its zero set if it vanishes in codimension 1.

The **singular locus** of \mathcal{G} is locally defined by

$$\text{Sing}(\mathcal{G}) \cap \mathcal{U}_i = \{z \in \mathcal{U}_i \mid \omega_i(z) = 0\}.$$

This does not depend on the choice of the local defining 1-form ω_i because the $g_{i,j}$ do not vanish. Thus, $\text{Sing}(\mathcal{G})$ is a well defined complex analytic subset of X of codimension ≥ 2 .

If h is a birational transformation of X , one says that h **preserves** the foliation \mathcal{G} , or that \mathcal{G} is **invariant** under the action of h , if h maps local leaves to local leaves. This is equivalent to $h^*\omega_i = \phi_{i,j}\omega_j$ on $h^{-1}(\mathcal{U}_i) \cap \mathcal{U}_j$ for some meromorphic functions $\phi_{i,j}$.

5.1.2. *Global 1-forms and the co-normal bundle.* If ω is a global meromorphic 1-form that satisfies $\omega \wedge \omega = 0$, then ω determines a unique foliation \mathcal{G} . In local charts \mathcal{U}_i , there are meromorphic functions h_i such that the zeros (resp. the poles) of h_i coincide with the divisorial part of the zeros of ω (resp. with the poles); such a function is unique up to multiplication by a unit a , i.e. a holomorphic function that does not vanish. Then, the local 1-forms $\omega_i = (h_i)^{-1}\omega$ determine the foliation \mathcal{G} in the sense of § 5.1.1.

Consider a foliation \mathcal{G} determined by the family $(\mathcal{U}_i, \omega_i)$ of local 1-forms. The cocycle $(g_{i,j}) \in H^1(M, \mathcal{O}_M^*)$ defined by property (iii) determines a line bundle \mathcal{L} . Assume that its dual bundle \mathcal{L}^\vee has a meromorphic section s : Locally, s is defined by meromorphic functions $s_i: \mathcal{U}_i \rightarrow \mathbf{C}$ satisfying

$$s_i = (g_{i,j})^{-1} s_j.$$

Define ω locally by $\omega := s_i \omega_i$; then, ω is a global meromorphic 1-form that determines \mathcal{G} . Thus, the line bundle \mathcal{L}^\vee can be identified to the **co-normal bundle** of \mathcal{G} , and we denote it by $N_{\mathcal{G}}^*$ in what follows.

If \mathcal{G} is defined by the global meromorphic 1-form ω the divisor

$$D(\omega) = \text{Zeros}(\omega) - \text{Poles}(\omega)$$

satisfies

$$[D(\omega)] = c_1(N_{\mathcal{G}}^*)$$

where c_1 denotes the Chern class and $[D]$ the divisor class (viewed in $H^{1,1}(M; \mathbf{R})$).

Remark 5.1. On a rational variety, the line bundle $N_{\mathcal{G}}^*$ has a meromorphic section (because $h^{1,0}(M) = 0$). Thus, codimension 1 foliations are always defined by global meromorphic 1-forms.

5.2. **From dimension 2 to dimension 1.** In this paragraph, we fix an integer $k > 1$, and we assume that f_X^k preserves a codimension 1 foliation \mathcal{G} of X which is not invariant by f_X^j for $1 \leq j \leq k-1$.

The orbit of \mathcal{G} under the action of f and its iterates form a collection of k -distinct foliations $\mathcal{G}_j = (f^*)^j \mathcal{G}$, $1 \leq j \leq k$, with $\mathcal{G}_k = \mathcal{G}$. Since these foliations are distinct, the tangent planes to \mathcal{G}_1 and to \mathcal{G}_2 are distinct planes in $T_m X$ at the generic point $m \in X$; hence, $T_m \mathcal{G}_1 \cap T_m \mathcal{G}_2$ is a line $L_{1,2}(m)$ in $T_m X$. These lines form a meromorphic distribution of tangent lines to X , this distribution defines a foliation \mathcal{F} of dimension 1 on X , and this foliation is f^k -invariant. This remark contradicts the main result of Section 4 and proves the following proposition.

Proposition 5.2. *Let ℓ be an integer with $\ell \geq 2$. Let $f_X: X \dashrightarrow X$ be the pseudo-automorphism given by a couple of parameters (a, c) that satisfies the*

ℓ -condition. If a non-trivial iterate f_X^k of f_X preserves a foliation \mathcal{G} , then f_X preserves \mathcal{G} .

