Abstract framework

Smooth domain

Corner domains

Polyhedral domains

## Weighted analytic regularity in polyhedra

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Workshop High-Order Numerical Approximation for PDE Hausdorff Center for Mathematics, Bonn, February 6-10, 2012

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#### Outline









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## **Question of regularity**

Consider a (elliptic) boundary value problem, written in compact form as

#### $\mathbb{P}\boldsymbol{u} = \boldsymbol{q}$

where *q* may include interior, boundary, or interface data.

For a possible numerical approximation, answering (a priori) the question of regularity for  $\boldsymbol{u}$  is of fundamental importance.

Any regularity statement takes the form

 $oldsymbol{u} \in \mathbb{U}_{ extsf{base}}$  and  $oldsymbol{q} \in \mathbb{Q}_{ extsf{data}}$   $\implies$   $oldsymbol{u} \in \mathbb{U}_{ extsf{sol}}$ 

#### Ideally

- U<sub>base</sub> is a space where existence of solutions is known (e.g. variational space)
- $\mathbb{U}_{sol}$  is optimal in the sense that  $\mathbb{P}$  is bounded  $\mathbb{U}_{sol} \to \mathbb{Q}_{data}$ .
- If  $\mathbb{Q}_{data}$  is a space of piecewise analytic data,  $\mathbb{U}_{sol}$  is a space of piecewise analytic solutions.

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#### Three types of possible theorems

Type C: Existence of solutions in a space 𝒴

Coercivity or Fredholm alternative.

Type B: Basic regularity

 $\pmb{u} \in \mathbb{U}_{\mathsf{base}}$  and  $\pmb{q} \in \mathbb{Q}_{\mathsf{data}} \implies \pmb{u} \in \mathbb{U}_{\mathsf{sol}}$  with

•  $\mathbb{U}_{base} = \mathbb{V}$ 

② U<sub>sol</sub> = U<sup>B</sup><sub>sol</sub> involving estimates on a finite number of derivatives (e.g. space of strong solutions) — for suitable Q<sub>data</sub>.

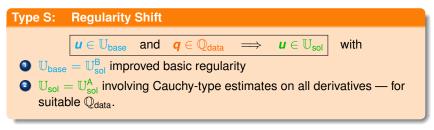
#### Type A: Analytic regularity

 $\boldsymbol{u} \in \mathbb{U}_{\mathsf{base}}$  and  $\boldsymbol{q} \in \mathbb{Q}_{\mathsf{data}} \implies \boldsymbol{u} \in \mathbb{U}_{\mathsf{sol}}$  with

U<sub>sol</sub> = U<sup>A</sup><sub>sol</sub> involving Cauchy-type estimates on all derivatives — for suitable Q<sub>data</sub>.

Polyhedral domains

## A fourth type of statement and a strategy



Strategy



Find suitable "pairs"  $(\mathbb{U}_{sol}^{B}, \mathbb{U}_{sol}^{A})$  so that

- Type B is known
- Type S is true (our job to prove it)

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#### Families of semi-norms

The objects  $\mathbb{U}_{sol}^{B}$  and  $\mathbb{U}_{sol}^{A}$  are realized by countable sets of semi-norms

 $\left\|\cdot\right\|_{\mathbb{X}^m}, \quad m \in \mathbb{N}$ 

Typically, the semi-norm  $\mathbb{X}^m$  is a norm on derivatives  $\partial^{\alpha}$  of length  $|\alpha| = m$ .

Several spaces are associated in a natural way:

• 
$$\mathbb{X}^{k} = \{ \boldsymbol{u} : |\boldsymbol{u}|_{\mathbb{X}^{m}} < \infty, 0 \le m \le k \}$$
 and  $\|\boldsymbol{u}\|_{\mathbb{X}^{k}} = \sup_{m=0}^{\infty} |\boldsymbol{u}|_{\mathbb{X}^{m}}$   
•  $\mathbb{X}^{\infty} = \{ \boldsymbol{u} : |\boldsymbol{u}|_{\mathbb{X}^{m}} < \infty, \forall m \in \mathbb{N} \}$   
•  $\mathbb{X}^{\varpi} = \{ \boldsymbol{u} \in \mathbb{X}^{\infty} : \sup_{m \in \mathbb{N}} \left( \frac{1}{m!} |\boldsymbol{u}|_{\mathbb{X}^{m}} \right)^{1/m} < \infty \}$  — analytic class  
•  $\{ \boldsymbol{u} \in \mathbb{X}^{\infty} : \sup_{m \in \mathbb{N}} \left( \frac{1}{(m!)^{s}} |\boldsymbol{u}|_{\mathbb{X}^{m}} \right)^{1/m} < \infty \}$  — Gevrey class

Similar definitions for right hand sides q. Denote the semi-norms by  $|\cdot|_{\mathbb{W}^m}$ .

