# Strongly elliptic boundary integral equations for electromagnetic transmission problems 

Martin Costabel<br>Fachbereich Mathematik, Technische Hochschule Darmstadt, Schlossgartenstr. 7, 6100 Darmstadt, Germany<br>and<br>Ernst P. Stephan*<br>School of Mathematics, Georgia Institute of Technology, Atlanta, Georgia 330332, U.S.A.<br>(MS received 14 November 1986. Revised MS received 19 November 1987)

## Synopsis

We study a boundary integral equation method for transmission problems for strongly elliptic differential operators, which yields a strongly elliptic system of pseudodifferential operators and which therefore can be used for numerical computations with Galerkin's procedure. The method is shown to work for the vector Helmholtz equation in $\mathbb{R}^{3}$ with electromagnetic transmission conditions. We propose a slightly modified system of boundary values in order for the corresponding bilinear form to be coercive over $H^{1}$. We analyse the boundary integral equations using the calculus of pseudodifferential operators. Here the concept of the principal symbol is used to derive existence and regularity results for the solution.

## 1. Introduction

The usefulness of strongly elliptic pseudodifferential operators for numerical methods is now well established ( $[9,13,23,29,30,11]$ ). For boundary value problems, there are many papers dealing with the analytical and computational aspects of various examples demonstrating this fact. The so-called "direct method" leads easily from a strongly elliptic boundary value problem to a strongly elliptic system of pseudodifferential equations on the boundary. This method is now well understood and also has, by its simplicity, a wide range of applications to mixed boundary value problems and to problems with irregular boundaries [3]. This is one advantage of such first kind integral equations compared to the traditionally-preferred Fredholm integral equations of the second kind. For the latter equations, there is no generally applicable method of derivation, and they lose their Fredholm properties as soon as the coefficients or the boundaries are not smooth. Other advantages of the direct method are that the solutions have direct physical meaning, and the appropriate norm is the energy norm. Therefore the corresponding boundary element methods share several nice properties of the usual finite element methods [31].

[^0]For acoustic transmission problems, the authors showed in [4] that for the case of the Helmholtz equation the direct method also leads to strongly elliptic boundary integral equations. This was done using the symbols of the operators defined by local Fourier transformation in the case of smooth boundaries in any dimension, respectively by local Mellin transformation in the case of a twodimensional domain with corners (see also [26]).
In the present paper, we show how to derive strongly elliptic boundary integral equations for a general class of strongly elliptic transmission problems, by the direct method. We then apply this to electromagnetic transmission problems. To do this we must have a bilinear form, connected with the boundary data through Green's first theorem, that is, coercive over all of $H^{1}$, whereas the usual energy form is not [8]. To achieve this, we use a modification of the boundary data which gives rise to a transmission problem equivalent to the original one. Then we compute the kernels of the integral operators and their principal symbols which show clearly how the proposed modification transforms the system of operators into a strongly elliptic one. This kind of transformation of the boundary integral operators was first used by MacCamy and Stephan in [18] for the perfect conductor problem, i.e. the exterior boundary value problem for Maxwell's equations with given electric data.

Under the assumption of uniqueness we derive existence of the solution of our integral equation on the transmission manifold. Since the general electromagnetic transmission problem is equivalent to our boundary integral equation, we have an analytic solution procedure via the integral equation; in connection with Galerkin's method we even have a numerical solution procedure by boundary elements. Our system of operators for the transmission problem contains the systems which can be used for electric and magnetic boundary value problems and for screen scattering problems with electric and with magnetic boundary data. For all these cases we therefore have strong ellipticity of the corresponding boundary integral equations. For screen problems, these and corresponding symbols are the starting point of an analysis of singularities at the screen edge, see $[\mathbf{2 5}, 24]$.

## 2. The direct method for transmission problems

The "direct method" for strongly elliptic boundary value problems was studied in [5]. Here we present a related analysis of transmission problems. We see that the case of the scalar Helmholtz equation studied in [4] is representative of a general class of transmission problems. A similar analysis is possible for very general combinations of boundary and transmission conditions [21].

Let $\Omega_{1}$ be a bounded domain in $\mathbb{R}^{n}$ with boundary $\Gamma \in C^{\infty}$ and $\Omega_{2}:=\mathbb{R}^{n} \backslash \overline{\Omega_{1}}$. We consider the following transmission problem:

$$
\begin{align*}
& P_{1} u_{1}=0 \text { in } \Omega_{1},  \tag{2.1}\\
& P_{2} u_{2}=0 \text { in } \Omega_{2}, \tag{2.2}
\end{align*}
$$

$u_{2}$ satisfies some "radiation condition", see (2.17),

$$
\begin{equation*}
R_{2} \gamma_{2} u_{2}-R_{1} \gamma_{1} u_{1}=u_{0} \quad \text { on } \Gamma . \tag{2.3}
\end{equation*}
$$