5.3. There is no invariant fibration.

Proposition 5.3. *Let ℓ be an integer with $\ell \geq 2$. If the parameter (a, c) satisfies the ℓ -condition, the automorphism f_X and its iterates f_X^k , $k > 1$, do not preserve any invariant fibration.*

To prove this assertion, we fix a positive integer k and suppose that f_X^k preserves a fibration $\varphi: X \dashrightarrow C$, where C is a (smooth) connected Riemann surface. In other words, $\varphi \circ f_X^k = h \circ \varphi$ for some automorphism h of C . From Proposition 5.2, we may – and do – assume that

$$k = 1.$$

5.3.1. The linear system determined by φ .

Lemma 5.4. *The curve C is a projective line $\mathbb{P}^1(\mathbf{C})$ and the automorphism $h: C \rightarrow C$ is conjugate to a similitude $\zeta \mapsto \kappa\zeta$ or to the translation $\zeta \mapsto \zeta + 1$.*

Proof. Since X is rational, the curve C is covered by a rational curve; hence, C is isomorphic to $\mathbb{P}^1(\mathbf{C})$. The automorphism h of C is a Möbius transformation of the Riemann sphere and, as such, is conjugate to a similitude or a translation. \square

The fibers of φ determine a linear system of hypersurfaces $S(c) = \varphi^{-1}(c)$ in X , $c \in C$. From Section 2.2.9, we deduce that there is a positive integer r such that the divisor class $[S(c)]$ satisfies $[S(c)] = r[\Gamma]$ for all c .

Viewed on $\mathbb{P}_{\mathbf{C}}^3$, the pencil of hypersurfaces $(S(c))_{c \in C}$ is generated by the two surfaces $S(0)$ and $S(\infty)$. Changing the coordinate of C if necessary, one may assume that $S(\infty)$ is the hypersurface $\Sigma_0 + \Sigma_2$, with multiplicity r ; its equation is

$$Q = (x_0x_2)^r.$$

The hypersurface $S(0)$ is also given by a homogeneous polynomial P of degree r . The invariance of the pencil reads

$$f^*Q = \text{Jac}(f)^r Q, \text{ and } f^*P = \text{Jac}(f)^r \kappa P \quad \text{or } f^*P = \text{Jac}(f)^r (P + Q).$$

according to the two distinct possibilities for h . (here f^*P denotes the composition of P with a lift F of f to \mathbf{C}^4 , as in Section 2.2.9, and $\text{Jac}(f)$ stands for $\text{Jac}(F)$)

The base points of the linear system $(S(c))_{c \in C}$ form a curve of X . This curve B is contained in all members of the linear system; hence, B is contained in Γ . Its trace on Σ_0 is a g -invariant curve.

5.3.2. *Conclusion by computation.* To study the equation P of $S(0)$ in \mathbb{P}^3 , note that Lemma 3.3 implies that the equation $P(0, x_1, x_2, x_3) = 0$ defines a divisor $B|_{\Sigma_0} \subset \Sigma_0$ of the form $m_1\Sigma_{0,2} + m_2\beta_0$; hence

$$P(0, x_1, x_2, x_3) = c^{st} x_2^{m_1} (ax_1 - cx_3)^{m_2}.$$

The same argument, once applied to the plane Σ_2 , shows that

$$P(x_0, x_1, 0, x_3) = c^{st} x_0^{m'_1} (ax_1 - cx_3)^{m'_2}.$$

Thus,

$$P = c_1 x_2^{m_1} (ax_1 - cx_3)^{m_2} + c_2 x_0^{m'_1} (ax_1 - cx_3)^{m'_2} + x_0 x_2 R$$

for some homogeneous polynomial $R(x_0, x_1, x_2, x_3)$ of degree $\deg(P) - 2$. The integers m_1, m_2 and m'_1, m'_2 satisfy $m_1 + m_2 = m'_1 + m'_2 = \deg(P) = 2r$. On the other hand, P vanishes at e_i with multiplicity r , so that the degree of x_i in each monomial of P is at most r . Thus, $m_1 = m_2 = m'_1 = m'_2 = r$ and we get:

Lemma 5.5. *The homogeneous polynomial P can be written*

$$P = c_1 x_2^r (ax_1 - cx_3)^r + c_2 x_0^r (ax_1 - cx_3)^r + x_0 x_2 R$$

for some non-zero constants c_1 and c_2 and some homogeneous polynomial R of degree $2r - 2$.