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## Types B and A associated with families of semi-norms

## Type B: Basic regularity

Exists  $m \in \mathbb{N}$  such that

$$\boldsymbol{u} \in \mathbb{V}$$
 and  $\boldsymbol{q} \in \mathbb{Y}^m \implies \boldsymbol{u} \in \mathbb{X}^m$ 

with estimates

$$\left\| \boldsymbol{u} \right\|_{\mathbb{X}^m} \leq C \big( \left\| \mathbb{P} \boldsymbol{u} \right\|_{\mathbb{Y}^m} + \left\| \boldsymbol{u} \right\|_{\mathbb{V}} \big)$$

#### Type A: Analytic regularity

$$\pmb{u} \in \mathbb{V}$$
 and  $\pmb{q} \in \mathbb{Y}^{\varpi} \implies \pmb{u} \in \mathbb{X}^{\varpi}$ 

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## Types S associated with families of semi-norms

#### **Type S standard**

Exists  $m \in \mathbb{N}$  such that for all k > m

$$\boldsymbol{u} \in \mathbb{X}^m$$
 and  $\boldsymbol{q} \in \mathbb{Y}^k \implies \boldsymbol{u} \in \mathbb{X}^k$ 

with estimates

$$\left\| \boldsymbol{u} \right\|_{\mathbb{X}^k} \leq C ig( \left\| \mathbb{P} \boldsymbol{u} \right\|_{\mathbb{Y}^k} + \left\| \boldsymbol{u} \right\|_{\mathbb{X}^m} ig)$$

#### Type S with Cauchy estimates

Exists  $m \in \mathbb{N}$  such that for all k > m

$$\boldsymbol{u} \in \mathbb{X}^m$$
 and  $\boldsymbol{q} \in \mathbb{Y}^k \implies \boldsymbol{u} \in \mathbb{X}^k$ 

with estimates (constant A independent from k)

(S-Cauchy) 
$$\frac{1}{k!} \left| \boldsymbol{u} \right|_{\mathbb{X}^k} \le A^{k+1} \left( \sum_{\ell=0}^k \frac{1}{\ell!} \left| \mathbb{P} \boldsymbol{u} \right|_{\mathbb{Y}^\ell} + \left\| \boldsymbol{u} \right\|_{\mathbb{X}^m} \right)$$

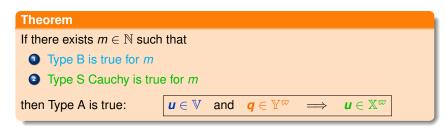
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## A true theorem, at last

Theorem			
If there exists $m \in \mathbb{N}$ such	ch that		
Type B is true for m			
Type S Cauchy is true	ue for <i>m</i>		
then Type A is true:	$u \in \mathbb{V}$ and $q \in \mathbb{Y}^{\varpi} \implies u \in \mathbb{X}^{\varpi}$		

## A true theorem, at last



Proof. (S-Cauchy) implies, after enlarging A:

$$\frac{1}{k!} \left\| \boldsymbol{u} \right\|_{\mathbb{X}^{k}} \leq \boldsymbol{A}^{k+1} \left( \max_{\ell=0}^{k} \frac{1}{\ell!} \left\| \mathbb{P} \boldsymbol{u} \right\|_{\mathbb{Y}^{\ell}} + \left\| \boldsymbol{u} \right\|_{\mathbb{X}^{m}} \right)$$

Take power 1/k

$$\begin{aligned} \left(\frac{1}{k!} \left\|\boldsymbol{u}\right\|_{\mathbb{X}^{k}}\right)^{1/k} &\leq A' \left(\max_{\ell=0}^{k} \frac{1}{\ell!} \left\|\mathbb{P}\boldsymbol{u}\right\|_{\mathbb{Y}^{\ell}} + \left\|\boldsymbol{u}\right\|_{\mathbb{X}^{m}}\right)^{1/k} \\ &\leq A' \left\{\max_{\ell=0}^{k} \left(\frac{1}{\ell!} \left\|\mathbb{P}\boldsymbol{u}\right\|_{\mathbb{Y}^{\ell}}\right)^{1/k} + \left\|\boldsymbol{u}\right\|_{\mathbb{X}^{m}}^{1/k}\right\} \end{aligned}$$

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## It suffices to realize the program Type B + Type S

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# It suffices to realize the program Type B + Type S to obtain Type A ... in any situation we want

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Abstract framework	Smooth domains	Corner domains	Polyhedral domains
First things	first		

- $\Omega$  smooth domain with analytic boundary.
- $\partial_{\mathbf{s}}\Omega$  for  $\mathbf{s} \in \mathscr{S}$ , connected components of  $\partial\Omega$ .
- $\mathbb{P}$  elliptic 2d order boundary value problem (system).
- $\mathbb{P} = (L, T_s, D_s)$ , operators with analytic coefficients:
  - L interior operator
  - $T_s$  boundary operator of order 1,  $s \in \mathscr{S}_N$
  - $D_{\boldsymbol{s}}$  boundary operator of order 0,  $\boldsymbol{s} \in \mathscr{S}_{D}$