Here, for $j=1,2, P_{j}$ are elliptic differential operators of order $2 m$ with $C^{\infty}$
coefficients, for simplicity both defined throughout $\mathbb{R}^{n} ; \gamma_{j} u_{j}$ are the Cauchy data of $u_{j}$ on $\Gamma$ from $\Omega_{j}$ :

$$
\begin{equation*}
\gamma_{j} u_{j}=\left.\left(u_{j}, \partial_{n} u_{j}, \ldots, \partial_{n}^{2 m-1} u_{j}\right)\right|_{\Gamma} \tag{2.4}
\end{equation*}
$$

where $\partial_{n}$ means the normal derivative with respect to the normal pointing from $\Omega_{1}$ to $\Omega_{2} ; R_{j} \gamma_{j}$ are systems of $2 m$ differential operators with $C^{\infty}$ coefficients:

$$
\begin{equation*}
\left(R_{j} \gamma_{j} u_{j}\right)_{i}=\left.\sum_{k=0}^{2 m-1} R_{j}^{i k} \partial_{n}^{k} u_{j}\right|_{\Gamma}, \tag{2.5}
\end{equation*}
$$

where $R_{j}^{i k}$ are tangential differential operators of order

$$
\begin{equation*}
\text { ord } R_{j}^{i k}=i-k \tag{2.6}
\end{equation*}
$$

We assume that $R_{j}$ are Dirichlet systems of order $2 m$ (see [17]), which implies, as well as (2.6), that the lower triangular matrix

$$
R_{j}=\left(R_{j}^{i k}\right)_{i, k=0, \ldots, 2 m-1}
$$

is invertible, the inverse also being a tangential differential operator.
In order to transform the transmission problem to a problem on the boundary, we must assume that we know fundamental solutions $G_{j}$ for the differential operators $P_{j}$, i.e. two-sided inverses on the space $\mathscr{E}^{\prime}$ of distributions with compact support on $\mathbb{R}^{n}$. This hypothesis immediately makes available a 'second Green formula" and a "representation formula" as follows: Let

$$
\begin{equation*}
P_{i}=\sum_{l=0}^{2 m} P_{j l} \partial_{n}^{l} \tag{2.7}
\end{equation*}
$$

be the representation of $P_{j}$ near $\Gamma$ with differential operators $P_{j l}$ of order $2 m-l$ which are tangential on $\Gamma$. Let $u_{j} \in C_{0}^{\infty}\left(\overline{\Omega_{j}}\right), f_{j}:=\left.P_{j} u_{j}\right|_{\Omega_{j}}$, and $u_{j}^{0}$ be the extension of $u_{j}$ by zero outside $\Omega_{j}$. If we apply $P_{j}$ in the distributional sense to $u_{j}^{0}$, the result differs from $f_{j}^{0}$ by a distribution supported by $\Gamma[6$ (23.48.13.4)], [1]:

$$
\begin{equation*}
P_{j} u_{j}^{0}=f_{j}^{0}+(-1)^{j} \sum_{k=0}^{2 m-1} \sum_{l=0}^{2 m-1-k} P_{j, k+l+1} \partial_{n}^{l} u_{j} \otimes \partial_{n}^{k} \delta_{\Gamma} . \tag{2.8}
\end{equation*}
$$

Multipole layers $v \otimes \partial_{n}^{k} \delta_{\Gamma}$ appear here, defined by

$$
\begin{equation*}
\left\langle v \otimes \partial_{n}^{k} \delta_{\Gamma}, \phi\right\rangle:=\int_{\Gamma} v \partial_{n}^{\prime k} \phi d o \quad \text { for } \phi \in C_{0}^{\infty}\left(\mathbb{R}^{n}\right), \tag{2.9}
\end{equation*}
$$

where $d o$ is the $(n-1)$-dimensional surface measure on $\Gamma$, and $\partial_{n}^{\prime}$ is the transpose of the differential operator $\partial_{n}$. Thus (2.8) is a distributional formulation of Green's second formula. By applying the relation $G_{j} P_{j} u_{j}^{0}=u_{j}^{0}$ to (2.8), we obtain the representation formula:

$$
\begin{equation*}
u_{j}^{0}=G_{j} f_{j}^{0}+(-1)^{j} \sum_{k=0}^{2 m-1} \sum_{l=0}^{2 m-1-k} K_{j k}\left(P_{j, k+l+1} \partial_{n}^{l} u_{j}\right) \tag{2.10}
\end{equation*}
$$

Here the multipole potential operators $K_{j k}$ are defined by

$$
\begin{equation*}
K_{j k} \phi=G_{j}\left(\phi \otimes \partial_{n}^{k} \delta_{\Gamma}\right)=\int_{\Gamma} \partial_{n(y)}^{\prime k} G_{j}(\cdot, y) \phi(y) d o(y) \quad \text { for } \quad \phi \in C^{\infty}(\Gamma) \tag{2.11}
\end{equation*}
$$

where $G_{j}(x, y)$ is the kernel of $G_{j}$.

If we introduce the matrices

$$
\begin{align*}
& \mathscr{P}_{j}:=\left(P_{j, k+l+1}\right)_{k, l=0}^{2 m-1} \quad \text { with } \quad P_{j k}:=0 \quad \text { for } \quad k>2 m,  \tag{2.12}\\
& \mathscr{K}_{j}:=\left(\left.\partial_{n}^{i} K_{j k}\right|_{\partial \Omega_{j}}{ }_{i, k=0}^{2 m-1},\right.
\end{align*}
$$

then we find from (2.10) by taking Cauchy data, that

$$
\begin{equation*}
\gamma_{j} u_{j}=\gamma_{j} G_{j} f_{j}^{0}+(-1)^{i} \mathscr{X}_{j} \mathscr{P}_{j} \gamma_{j} u_{j} . \tag{2.13}
\end{equation*}
$$