We shall now derive a contradiction. If $P' = \kappa P + \mu Q$ with $\kappa \in \mathbf{C}$ and $\mu \in \mathbf{C}$, then

$$\begin{aligned} P'(0, x_1, x_2, x_3) &= \kappa c_1 x_2^r (ax_1 - cx_3)^r \\ P'(x_0, x_1, 0, x_3) &= \kappa c_2 x_0^r (ax_1 - cx_3)^r. \end{aligned}$$

In particular $P'(0, x_1, x_2, ax_1/c) = 0$ and $P'(x_0, x_1, 0, cx_1/a) = 0$. But $f^*P = \text{Jac}(f)^r(\kappa P + \mu Q)$ for some complex numbers κ and μ , and at the same time it is equal to

$$\text{Jac}(f)^r \{c_1 (cx_0 - ax_2)^r x_3^r + c_2 (ax_0 - cx_2)^r x_1^r + x_0 x_2 R'\}$$

for some homogeneous polynomial R' . Evaluating along $(0, x_1, x_2, ax_1/c)$ and $(x_0, x_1, 0, cx_1/a)$ one must obtain 0; hence,

$$c_1 a^{2r} + c_2 c^{2r} = 0 = c_1 c^{2r} + c_2 a^{2r}$$

and we deduce that $a^{2r} = -c^{2r}$ because c_1 and c_2 are not equal to zero. This is in contradiction with the ℓ -condition and this contradiction concludes the proof of Proposition 5.3.

5.4. From invariant foliations to invariant global 1-forms. Let (a, c) satisfy the ℓ -condition for some integer $\ell \geq 2$, and $f: X \dashrightarrow X$ be the pseudo-automorphism constructed in Section 2. Let \mathcal{G} be a codimension 1 foliation of X which is invariant under the action of f .

Since X is a rational variety, there exists a global meromorphic 1-form ω that defines \mathcal{G} . The pull-back of ω by f is another meromorphic 1-form defining \mathcal{G} . Hence, the divisor classes of $D(\omega)$ and $D(f^*\omega)$ coincide with the Chern class of the co-normal bundle $N_{\mathcal{G}}^*$. Since f_X is a pseudo-automorphism $[D(f_X^*\omega)] = f_X^*[D(\omega)]$, and

$$[D(\omega)] = c_1(N_{\mathcal{G}}^*) = f_X^*[D(\omega)].$$

In other words, the Chern class of the co-normal bundle is f_X^* -invariant. This provides a fixed vector in $H^{1,1}(X; \mathbf{R}) \cap H^2(X; \mathbf{Z})$.

The eigenspace of f_X^* corresponding to the eigenvalue 1 is the line $\mathbf{R}[\Gamma]$ in $H^{1,1}(X; \mathbf{R})$. As a consequence, there is a global meromorphic 2-form α on X that does not vanish, has poles along Γ (of order k for some $k > 0$), and defines the foliation \mathcal{G} . If β is another global meromorphic 2-form with the same properties, then β is a multiple of α by a meromorphic function φ , because they both define the same foliation; since β and α define the same divisor Γ , φ has no pole and no zero: Thus, φ is a non-zero constant. This argument proves the following result.

Lemma 5.6. *The Chern class $c_1(N_{\mathcal{G}}^*)$ is a negative multiple $-k[\Gamma]$ of the class of the invariant cycle Γ . The space $\mathcal{M}_{\mathcal{G}}^1(-k\Gamma)$ of meromorphic 1-forms α on X with $D(\alpha) = -k\Gamma$ is a complex vector space of dimension 1.*

Let $\alpha_{\mathcal{G}}$ be a non-zero element of $\mathcal{M}_{\mathcal{G}}^1(-k\Gamma)$. Being a pseudo-automorphism, the transformation f acts by pull-back on $\mathcal{M}_{\mathcal{G}}^1(-k\Gamma)$. Thus, *there is a non-zero complex number η such that*

$$f_X^*\alpha_{\mathcal{G}} = \eta \cdot \alpha_{\mathcal{G}}.$$

All we need to do, now, is to exclude the existence of such an f_X -invariant, integrable 1-form.

5.5. Invariant 1-forms.

5.5.1. $\alpha_{\mathcal{G}}$ is closed. If $d\alpha_{\mathcal{G}} \neq 0$, there is a meromorphic vector field $V_{\mathcal{G}}$ such that

$$d\alpha_{\mathcal{G}} = \iota_{V_{\mathcal{G}}}\Omega$$

where ι_{ξ} denotes the interior product with ξ , and Ω is the f -invariant 3-form described in Section 2.2.9. Since Ω and $\alpha_{\mathcal{G}}$ are multiplied by non-zero complex numbers under the action of f , $V_{\mathcal{G}}$ is also multiplied by some non-zero

complex number. Thus, the foliation determined by V_G is f_X -invariant. This is a contradiction with Proposition 4.5 of Section 4, so that the following lemma is proved.