<sup>&</sup>lt;sup>1</sup> for more than 50 years

Abstract framework	Smooth domains ●○○	Corner domains	Polyhedral domains
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  - $D_{s}$  boundary operator of order 0,  $s \in \mathscr{S}_{D}$

Theorems of Type C, B, and A known<sup>1</sup> in the framework of Sobolev spaces:

$$\left\|\boldsymbol{u}\right\|_{\mathbb{X}^{m}}=\sum_{|\alpha|=m}\left\|\partial_{\boldsymbol{x}}^{\alpha}\boldsymbol{u}\right\|_{L^{2}(\Omega)}$$

$$\|\boldsymbol{q}\|_{\mathbb{Y}^m} = \sum_{|\alpha|=m-2} \|\partial_{\boldsymbol{x}}^{\alpha}\boldsymbol{f}\|_{L^2(\Omega)} + \sum_{\substack{\boldsymbol{s}\in\mathscr{S}_N\\|\alpha|=m-2}} \|\partial_{\boldsymbol{x}}^{\alpha}\boldsymbol{g}_{\boldsymbol{s}}\|_{H^{\frac{1}{2}}(\partial_{\boldsymbol{s}}\Omega)} + \sum_{\substack{\boldsymbol{s}\in\mathscr{S}_D\\|\alpha|=m-1}} \|\partial_{\boldsymbol{x}}^{\alpha}\boldsymbol{h}_{\boldsymbol{s}}\|_{H^{\frac{1}{2}}(\partial_{\boldsymbol{s}}\Omega)}$$

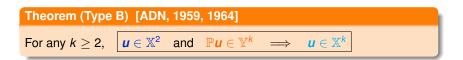
<sup>1</sup> for more than 50 years

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#### ADN & Morrey

#### Theorem (Type C) [ADN, 1959, 1964]

 $\mathbb{P}: \mathbb{X}^m \to \mathbb{Y}^m$  is Fredholm for any  $m \geq 2$ .





Anything to add?

Polyhedral domains

## Yes: Regularity Shift with Cauchy-type estimates

#### Theorem (Type S) [CoDaNi, 2010]

There exists A > 0 such that for any  $k \ge 2$  and  $\boldsymbol{u} \in \mathbb{X}^2$ 

(S-Cauchy) 
$$\frac{1}{k!} \left| \boldsymbol{u} \right|_{\mathbb{X}^k} \leq A^{k+1} \left( \sum_{\ell=0}^k \frac{1}{\ell!} \left\| \mathbb{P} \boldsymbol{u} \right\|_{\mathbb{Y}^\ell} + \left\| \boldsymbol{u} \right\|_{\mathbb{X}^2} \right)$$

Proof. Clean old proofs:

- Nested open sets on model problems
- Faà di Bruno formula for local maps

#### **Coercive variational form**

If  $\mathbb{P}$  issues from a variational form coercive on  $\mathbb{V} \subset \boldsymbol{H}^1(\Omega)$ , all thms adapt:

- C Existence in  $\mathbb V$
- **B** Basic regularity in  $\mathbb{X}^2$  if  $\mathbb{P} \boldsymbol{u} \in \mathbb{Y}^2$  (var. solutions are strong solutions)
- **A**, **S** Estimates with  $\|\boldsymbol{u}\|_{H^1(\Omega)}$  in the RHS.

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## **3D Examples**

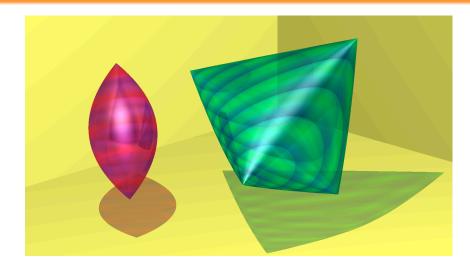


Figure: Axisymmetric domain & Cayley's tetrahedron (M. Costabel with POV-Ray)

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#### **Domains with conical points**

- Ω analytic corner domain (analytic cones and maps) with corner set *C* (in 2D, piecewise analytic in 2D polygonal domains).
- $\mathbb{P} = (L, T_s, D_s)$  elliptic 2d order with analytic coefficients.
- To simplify: coercive problems with zero boundary data ( $q \equiv f$ ).

#### **Domains with conical points**

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- To simplify: coercive problems with zero boundary data ( $q \equiv f$ ).

Theorems of Type C based on Lax-Milgram, no regularity required.