The operator

$$
\begin{equation*}
C_{j}:=(-1)^{j} \mathscr{K}_{j} \mathscr{P}_{j} \tag{2.14}
\end{equation*}
$$

is the so-called "Calderon projector". Its properties are known [22]:
Lemma 2.1. The operator $C_{j}$ is a pseudodifferential operator $C_{j}=\left(C_{j}^{i k}\right)_{i, k=0}^{2 m-1}$ with orders ord $C_{j}^{i k}=i-k$. Thus it is a continuous operator from

$$
\begin{equation*}
\mathscr{H}^{s}:=\prod_{k=0}^{2 m-1} H^{m-k-1 / 2+s}(\Gamma) \tag{2.15}
\end{equation*}
$$

into itself for any $s \in \mathbb{R}$. If $P_{1}=P_{2}$ then

$$
\begin{equation*}
C_{1}+C_{2}=1 \tag{2.16}
\end{equation*}
$$

Here $H^{s}(\Gamma)$ is the usual Sobolev space on $\Gamma$.
From (2.13) it follows immediately that $C_{j}$ are projection operators: $C_{j}^{2}=C_{j}$. For $\Omega_{1}$ we can take closures in Sobolev spaces in (2.10), whereas for the exterior domain $\Omega_{2}$ we have (2.10) at first only for functions $u_{2}$ with compact support. But we can use (2.10) for

$$
\Omega_{2}^{R}:=\Omega_{2} \cap\left\{x \in \mathbb{R}^{n}| | x \mid \leqq R\right\} \quad(R \text { large enough }) .
$$

Then (2.10) holds for $\Omega_{j}$ if and only if the terms coming from $\Omega_{2} \backslash \Omega_{2}^{R}$ and from $\partial \Omega_{2}^{R} \backslash \Gamma=\left\{x \in \mathbb{R}^{n}| | x \mid=R\right\}$ tend to zero as $R \rightarrow \infty$. For $f_{2}=0$ this means

$$
\begin{equation*}
\lim _{R \rightarrow \infty} \sum_{k+l+1 \leqq 2 m} \int_{|y|=R} \partial_{n(y)}^{\prime k} G_{2}(\cdot, y)\left(P_{2, k+l+1} \partial_{n}^{l} u_{2}\right)(y) d o(y) \rightarrow 0 \text { for all } x \in \Omega_{2} \tag{2.17}
\end{equation*}
$$

Analogously to the classical situation of the Helmholtz and Maxwell equations, we call this a "radiation condition".

We can now define the solution spaces for (2.1), (2.2):
DEfinition 2.2.

$$
\begin{aligned}
& L_{1}^{s}:=\left\{u_{1} \in H^{m+s}\left(\Omega_{1}\right) \mid P_{1} u_{1}=0 \text { in } \Omega_{1}\right\} \\
& L_{2}^{s}:=\left\{u_{2} \in H^{m+s}\left(\Omega_{2}\right) \mid P_{2} u_{2}=0 \text { in } \Omega_{2} \text { and } u_{2} \text { satisfies (2.17) }\right\} .
\end{aligned}
$$

Note that the ellipticity of $P_{2}$ implies $u_{2} \in C^{\infty}\left(\Omega_{2}\right)$, so that the integral in (2.17) makes sense. If we use the well-known mapping properties of the potential
operators $K_{j k}([1],[6])$, we obtain
Lemma 2.3. Let $s \in \mathbb{R}$. For $v \in \mathscr{H}^{s}$ the following are equivalent:
(i) $C_{j} v=v$.
(ii) $C_{j} g=v$ for some $g \in \mathscr{H}^{s}$.
(iii) $v=\gamma_{j} u_{j}$ for some $u_{j} \in L_{j}^{s}$.

In this case, $u_{j}$ is given by the representation formula

$$
\begin{equation*}
u_{j}=K_{j} \mathscr{P}_{j} v \text { in } \Omega_{j} \tag{2.18}
\end{equation*}
$$

where $K_{j}$ is the vector $\left(K_{j 0}, \ldots, K_{j, 2 m-1}\right)$.
Thus we can write problem (2.1)-(2.3) in the equivalent form

$$
\begin{gather*}
\left(1-C_{1}\right) \gamma_{1} u_{1}=0,  \tag{2.19}\\
\left(1-C_{2}\right) \gamma_{2} u_{2}=0,  \tag{2.20}\\
R_{2} \gamma_{2} u_{2}-R_{1} \gamma_{1} u_{1}=u_{0} . \tag{2.21}
\end{gather*}
$$

This is a system of $6 m$ equations on the boundary for the $4 m$ unknowns $\gamma_{1} u_{1}, \gamma_{2} u_{2}$.

We emphasise here that up to now everything remains true if we consider $u_{1}$ and $u_{2}$ as vector-valued functions with $N$ components and $P_{1}$ and $P_{2}$ as ( $N \times N$ )-systems of differential operators. The matrices $R_{j}, \mathscr{P}_{j}, \mathscr{K}_{j}, C_{j}$, etc., must then be block matrices of ( $N \times N$ )-blocks. System (2.19), (2.20), (2.21) is then a $(6 m N \times 4 m N)$-system.