Lemma 5.7. *The 1-form α_G is closed.*

Remark 5.8. The non-existence of 1-dimensional foliations is not necessary to prove this lemma. Indeed, V_G has no poles and vanishes only along Γ . Thus, if one projects V_G onto \mathbb{P}^3 , one gets a vector field that vanishes along $\Sigma_0 \cup \Sigma_2$. It is easy to exclude the existence of such an f -invariant vector field.

5.5.2. *First integral.*

Lemma 5.9. *The poles of α_G along Γ have order $k \geq 2$.*

Proof. Consider the set of lines through the point e_1 in \mathbb{P}^3 . When lifted to X , these lines intersect E_1 but do not intersect the other irreducible components of Γ , except for those lines that are contained in Γ . Thus, when one restricts α_G to such a curve, one gets a 1-form on $\mathbb{P}^1_{\mathbb{C}}$, with a unique pole. If the form does not vanish, this pole must have multiplicity ≥ 2 .

Apply the same argument for the family of lines through e_3 . Either α_G vanishes identically along this family of lines, or the order of the pole of α_G along E_3 is ≥ 2 .

This argument concludes the proof if α_G does not vanish identically along one of these two families of lines. If it does, the foliation defined by α_G is the pencil of planes containing the curve $\Sigma_{0,2}$. It is easy to see that f does not preserve any pencil of planes (and this is a consequence of Proposition 5.3). Thus, $k \geq 2$. \square

Since α_G is closed, α_G is locally the differential of a function. Locally, $\alpha_G = d\varphi$, where φ is obtained by integration of α_G :

$$\varphi(z) - \varphi(z_0) = \int_{\gamma} \alpha_G$$

where γ is a local path from z_0 to z . The local function φ is a well defined meromorphic function on any simply connected subset \mathcal{U} of $X \setminus \Gamma$.

To show that φ is also locally defined around Γ , one needs to show that the residue of α_G along Γ vanishes. Let \mathcal{U} be a small ball that intersects Σ_0^X , V be a disk in \mathcal{U} that intersects Σ_0^X transversally, and β be a loop in V that turns once around $V \cap \Gamma$. One wants to show that

$$\int_{\beta} \alpha_G = 0. \quad (5.1)$$

For V , one can take the intersection of the strict transform of a line $L \subset \mathbb{P}^3$ with \mathcal{U} . The line L and the point p_3 generate a plane $\Pi \subset \mathbb{P}^3$. Let Π^X be the strict

transform of Π in X ; it intersects P_3 on a line $\Pi^X \cap P_3$ and this line intersects $\Sigma_0^X \cap P_3$ in a unique point z . Now, one can deform the loop β within Π^X to a loop with the same base point that go straight to P_3 , makes one turn around z in the line $\Pi^X \cap P_3$, and come back to the base point along the same way. But the line $\Pi^X \cap P_3$ is a sphere that intersects Γ at a unique point, namely z . Thus, one can change β continuously to a trivial loop, and we obtain Equality (5.1).

As a consequence, the local function φ is a well defined meromorphic function on any simply connected subset \mathcal{U} of X , even if \mathcal{U} intersects Γ ; moreover, $\varphi: \mathcal{U} \rightarrow \mathbf{C}$ is unique up to an additive constant. Thus, there is an open cover of X by simply connected domains \mathcal{U}_i and meromorphic functions $\varphi_i: \mathcal{U}_i \rightarrow \mathbf{C}$ such that

- $\alpha_{\mathcal{G}} = d\varphi_i$ in \mathcal{U}_i ;
- the intersections $\mathcal{U}_i \cap \mathcal{U}_j$ are connected (or empty);
- the functions φ_i satisfy a cocycle relation: $\varphi_i = \varphi_j + \delta_{i,j}$ on $\mathcal{U}_i \cap \mathcal{U}_j$ for some complex numbers $\delta_{i,j}$.

The cocycle $(\delta_{i,j})$ determines a class in $H^1(X; \mathbf{C})$ for Čech cohomology. But X is obtained from the projective space $\mathbb{P}_{\mathbf{C}}^3$ by a finite sequence of blow-ups and, as such, is simply connected. It follows that the cohomology class of the cocycle $(\delta_{i,j})$ is equal to zero: One can choose the functions φ_i in such a way that they glue together to define a global meromorphic function

$$\varphi_{\mathcal{G}}: X \dashrightarrow \mathbf{C}.$$

The level sets of $\varphi_{\mathcal{G}}$ form a meromorphic fibration of X by algebraic surfaces, the fibers of which are the Zariski closure of the leaves of \mathcal{G} . Thus, f preserves a fibration, in contradiction with Proposition 5.3. This contradiction shows that there is no invariant foliation of codimension 1 in X , and this concludes the proof of Theorem 1.2.