Theorems of Type B and "S standard" known, starting with [Kondratev '67]. Use of weighted Sobolev spaces:

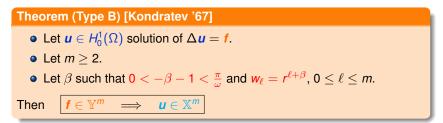
$$\left|\boldsymbol{u}\right|_{\mathbb{X}^{m}}=\sum_{|\alpha|=m}\left\|\boldsymbol{w}_{m}\,\partial_{\boldsymbol{x}}^{\alpha}\boldsymbol{u}\right\|_{L^{2}(\Omega)}\quad\text{and}\quad\left|\boldsymbol{f}\right|_{\mathbb{Y}^{m}}=\sum_{|\alpha|=m-2}\left\|\boldsymbol{w}_{m}\,\partial_{\boldsymbol{x}}^{\alpha}\boldsymbol{f}\right\|_{L^{2}(\Omega)}$$

where  $w_0(\mathbf{x}), w_1(\mathbf{x}), \dots, w_m(\mathbf{x}), \dots$  family of weights of general type

$$w_m(\mathbf{x}) = r(\mathbf{x})^{m+\beta}, \quad r(\mathbf{x}) = dist(\mathbf{x}, \mathscr{C}), \quad \beta \in \mathbb{R}.$$

## An old friend: The Dirichlet Laplacian on a polygon

Let  $\omega = \omega_c$  be the largest opening angle of the polygon  $\Omega$  (corner c).



- Why 0 < −β − 1, i.e. β < −1? ⇒ w<sub>1</sub> unbounded. Because this condition implies X<sup>2</sup> compactly embedded in H<sup>1</sup>(Ω).
- Why -β 1 < π/ω? Because under this condition the strongest singularity</p>

$$m{x}\longmapsto r_{m{c}}^{\pi/\omega}\sinrac{\pi heta_{m{c}}}{\omega_{m{c}}}$$

belongs to  $\mathbb{X}^m$  for all *m*.

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0	0				0		0				

## What about the Neumann Laplacian on a polygon?

- The previous functional setting is unpleasant for the Neumann  $\Delta$ .
- Independent pointwise values arise at each corner.
- The constant function 1 ∉ X<sup>2</sup> if 0 < −β − 1 because w<sub>0</sub> = r<sup>β</sup>. But no problem for derivatives...

Remedy: modify the first weights. Take

$$W_{\ell} = r^{\max\{0, \ell+\beta\}} \simeq \min\{1, r^{\ell+\beta}\}, \quad \ell \in \mathbb{N}$$

*Example*: If  $\beta = -\frac{3}{2}$ ,  $w_0 = w_1 = 1$ , and  $w_\ell = r^{\ell+\beta}$  as before if  $\ell \ge 2$ .

#### Theorem (Type B) [Mazya-Plamenevskii, 1984]

- Let  $\boldsymbol{u} \in H^1(\Omega)$  solution of  $\Delta \boldsymbol{u} = \boldsymbol{f}$  with  $\partial_n \boldsymbol{u} = 0$ .
- Let *m* ≥ 2.
- Let  $\beta$  such that  $0 < -\beta 1 < \frac{\pi}{\omega}$  and  $w_{\ell} = r^{\max\{0, \ell+\beta\}}$ ,  $0 \le \ell \le m$ .

Then  $\boldsymbol{f} \in \mathbb{Y}^m \implies \boldsymbol{u} \in \mathbb{X}^m$ 

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## General case, Type B in corner domains

- $\Omega \subset \mathbb{R}^d$ . Dimension  $d \geq 2$ .
- Coercive variational formulation in  $\mathbb{V} \subset \boldsymbol{H}^1(\Omega)$
- Smooth coefficients

#### Theorem (Type B)

Exists an optimal number  $b^*(\Omega, \mathbb{P}) > 1 - \frac{d}{2}$  such that the following holds.

- Let *m* ≥ 2.
- Let  $\beta < -1$  such that  $-\beta \frac{d}{2} < b^*(\Omega, \mathbb{P})$
- Choose the weights  $w_{\ell} = r^{\max\{0, \ell+\beta\}}$  (non-homogeneous norms).

Then  $\boldsymbol{u} \in \mathbb{V}$  and  $\mathbb{P}\boldsymbol{u} \in \mathbb{Y}^m \implies \boldsymbol{u} \in \mathbb{X}^m$ 

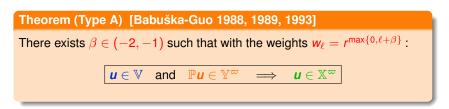
#### Remark.

Weights  $w_{\ell} = r^{\ell+\beta}$  (homogeneous norms) suitable if  $\boldsymbol{u} \in \mathbb{V} \Rightarrow \frac{\boldsymbol{u}}{r} \in L^2(\Omega)$ . There holds a similar statement involving another positive number  $\boldsymbol{b}(\Omega, \mathbb{P})$  determined by Mellin corner spectra  $\sigma(\mathfrak{A}_c), \boldsymbol{c} \in \mathscr{C}$ .