From this system we can extract a quadratic subsystem by eliminating $R_{2} \gamma_{2} u_{2}$ from (2.21) and multiplying (2.19), (2.20) by $R_{1}$ and $R_{2}$, respectively. We obtain

$$
\begin{gather*}
\left(1-\tilde{C}_{1}\right) R_{1} \gamma_{1} u_{1}=0,  \tag{2.22}\\
\left(1-\tilde{C}_{2}\right) R_{1} \gamma_{1} u_{1}=-\left(1-\tilde{C}_{2}\right) u_{0} \tag{2.23}
\end{gather*}
$$

with

$$
\begin{equation*}
\tilde{C}_{j}:=R_{j} C_{j} R_{j}^{-1} \quad(j=1,2) \tag{2.24}
\end{equation*}
$$

Now we subtract (2.22) from (2.23) and obtain the quadratic system

$$
\begin{equation*}
H v=-\left(1-\tilde{C}_{2}\right) u_{0} \quad \text { with } \quad H:=\tilde{C}_{1}-\tilde{C}_{2} \tag{2.25}
\end{equation*}
$$

for the unknown $v=R_{1} \gamma_{1} u_{1}$.
We have the following equivalence theorem:
Theorem 2.4. Let $u_{0} \in \mathscr{H}^{s}$ be given.
(i) If $u_{j} \in L_{j}^{s}(j=1,2)$ solve the transmission problem (2.1), (2.2), (2.3) then $v=R_{1} \gamma_{1} u_{1} \in \mathscr{H}^{s}$ solves the equation (2.25).
(ii) If $v \in \mathscr{H}^{s}$ solves (2.25) then with
and

$$
\begin{equation*}
v_{1}:=\tilde{C}_{1} v ; \quad v_{2}:=\tilde{C}_{2}\left(v+u_{0}\right) \tag{2.26}
\end{equation*}
$$

$$
\begin{equation*}
u_{j}:=K_{j} \mathscr{P}_{j} R_{j}^{-1} v_{j} \text { in } \Omega_{j} \quad(\text { see }(2.18)), \tag{2.27}
\end{equation*}
$$

$u_{j} \in L_{j}^{s}$ solve the problem (2.1), (2.2), (2.3).
Proof. (i) This follows from the derivation of (2.25) above.
(ii) We use Lemma 2.3 which, from (2.26), gives that (for $j=1,2)\left(1-\bar{C}_{j}\right) v_{j}=0$, hence $v_{j}=R_{j} \gamma_{j} \mu_{j}$ for some $u_{j} \in L_{j}^{s}$. It remains to show (2.3):
From (2.26) and (2.25) it follows that

$$
v_{2}-v_{1}=\left(\tilde{C}_{2}-\tilde{C}_{1}\right) v+\tilde{C}_{2} u_{0}=-H v+\tilde{C}_{2} u_{0}=\left(1-\tilde{C}_{2}+\tilde{C}_{2}\right) u_{0}=u_{0} .
$$

Now we formulate the assumptions which will imply the strong ellipticity of the operator $H$. They consist essentially of the strong ellipticity of the boundary value problems on $\Omega_{1}$ and $\Omega_{2}$ and of two other boundary value problems obtained from interchanging the domains $\Omega_{1}$ and $\Omega_{2}$.

We require the existence of a "first Green formula" for $P_{j}$ and $R_{j}$ : Let

$$
\left.R_{j}:=\left(\begin{array}{c}
B_{j}^{0}  \tag{2.28}\\
\vdots \\
B_{j}^{m-1} \\
Q_{j}^{m-1} \\
\vdots \\
Q_{j}^{0}
\end{array}\right), \quad \text { i.e. } \begin{array}{ll}
B_{j}^{i k}=R_{j}^{i k} & \text { for } k=0, \ldots, m-1, \\
Q_{j}^{i k}=R_{j}^{i, 2 m-k-1} & \text { for } k=0, \ldots, m-1 ;
\end{array}\right\}
$$

and $B_{j}^{i} v:=\sum_{k=0}^{m-1} B_{j}^{i k} v^{k}$ for $v \in C^{\infty}\left(\Gamma ; \mathbb{C}^{m}\right), Q_{j}^{i}$ correspondingly.
Assumption 2.5. For $j=1,2$, there exists a sesquilinear form $\Phi_{j}:(u, v) \mapsto$ $\Phi_{j}(u, v)$ on $C_{0}^{\infty}\left(\overline{\Omega_{j}}\right) \times C_{0}^{\infty}\left(\overline{\Omega_{j}}\right)$ such that

$$
\begin{equation*}
\operatorname{Re} \int_{\Omega_{j}} \bar{u}_{j} . P_{j} u_{j} d x=\operatorname{Re} \Phi_{j}\left(u_{j}, u_{j}\right)+(-1)^{j} \operatorname{Re} \int_{\Gamma} \sum_{i=0}^{m-1} \overline{B_{j}^{i} \gamma_{j} u_{j}} \cdot Q_{j}^{i} \gamma_{j} u_{j} d o \tag{2.29}
\end{equation*}
$$

for $u_{j} \in C_{0}^{\infty}\left(\overline{\Omega_{j}}\right)$.
Assumption 2.6. (a) (Continuity). For every bounded subset $K \subset \mathbb{R}^{n}$ there exists $C>0$ such that (for $j=1,2$ )

$$
\left|\Phi_{j}(u, v)\right| \leqq C\|u\|_{H^{m}\left(\Omega_{j}\right)}\|v\|_{\boldsymbol{H}^{m}\left(\Omega_{j}\right)}
$$

for all $u, v \in C_{0}^{\infty}\left(\overline{\Omega_{j}} \cap K\right)$.
(b) (Gårding's inequality) For every bounded subset $K \subset \mathbb{R}^{n}$ there exist $\lambda>0$, $c \in \mathbb{R}, \varepsilon>0$ such that

$$
\begin{equation*}
\operatorname{Re} \Phi_{j}(u, u) \geqq \lambda\|u\|_{H^{m}\left(\Omega_{j}\right)}^{2}-c\|u\|_{H^{m-\varepsilon}\left(\Omega_{j}\right)}^{2} \tag{2.30}
\end{equation*}
$$

for all $u \in C_{0}^{\infty}\left(\overline{\Omega_{j}} \cap K\right)$.
It is classical (see e.g. [17]) that these assumptions are satisfied for many strongly elliptic boundary value problems. For example, let $P_{j}$ be of second order, i.e.