6. APPENDIX : A TYPICAL COMPUTATION

In this appendix, we describe the computation that leads to Lemma 2.3 and Proposition 2.6.

- The curve β_2 is parametrized by $t \mapsto [1 : t : 0 : ct/a]$. We have

$$f[x_0 : x_1 : x_2 : x_3] = [x_0x_1x_2 : x_1x_2x_3 + ax_0x_1x_2 : x_0x_2x_3 : x_0x_1x_3 + cx_0x_1x_2].$$

In good local coordinates (u, v, w) , the projection $\pi: Y \rightarrow \mathbb{P}_{\mathbf{C}}^2$ is given by

$$\pi(u, v, w) = [u : uv : uw : 1],$$

with the exceptional divisor $E_3^Y = \{u = 0\}$ that is mapped to the point $e_3 = [0 : 0 : 0 : 1]$. Consider f as a map from the open set $x_0 = 1$ to the open set $x_3 = 1$. One gets

$$f[1 : x_1 : x_2 : x_3] = \left[\frac{x_2}{x_3 + cx_2} : \frac{x_2}{x_3 + cx_2}(x_3 + a) : \frac{x_2}{x_3 + cx_2} \frac{x_3}{x_1} : 1 \right].$$

Hence, f_Y maps Σ_2^Y to E_3^Y , and in local affine coordinates (x_1, x_2, x_3) and (u, v, w) one has

$$f_Y(x_1, x_2, x_3) = \left(\frac{x_2}{x_3 + cx_2}, x_3 + a, \frac{x_3}{x_1} \right).$$

Applied to the parametrization of β_2 , one gets

$$t \mapsto [1 : t : 0 : ct/a] \mapsto (u', v', w') = (0, (ct + a^2)/a, c/a).$$

The image is a curve of E_3^Y (because $u' = 0$) that satisfies $ax_2 = cx_0$ (because $w' = c/a$).

• Then, consider the restriction of f_Y to E_3^Y . For this, compute $f \circ \pi$ in the (u, v, w) coordinates, to get

$$\begin{aligned} f \circ \pi(u, v, w) &= [u^3vw : u^2vw + au^3vw : u^2w : u^2v + cu^3vw] \\ &= [uvw : vw + auvw : w : v + cuvw] \end{aligned}$$

after division by the common factor u^2 . In particular, for $u = 0$, one gets

$$f \circ \pi(0, v, w) = [0 : vw : w : v].$$

This implies that E_3^Y is mapped to Σ_0 and, moreover, that E_3^Y appears with multiplicity 2 in the pull-back of Σ_0 by f_Y (because we had to divide by u^2). This proves two of our statements, namely $f_Y(E_3^Y) = \Sigma_0^Y$, and the coefficient -2 in front of \hat{E}_3 in the formula for f_X^*H . Then, the curve $f_Y(\beta_2)$ is parametrized by

$$t \mapsto [0 : (ct + a^2)/a : 1 : (ct + a^2)/c].$$

As mentioned, this curve is β_0 (i.e. $ax_1 = cx_3$ in Σ_0).

• One then pursues this kind of computation, by blowing up e_1 into E_1^Y . This gives $\pi(u, v, w) = [u : 1 : uv : uw]$ in local coordinates and

$$f[x_0 : x_1 : x_2 : x_3] = \left[\frac{x_0}{x_3 + ax_0} : 1 : \frac{x_0}{x_3 + ax_0} \frac{x_3}{x_1} : \frac{x_0}{x_3 + ax_0} \frac{x_3 + cx_2}{x_2} \right]$$

i.e. $(u, v, w) = (x_0/(x_3 + ax_0), x_3/x_1, (x_3 + cx_2)/x_2)$. Along the curve β_0 one gets the parametrization

$$t \mapsto (u', v', w') = (0, a/c, t + (a^2 + c^2)/c).$$

• Then, with coordinates (u, v, w) near E_1^Y , one obtains

$$f \circ \pi(u, v, w) = [v : vw + av : uvw : w + cv]$$

after division by the common factor u^2 . Hence, applied to the curve β_1 , one gets the new parametrization

$$t \mapsto [1 : t + \frac{a^2}{c} + c + a : 0 : \frac{c}{a}(t + \frac{a^2}{c} + c + a)]$$

of the curve β_2 . This proves that $h = f_Y^4$ transforms the parameter t into

$$t' = t + \frac{a^2}{c} + c + a,$$

as explained before Lemma 2.3.

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