Polyhedral domains

## Type A for $\Delta$ , Lamé in polygonal domains

Weighted analytic regularity has been invented by Babuška and Guo, and proved for model operators in polygonal domains.



#### Exponential convergence [Babuška-Guo 1988, 1989, 1993]

This weighted analytic regularity allows to prove the exponential convergence of the h-p method of finite elements.

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## This is not the end of the story for corner domains

Theorem (Type S standard) [Kondratev 1967]

With homogeneous weights  $w_{\ell} = r^{\ell+\beta}$ :

For all  $k \ge 2$  and all  $\beta \in \mathbb{R}$ 

$$\boldsymbol{u} \in \mathbb{X}^2$$
 and  $\boldsymbol{q} \in \mathbb{Y}^k \implies \boldsymbol{u} \in \mathbb{X}^k$ 

with estimates (C depends on  $\beta$  and k)

$$\left\| oldsymbol{u} 
ight\|_{\mathbb{X}^k} \leq oldsymbol{C} ig( \left\| \mathbb{P} oldsymbol{u} 
ight\|_{\mathbb{Y}^k} + \left\| oldsymbol{u} 
ight\|_{\mathbb{X}^2} ig)$$

In other words :

For any  $\beta$ , if  $r^{|\alpha|+\beta} \boldsymbol{u} \in L^2(\Omega)$  for  $|\alpha| \leq 1$ , then  $r^{|\alpha|+\beta} \boldsymbol{u} \in L^2(\Omega)$  for  $|\alpha| \leq k$  if the rhs has the corresponding regularity.

This is an unconditional elliptic regularity shift for corner domains.

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## **Regularity Shift with Cauchy-type estimates**

#### Theorem (Type S) [CoDaNi, 2010]

 With homogeneous weights w<sub>ℓ</sub> = r<sup>ℓ+β</sup>: For all β ∈ ℝ exists A > 0 such that for any k ≥ 2 and u ∈ X<sup>2</sup>

$$\frac{1}{k!} \left| \boldsymbol{u} \right|_{\mathbb{X}^k} \le A^{k+1} \left( \sum_{\ell=0}^k \frac{1}{\ell!} \left\| \mathbb{P} \boldsymbol{u} \right\|_{\mathbb{Y}^\ell} + \left\| \boldsymbol{u} \right\|_{\mathbb{X}^1} \right)$$

With non-homogeneous weights  $w_{\ell} = r^{\max\{0, \ell+\beta\}}$ : For all  $\beta \in \mathbb{R}$  and  $m \ge \max\{-\beta, 2\}$  exists A > 0 such that for any  $k \ge m$  and  $u \in \mathbb{X}^m$ 

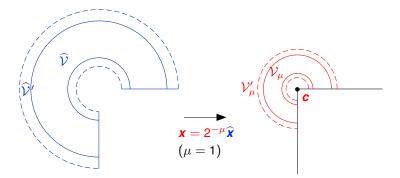
$$\frac{1}{k!} \left| \boldsymbol{u} \right|_{\mathbb{X}^{k}} \leq A^{k+1} \left( \sum_{\ell=m+1}^{k} \frac{1}{\ell!} \left| \mathbb{P} \boldsymbol{u} \right|_{\mathbb{Y}^{\ell}} + \left| \boldsymbol{u} \right|_{\mathbb{X}^{m}} \right)$$

Proof

- Unweighted estimates (S-Cauchy) in fixed annulus far from corner c
- Scale estimates to closer annuli. Weight appears.
- Sum over a dyadic partition of a neighborhood of c

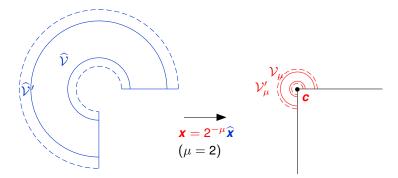
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Scale on 
$$\mathcal{V}_{\mu} = 2^{-\mu} \mathcal{V}$$
 and  $\mathcal{V}'_{\mu} = 2^{-\mu} \mathcal{V}'$ , for  $\mu = 1$ 



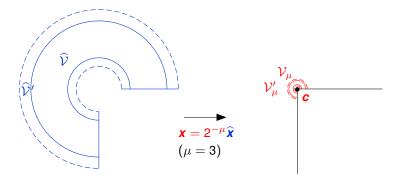
Abstract framework	Smooth domains	Corner domains	Polyhedral domains

Scale on 
$$\mathcal{V}_{\mu} = 2^{-\mu} \mathcal{V}$$
 and  $\mathcal{V}'_{\mu} = 2^{-\mu} \mathcal{V}'$ , for  $\mu = 2$ 