$$
\begin{equation*}
P_{j}=-\sum_{i, k=1}^{n} \partial_{i} a_{j}^{i k} \partial_{k}+\sum_{k=1}^{n} b_{j}^{k} \partial_{k}+c_{j} \tag{2.31}
\end{equation*}
$$

with smooth coefficients $a_{j}^{i k}, b_{j}^{k}$, and $c_{j} ;\left(\partial_{k}=\partial / \partial_{x_{k}}\right)$.

Green's first formula (2.29) holds with

$$
\begin{equation*}
\Phi_{j}(u, v)=\int_{\Omega_{j}}\left(\sum_{i, k=1}^{n} \overline{\partial_{i} u} \cdot a_{j}^{i k} \partial_{k} v+\sum_{k=1}^{n} \bar{u} \cdot b_{j}^{k} \partial_{k} v+\bar{u} \cdot c_{j} v\right) d x \tag{2.32}
\end{equation*}
$$

and

$$
\begin{align*}
& B_{j} \gamma_{j} u_{j}=\left.u\right|_{\Gamma}, \\
& Q_{j} \gamma_{j} u_{j}=\left.\partial_{v_{i}} u\right|_{\Gamma}, \tag{2.33}
\end{align*}
$$

with the conormal derivative

$$
\begin{equation*}
\partial_{v_{i}} u=\sum_{i, k=1}^{n} n_{i} a_{j}^{i k} \partial_{k} u . \tag{2.34}
\end{equation*}
$$

Here $u$ may be an $N$-vector and $a_{j}^{i k}, b_{j}^{i k}$, and $c_{j}(N \times N)$-matrices. The representation (2.31) is not unique, and, contrary to the scalar case, in the vector-valued case the validity of Assumption 2.6(b) depends on the choice of this divergence representation. This is what happens for the case of electromagnetic problems, see Section 3.

The boundary integral in (2.29) corresponds to the natural duality on the "energy space" $\mathscr{H}^{0}$ with respect to the $L^{2}\left(\Gamma ; \mathbb{C}^{2 m}\right)$ scalar product:

For $v, w \in C^{\infty}\left(\Gamma ; \mathbb{C}^{m}\right)$ with

$$
v=\left(\begin{array}{c}
v_{0} \\
\vdots \\
v_{2 m-1}
\end{array}\right), \quad w=\left(\begin{array}{c}
w_{0} \\
\vdots \\
w_{2 m-1}
\end{array}\right)
$$

let

$$
\begin{equation*}
(v, w)_{\mathscr{H}_{0}}:=\int_{\Gamma} \sum_{k=0}^{2 m-1} \overline{v_{k}} \cdot w_{2 m-1-k} d o . \tag{2.35}
\end{equation*}
$$

This then extends by continuity to $v, w \in \mathscr{H}^{0}$ (cf. (2.15)), and we have

$$
\left.\left(R_{j} v, R_{j} w\right)_{\mathscr{F}^{0}}=\int_{\Gamma} \sum_{k=0}^{m-1} \overline{B_{j}^{k} v} \cdot Q_{j}^{k} w+\sum_{k=0}^{m-1} \overline{Q_{j}^{k} v} \cdot B_{j}^{k} w\right\} d o,
$$

in particular for $v=w$

$$
\begin{equation*}
\left(R_{j} v, R_{j} v\right)_{\mathscr{O}^{0}}=2 \operatorname{Re} \int_{\Gamma} \sum_{k=0}^{m-1} \overline{B_{j}^{k} v} \cdot Q_{j}^{k} v d o . \tag{2.36}
\end{equation*}
$$

We need to consider two more boundary value problems defined by interchanging the interior and exterior domains. Thus we write

$$
\left.\begin{array}{ll}
P_{1}^{\dagger}:=P_{2} \text { on } \Omega_{1}, & P_{2}^{\dagger}:=P_{1} \text { on } \Omega_{2},  \tag{2.37}\\
R_{1}^{\dagger}:=R_{2}, & R_{2}^{\dagger}:=R_{1} .
\end{array}\right\}
$$

Assumption 2.7. Assumptions 2.5, 2.6 are satisfied if $P_{j}$ is replaced by $P_{j}^{\dagger}$ and $R_{j}$ by $R_{j}^{\dagger}$ for $j=1,2$.

Under these assumptions, we can infer the strong ellipticity of our boundary integral operator $H$, as follows:
Theorem 2.8. Let Assumptions 2.5, 2,6, 2.7 be satisfied. Then there exists a
compact operator $C: \mathscr{H}^{0} \rightarrow \mathscr{H}^{0}$ and a constant $\beta>0$ such that

$$
\begin{equation*}
\operatorname{Re}(v,(H+C) v)_{\mathscr{H}^{0}} \geqq \beta\|v\|_{\mathscr{H}^{0}}^{2} \quad \text { for all } v \in \mathscr{H}^{0} . \tag{2.38}
\end{equation*}
$$

Here $\|v\|_{2_{2}}^{2}=\sum_{k=0}^{2 m-1}\left\|v_{k}\right\|_{H^{m-k-1 / 2}(\Gamma)}^{2}$.
Proof. We first consider the special case

$$
\begin{equation*}
P_{1}=P_{2}, \quad R_{1}=R_{2} \tag{2.39}
\end{equation*}
$$

In this case, one finds from (2.16), (2.24) that

$$
\begin{equation*}
\tilde{C}_{1}+\tilde{C}_{2}=1 \tag{2.40}
\end{equation*}
$$

It suffices to show (2.38) for $v \in C^{\infty}\left(\Gamma ; \mathbb{C}^{m}\right) \subset \mathscr{H}^{0}$. Define $u_{j}(j=1,2)$ by the representation formula (2.27):

$$
\begin{equation*}
u_{j}=\chi K_{j} \mathscr{P}_{j} R_{j}^{-1} v \quad \text { in } \Omega_{j}, \tag{2.41}
\end{equation*}
$$

where $\chi \in C_{0}^{\infty}\left(\mathbb{R}^{n}\right)$ satisfies $\chi \equiv 1$ on a neighbourhood of $\overline{\Omega_{1}}$. Then from (2.24) and (2.14) we see that, for the Cauchy data,

$$
\begin{equation*}
R_{j} \gamma_{j} u_{j}=(-1)^{j} \tilde{C}_{j} v \tag{2.42}
\end{equation*}
$$

holds.
Thus, by the definition of $H$ in (2.25),

$$
\begin{equation*}
H v=-\left(R_{1} \gamma_{1} u_{1}+R_{2} \gamma_{2} u_{2}\right) . \tag{2.43}
\end{equation*}
$$

By (2.40) we have

$$
\begin{equation*}
v=R_{2} \gamma_{2} u_{2}-R_{1} \gamma_{1} u_{1} \tag{2.44}
\end{equation*}
$$

Thus the trace lemma gives

$$
\begin{equation*}
\|v\|_{\mathscr{H}^{0}}^{2} \leqq C\left(\left\|u_{1}\right\|_{H^{m}\left(\Omega_{1}\right)}^{2}+\left\|u_{2}\right\|_{H^{m}\left(\Omega_{2}\right)}^{2}\right) . \tag{2.45}
\end{equation*}
$$

By Gårding's inequality (2.30), the right-hand side can be further estimated by

$$
\begin{equation*}
\frac{C}{\lambda} \operatorname{Re}\left(\Phi_{1}\left(u_{1}, u_{1}\right)+\Phi_{2}\left(u_{2}, u_{2}\right)\right)+\frac{c C}{\lambda}\left(\left\|u_{1}\right\|_{H^{m-\varepsilon}\left(\Omega_{1}\right)}^{2}+\left\|u_{2}\right\|_{H^{m-\varepsilon}\left(\Omega_{2}\right)}^{2}\right) . \tag{2.46}
\end{equation*}
$$

Note that supp $u_{2} \subset K$ where $K=\operatorname{supp} \chi$ is bounded.
From (2.41) it follows that the $\|\cdot\|_{H^{m-\epsilon}}$-terms in (2.46) can be estimated by $\left\|T_{1} v\right\|_{\mathscr{H}^{0}}$ with a compact operator $T_{1}: \mathscr{H}^{0} \rightarrow \mathscr{H}^{0}$. Such an estimate is also possible for $\left\|P_{2} u_{2}\right\|_{H^{\prime}\left(\Omega_{2}\right)}$ for any $t \in \mathbb{R}$, because $P_{2} u_{2}=0$ where $\chi \equiv 1$ or $\chi \equiv 0$ holds, thus $P_{2} u_{2} \in C_{0}^{\infty}\left(\mathbb{R}^{n}\right)$, and its support has a positive distance from $\Gamma$, so that the kernel of the operator $P_{j} \chi K_{j} \mathscr{P}_{j} R_{j}^{-1}$ defining it is smooth. Thus

$$
\left|\int_{\Omega_{2}} \overline{u_{2}} \cdot P_{2} u_{2} d x\right| \leqq\left\|T_{2} v\right\|_{\mathscr{K}^{0}}^{2} \quad \text { for some compact } T_{2}: \mathscr{H}^{0} \rightarrow \mathscr{H}^{0} .
$$

Now we apply Green's first theorem (2.29) to (2.46) and use (2.36). With $P_{1} u_{1}=0$, we obtain

$$
\operatorname{Re} \Phi_{j}\left(u_{j}, u_{j}\right)=\operatorname{Re} \int_{\Omega_{j}} \bar{u}_{j} . P_{j} u_{j} d x-\frac{(-1)^{j}}{2}\left(R_{j} \gamma_{j} u_{j}, R_{j} \gamma_{j} u_{j}\right)_{\mathscr{H}^{0}},
$$

hence

$$
\begin{equation*}
\|v\|_{\mathscr{R}^{0}}^{2} \leqq\left\|T_{1} v\right\|_{\mathscr{C}^{0}}^{2}+\left\|T_{2} v\right\|_{\mathscr{R}^{0}}^{2}+\frac{C}{2 \lambda}\left\{\left(R_{1} \gamma_{1} u_{1}, R_{1} \gamma_{1} u_{1}\right)_{\mathscr{H}^{0}}-\left(R_{2} \gamma_{2} u_{2}, R_{2} \gamma_{2} u_{2}\right)_{\mathscr{H}^{0}}\right\} . \tag{2.47}
\end{equation*}
$$