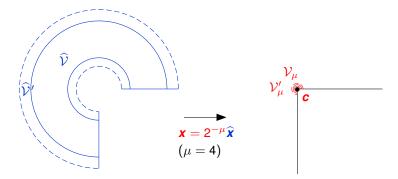
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Scale on 
$$\mathcal{V}_{\mu} = 2^{-\mu} \mathcal{V}$$
 and  $\mathcal{V}'_{\mu} = 2^{-\mu} \mathcal{V}'$ , for  $\mu = 3$ 



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Scale on 
$$\mathcal{V}_{\mu} = 2^{-\mu} \mathcal{V}$$
 and  $\mathcal{V}'_{\mu} = 2^{-\mu} \mathcal{V}'$ , for  $\mu = 4, \dots$ 



## As a corollary of B & S: Type A in corner domains

#### General case sine dolore

- $\Omega \subset \mathbb{R}^d$ . Dimension  $d \geq 2$ .
- Coercive variational formulation in  $\mathbb{V} \subset \boldsymbol{H}^1(\Omega)$
- Analytic coefficients

#### Theorem (Type A) [CoDaNi, 2010]

With the same optimal number  $b^*(\Omega, \mathbb{P})$  as in Theorem B, there holds.

• Let  $\beta < -1$  such that  $-\beta - \frac{d}{2} < b^*(\Omega, \mathbb{P})$ 

• Choose the weights 
$$w_{\ell} = r^{\max\{0, \ell+\beta\}}, \ell \in \mathbb{N}$$
.

Then  $\boldsymbol{u} \in \mathbb{V}$  and  $\mathbb{P}\boldsymbol{u} \in \mathbb{Y}^{\varpi} \implies \boldsymbol{u} \in \mathbb{X}^{\varpi}$ 

#### Remark.

Homogeneous weights  $w_{\ell} = r^{\ell+\beta}$  can be used instead if

$$\boldsymbol{u} \in \mathbb{V} \Longrightarrow \frac{\boldsymbol{u}}{r} \in L^{2}(\Omega).$$
  
If  $\beta < -1 \& -\beta - \frac{d}{2} < \boldsymbol{b}(\Omega, \mathbb{P}), \quad \overline{\boldsymbol{u} \in \mathbb{V} \text{ and } \mathbb{P}\boldsymbol{u} \in \mathbb{Y}^{\varpi} \implies \boldsymbol{u} \in \mathbb{X}^{\varpi}}$ 

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#### Corners, edges, distance functions and weights

- $\Omega$  polyhedral domain in  $\mathbb{R}^3$ . Distance to singular points:  $\mathbf{x} \mapsto r(\mathbf{x})$
- Corners c, set of corners  $\mathscr{C}$ , distance functions:  $r_c$  to c,  $r_{\mathscr{C}}$  to  $\mathscr{C}$ ,
- Edges *e*, set of edges *&*, distance functions: *r<sub>e</sub>* to *e*.

Two ways of generating weights

**()** A simple way: choose  $\beta \in \mathbb{R}$  and use powers of *r* 

$$w_{\ell} = r^{\ell+\beta}$$
 or  $w_{\ell} = r^{\max\{0,\ell+\beta\}}$ 

3 A finer tool: choose a multi- $\beta$ , i.e.  $\beta = (\beta_c, \beta_e)$ 

$$W_{\ell} = \prod_{\boldsymbol{c} \in \mathscr{C}} r_{\boldsymbol{c}}^{\ell+\beta_{\boldsymbol{c}}} \times \prod_{\boldsymbol{e} \in \mathscr{E}} \left(\frac{r_{\boldsymbol{e}}}{r_{\mathscr{C}}}\right)^{\ell+\beta_{\boldsymbol{e}}} \text{ or } w_{\ell} = \prod_{\boldsymbol{c} \in \mathscr{C}} r_{\boldsymbol{c}}^{\max\{0,\ell+\beta_{\boldsymbol{c}}\}} \times \prod_{\boldsymbol{e} \in \mathscr{E}} \left(\frac{r_{\boldsymbol{e}}}{r_{\mathscr{C}}}\right)^{\max\{0,\ell+\beta_{\boldsymbol{e}}\}}$$

Note: If  $\beta_{\boldsymbol{c}} \equiv \beta$ , then  $\prod_{\boldsymbol{c} \in \mathscr{C}} r_{\boldsymbol{c}}^{\ell+\beta_{\boldsymbol{c}}} \simeq r_{\mathscr{C}}^{\ell+\beta}$ If  $\beta_{\boldsymbol{c}} \equiv \beta_{\boldsymbol{e}} \equiv \beta$ , then  $\prod_{\boldsymbol{c} \in \mathscr{C}} r_{\boldsymbol{c}}^{\ell+\beta_{\boldsymbol{c}}} \times \prod_{\boldsymbol{e} \in \mathscr{E}} \left(\frac{r_{\boldsymbol{e}}}{r_{\mathscr{C}}}\right)^{\ell+\beta_{\boldsymbol{e}}} \simeq r^{\ell+\beta}$ .

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## Type B in polyhedral domains

- Coercive variational formulation in  $\mathbb{V} \subset \boldsymbol{H}^1(\Omega)$
- Smooth coefficients

#### Theorem (Type B) [Mazya-Rossmann 2003] [CoDaNi, 2012]

For optimal numbers  $b_c^*(\Omega, \mathbb{P}) > -\frac{1}{2}$  and  $b_e(\Omega, \mathbb{P}) > 0$  depending on Mellin corner and edge spectra  $\sigma(\mathfrak{A}_c)$  and  $\sigma(\mathfrak{A}_e)$ , the following holds.

- Let *m* ≥ 2.
- Let  $\underline{\beta} < -1$  such that  $-\beta_{\mathbf{c}} \frac{3}{2} < b_{\mathbf{c}}^*(\Omega, \mathbb{P})$  and  $-\beta_{\mathbf{e}} 1 < b_{\mathbf{e}}(\Omega, \mathbb{P})$
- Choose the weights  $w_{\ell} = \prod_{\boldsymbol{c} \in \mathscr{C}} r_{\boldsymbol{c}}^{\max\{0,\ell+\beta_{\boldsymbol{c}}\}} \times \prod_{\boldsymbol{e} \in \mathscr{E}} \left(\frac{r_{\boldsymbol{e}}}{r_{\mathscr{C}}}\right)^{\max\{0,\ell+\beta_{\boldsymbol{e}}\}}.$ Then  $\boldsymbol{u} \in \mathbb{V}$  and  $\mathbb{P}\boldsymbol{u} \in \mathbb{Y}^m \implies \boldsymbol{u} \in \mathbb{X}^m$

Example. For Dirichlet Laplacian,

$$\boldsymbol{b_e}(\Omega,\mathbb{P}) = \frac{\pi}{\omega_{\boldsymbol{e}}}, \quad \boldsymbol{b_c}(\Omega,\mathbb{P}) = -\frac{1}{2} + \sqrt{\mu_{\boldsymbol{c},1}^{\text{Dir}} + \frac{1}{4}}, \quad \boldsymbol{b_c^*}(\Omega,\mathbb{P}) = \min\{2, \boldsymbol{b_c}\}$$

Polyhedral domains

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Theorems of type S and, hence, of type A, can be proved without difficulty. But in connection with h-p version of finite elements, this would not help.

Polyhedral domains

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Weights  $w_{\ell}$  providing isotropic semi-norms  $\sum_{|\alpha|=\ell} \|w_{\ell} \partial_{\mathbf{x}}^{\alpha} \mathbf{u}\|_{L^{2}(\Omega)}$  will be replaced by weights  $w_{\mathbf{e},\alpha}$  defined in neighborhoods  $\mathcal{V}_{\mathbf{e}}$  of edges:

$$|\boldsymbol{u}|_{\mathbb{X}^{\ell}} = \sum_{\boldsymbol{e} \in \mathscr{E}} \sum_{|\alpha| = \ell} \|\boldsymbol{w}_{\boldsymbol{e},\alpha} \partial_{\boldsymbol{x}}^{\alpha} \boldsymbol{u}\|_{L^{2}(\mathcal{V}_{\boldsymbol{e}})}$$

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Choose tubular coordinates  $\boldsymbol{x}_{\boldsymbol{e}} = (\boldsymbol{x}_{\boldsymbol{e}}^{\perp}, \boldsymbol{x}_{\boldsymbol{e}}^{\parallel})$  and corresponding multi-indices  $\alpha_{\boldsymbol{e}} = (\alpha_{\boldsymbol{e}}^{\perp}, \alpha_{\boldsymbol{e}}^{\parallel}),$  — perpendicular and parallel to  $\boldsymbol{e}$ . Typically

$$\mathbf{W}_{\mathbf{e},\alpha} = \mathbf{r}_{\mathbf{e}}^{\beta_{\mathbf{e}} + |\alpha_{\mathbf{e}}^{\perp}|}$$

independent of derivatives  $\partial_{\mathbf{x}}^{\alpha_{\mathbf{e}}^{\parallel}}$  along  $\mathbf{e}$ .

Abstract framework

Smooth domains

Corner domains

Polyhedral domains

## Anisotropic weights (edges & corners)

To simplify, assume that all edges are parallel to coordinate axes. The non-homogeneous version of anisotropic weights is

$$W_{\alpha} = \prod_{\boldsymbol{c} \in \mathscr{C}} r_{\boldsymbol{c}}^{\max\{0,\beta_{\boldsymbol{c}}+|\alpha|\}} \times \prod_{\boldsymbol{e} \in \mathscr{E}} \left(\frac{r_{\boldsymbol{e}}}{r_{\mathscr{C}}}\right)^{\max\{0,\beta_{\boldsymbol{e}}+|\alpha_{\boldsymbol{e}}^{\perp}|\}}$$

Theorem (Type S) [CoDaNi, 2010]