On the other hand, we find, from (2.43), (2.44), that

$$
\begin{aligned}
(v, A v)_{\mathscr{H}^{0}}= & \left(-R_{1} \gamma_{1} u_{1}+R_{2} \gamma_{2} u_{2},-R_{1} \gamma_{1} u_{1}-R_{2} \gamma_{2} u_{2}\right)_{\mathscr{H}^{0}} \\
= & \left(R_{1} \gamma_{1} u_{1}, R_{1} \gamma_{1} u_{1}\right)_{\mathscr{H}^{0}}-\left(R_{2} \gamma_{2} u_{2}, R_{2} \gamma_{2} u_{2}\right)_{\mathscr{H}^{0}} \\
& +\left(R_{1} \gamma_{1} u_{1}, R_{2} \gamma_{2} u_{2}\right)_{\mathscr{H}^{0}}-\left(R_{2} \gamma_{2} u_{2}, R_{1} \gamma_{1} u_{1}\right)_{\mathscr{H}^{0}} \\
= & \left(R_{1} \gamma_{1} u_{1}, R_{1} \gamma_{1} u_{1}\right)_{\mathscr{H}^{0}}-\left(R_{2} \gamma_{2} u_{2}, R_{2} \gamma_{2} u_{2}\right)_{\mathscr{H}^{0}} \\
& +2 i \operatorname{Im}\left(R_{1} \gamma_{1} u_{1}, R_{2} \gamma_{2} u_{2}\right)_{\mathscr{H}} .
\end{aligned}
$$

By taking real parts, we conclude from (2.47) that

$$
\|v\|_{\mathscr{\mathscr { C } ^ { 0 }}}^{2} \leqq\left\|T_{1} v\right\|_{\mathscr{\mathscr { C } ^ { 0 }}}^{2}+\left\|T_{2} v\right\|_{\mathscr{e ^ { 0 }}}^{2}+\frac{C}{2 \lambda} \operatorname{Re}(v, A v)_{\mathscr{K ^ { 0 }}}
$$

After subsuming all compact parts into a single one, we arrive at (2.38).
Now we abandon hypothesis (2.39). By what we have shown so far, we know that Gårding's inequality (2.38) holds in particular for the case where $P_{2}$ and $R_{2}$ are replaced by $P_{2}^{\dagger}$ and $R_{2}^{\dagger}$, respectively, because by (2.37) hypothesis (2.39) is then satisfied. We denote the corresponding Calderón projector by $\tilde{C}_{2}^{\dagger}$, and the corresponding boundary integral operator by

$$
H_{1}^{\dagger}:=\tilde{C}_{1}-\tilde{C}_{2}^{\dagger}
$$

Similarly, if we replace $P_{1}$ and $R_{1}$ by $P_{1}^{\dagger}$ and $R_{1}^{\dagger}$, then (2.39) is satisfied and therefore Gårding's inequality holds. We denote the corresponding Calderón projector by $\tilde{C}_{1}^{\dagger}$ and the boundary integral operator by

$$
H_{2}^{\dagger}:=\tilde{C}_{1}^{\dagger}-\tilde{C}_{2}
$$

Now from (2.40), it follows that

$$
\tilde{C}_{1}+\tilde{C}_{2}^{\dagger}=1=\tilde{C}_{1}^{\dagger}+\tilde{C}_{2},
$$

hence

$$
H_{1}^{\dagger}=2 \tilde{C}_{1}-1 ; \quad H_{2}^{\dagger}=1-2 \tilde{C}_{2}
$$

and finally

$$
\begin{equation*}
H=\tilde{C}_{1}-\tilde{C}_{2}=\frac{1}{2}\left(H_{1}^{\dagger}+H_{2}^{\dagger}\right) \tag{2.48}
\end{equation*}
$$

Therefore, the Gårding inequality (2.38) for $H$ follows by adding the two Gårding inequalities for $H_{1}^{\dagger}$ and $H_{2}^{\dagger}$.

## 3. A coercive bilinear form for electromagnetic problems

The time-harmonic scattering of electromagnetic fields by a penetrable body $\Omega_{1}$ in the case of isotropic homogeneous materials is described by Maxwell's equations (see [20]):

$$
\begin{equation*}
\operatorname{curl} \vec{E}=i \omega \mu \vec{H} ; \quad \text { curl } \vec{H}=-i \omega \varepsilon \vec{E} \quad \text { in } \quad \Omega_{1} \cup \Omega_{2} \tag{3.1}
\end{equation*}
$$

with the transmission conditions

$$
\begin{equation*}
[\vec{n} \times \vec{E}]_{\Gamma}=0 ; \quad[\vec{n} \times \vec{H}]_{\Gamma}=0 \quad \text { on } \Gamma \tag{3.2}
\end{equation*}
$$

and the radiation condition

$$
\begin{equation*}
\omega \mu \frac{x}{|x|} \times \vec{H}_{\mathrm{sc}}+k \vec{E}_{\mathrm{sc}}=o\left(|x|^{-1}\right) ; \quad \vec{E}_{\mathrm{sc}}=O\left(|x|^{-1}\right) \quad \text { as } \quad|x| \rightarrow \infty \tag{3.3}
\end{equation*}
$$