• Let  $\underline{\beta} = (\beta_c, \beta_e)$  such that

 $\forall \boldsymbol{e} \in \mathscr{E}, \quad 0 < -\beta_{\boldsymbol{e}} - 1 \text{ and } -\beta_{\boldsymbol{e}} - 1 \notin \operatorname{Re} \sigma(\mathfrak{A}_{\boldsymbol{e}})$ 

• Let  $m \ge 1$  and  $\ge \max\{-\beta_{e}, -\beta_{c}\}$ 

Then for any  $k \ge m$  and  $\boldsymbol{u} \in \mathbb{X}^m$ 

$$\frac{1}{k!} \left| \boldsymbol{u} \right|_{\mathbb{X}^{k}} \leq A^{k+1} \Big( \sum_{\ell=0}^{k} \frac{1}{\ell!} \left| \mathbb{P} \boldsymbol{u} \right|_{\mathbb{Y}^{\ell}} + \left| \boldsymbol{u} \right|_{\mathbb{X}^{m}} \Big)$$

*Example.* For Dirichlet Laplacian,  $\sigma(\mathfrak{A}_{e}) = \{\frac{k\pi}{\omega_{e}} : k \in \mathbb{Z}^{*}\}.$ 

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## Corollary of B & S: Type AA in polyhedral domains

- $\Omega \subset \mathbb{R}^3$  polyhedron
- Coercive variational formulation in  $\mathbb{V} \subset \boldsymbol{H}^1(\Omega)$
- Homogeneous constant coefficients (Analytic coefficients possible)

#### Theorem (Type AA) [CoDaNi, 2010]

With the same numbers  $b_{c}^{*}(\Omega, \mathbb{P})$  and  $b_{e}(\Omega, \mathbb{P})$  as in Theorem B:

- Let  $\underline{\beta} < -1$  such that  $-\beta_c \frac{3}{2} < b_c^*(\Omega, \mathbb{P})$  and  $-\beta_e 1 < b_e(\Omega, \mathbb{P})$
- Choose the weights  $w_{\ell} = \prod_{c \in \mathscr{C}} r_c^{\max\{0, \ell+\beta_c\}} \times \prod_{e \in \mathscr{E}} \left(\frac{r_e}{r_{\mathscr{C}}}\right)^{\max\{0, \ell+\beta_e\}}$

Then  $\boldsymbol{u} \in \mathbb{V}$  and  $\mathbb{P}\boldsymbol{u} \in \mathbb{Y}^{\varpi} \implies \boldsymbol{u} \in \mathbb{X}^{\varpi}$ 

#### Remark.

Homogeneous weights 
$$w_{\ell} = \prod_{c \in \mathscr{C}} r_c^{\ell+\beta_c} \times \prod_{e \in \mathscr{E}} \left(\frac{r_e}{r_{\mathscr{C}}}\right)^{\ell+\beta_e}$$
 can be used if  
 $u \in \mathbb{V} \Longrightarrow \frac{u}{r} \in L^2(\Omega)$ 

#### Numbers *b* for $\triangle$ on examples

Domain Ω	$b_{e}(\Omega)$	$b_{\boldsymbol{c}}(\Omega)$	$b^*_{m{c}}(\Omega)$
Cube, Dirichlet	2	3	2
Cube, Neumann	2	0	2
Thick L, Dirichlet	0.66666	1.66666	1.66666
Thick L, Neumann	0.66666	0	1.66666
Fichera corner, Dirichlet	0.66666	0.45418	0.45418
Fichera corner, Neumann	0.66666	0	0.84001

$$\begin{split} \text{Thick } L &: \left\{(-1,1)^2 \setminus (0,1)^2\right\} \times (-1,1) \\ \text{Fichera corner} &: (-1,1)^3 \setminus (0,1)^3 \end{split}$$

Abstract framework	Smooth domains	Corner domains	Polyhedral domains
Sources			

M. COSTABEL, M. DAUGE, S. NICAISE Analytic Regularity for Linear Elliptic Systems in Polygons and Polyhedra Math. Models Methods Appl. Sci. 08(22) (2012), 59 p. DOI: 10.1142/S0218202512500157

M. Costabel, M. Dauge, S. Nicaise

Book project:

Corner Singularities and Analytic Regularity for Linear Elliptic Systems Part I: Smooth domains. *HAL: hal-00453934* (2010), 211 pages

#### **3D** Lexicon

Туре	Homogeneous norms	Non-homogeneous norms
Isotropic	$\mathcal{K}^k_eta(\Omega)$	$J^k_eta(\Omega)$
Anisotropic	$M^k_eta(\Omega)$	${\it N}^k_eta(\Omega)$
Anisotropic Analytic	${\it A}^k_eta(\Omega)$	$\textit{B}^{\textit{k}}_{\beta}(\Omega)$





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Augmented Anisotropic Analyticity



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Thank you for your attention