Here $[\vec{v}]_{\Gamma}:=\left.\vec{v}\right|_{\overline{\Omega_{2}}}-\left.\vec{v}\right|_{\bar{\Omega}_{1}}$ denotes the jump of $\vec{v}$ across $\Gamma$.
We assume that the coefficient functions $\varepsilon, \mu$, and $k$ are constant on $\Omega_{1}$ and on $\Omega_{2}$, and $\omega$ is the constant frequency:

$$
\varepsilon=\varepsilon_{j}, \quad \mu=\mu_{j}, \quad k=k_{j} \quad \text { on } \quad \Omega_{j}(j=1,2) ; \quad k^{2}=\omega^{2} \varepsilon \mu
$$

We further assume ([20]) that

$$
\begin{equation*}
\operatorname{Re} \varepsilon_{j}>0, \quad \operatorname{Im} \varepsilon_{j} \geqq 0 ; \quad \arg k_{j} \in[0, \pi) ; \quad \arg \omega \in[0, \pi) ; \quad \mu_{j}>0 \tag{3.4}
\end{equation*}
$$

The total fields $\vec{E}$ are decomposed into

$$
\vec{E}=\vec{E}_{\mathrm{in}}+\vec{E}_{\mathrm{sc}} ; \quad \vec{H}=\vec{H}_{\mathrm{in}}+\vec{H}_{\mathrm{sc}}
$$

where the incoming fields $\vec{E}_{\text {in }}$ and $\vec{H}_{\text {in }}$ are supposed to satisfy (3.1), and the scattered fields $\vec{E}_{\text {sc }}$ and $\vec{H}_{\text {sc }}$ appear in the radiation condition (3.3). The unique solvability of (3.1)-(3.3) is shown in [16], [20].

If we define

$$
\begin{equation*}
\vec{u}=\vec{u}_{1}=\vec{E} \quad \text { in } \Omega_{1} ; \quad \vec{u}=\vec{u}_{2}=\vec{E}_{\mathrm{sc}} \quad \text { in } \Omega_{2} ; \quad \vec{u}_{0}=\vec{E}_{\mathrm{in}} \tag{3.5}
\end{equation*}
$$

then the components of $\vec{u}$ satisfy the Helmholtz equation:

$$
\begin{equation*}
\left(\Delta+k_{1}^{2}\right) \vec{u}_{1}=0 \quad \text { in } \Omega_{1} ; \quad\left(\Delta+k_{2}^{2}\right) \vec{u}_{2}=0 \quad \text { in } \Omega_{2} . \tag{3.6}
\end{equation*}
$$

We consider the transmission conditions (compare [16])

$$
\left.\begin{array}{rl}
\vec{u}_{1 T}-\vec{u}_{2 T} & =\vec{u}_{0 T} ;  \tag{3.7}\\
\lambda_{1} \operatorname{div} \vec{u}_{1}-\lambda_{2} \operatorname{div} \vec{u}_{2} & =\lambda_{2} \operatorname{div} \vec{u}_{0} ; \\
\varepsilon_{1} \vec{n} \cdot \vec{u}_{1}-\varepsilon_{2} \vec{n} \cdot \vec{u}_{2} & =\varepsilon_{2} \vec{n} \cdot \vec{u}_{0} ; \\
\frac{1}{\mu_{1}} \vec{n} \times \operatorname{curl} \vec{u}_{1}-\frac{1}{\mu_{2}} \vec{n} \times \operatorname{curl} \vec{u}_{2} & =\frac{1}{\mu_{2}} \vec{n} \times \operatorname{curl} \vec{u}_{0},
\end{array}\right\}
$$

where $\vec{v}_{\mathrm{T}}:=-\vec{n} \times(\vec{n} \times \vec{v})$ denote the tangential components of $\vec{v}$, and the radiation condition

$$
\begin{equation*}
\frac{x}{|x|} \times \operatorname{curl} \vec{u}_{2}-\frac{x}{|x|} \operatorname{div} \vec{u}_{2}+i k_{2} \vec{u}_{2}=o\left(|x|^{-1}\right) \quad \text { as } \quad|x| \rightarrow \infty . \tag{3.8}
\end{equation*}
$$

The coefficients $\lambda_{j} \neq 0$ in (3.7) are specified later.
Let us now study the equivalence of the transmission problems (3.1)-(3.3) and (3.6)-(3.8). Because we only need standard applications of Green's formulae, we do not specify the precise smoothness requirements. Even weak solutions in $H_{\text {loc }}^{1}\left(\overline{\Omega_{j}}\right)$ are allowed.

We first show that (3.1)-(3.3) imply (3.6)-(3.8), for any choice of $\lambda_{1}, \lambda_{2}$ :
By the definition (3.5), it is clear that Maxwell's equations (3.1) imply the Helmholtz equations (3.6), and $\operatorname{div} \vec{E}=0$ shows that the radiation condition (3.8) follows from (3.3). Also the first, second, and fourth of the transmission conditions (3.7) are satisfied. In order to show the third condition in (3.7), we choose a test function $\varphi \in C_{0}^{\infty}\left(\mathbb{R}^{3}\right)$ and obtain

$$
\begin{align*}
0 & =\int_{\Gamma} \operatorname{grad} \varphi \cdot[\vec{n} \times \vec{H}]_{\Gamma} d o=-\int_{\Omega_{1} \cup \Omega_{2}} \operatorname{grad} \varphi \cdot \operatorname{curl} \vec{H} d x  \tag{3.9}\\
& =i \omega \int_{\Omega_{1} \cup \Omega_{2}} \operatorname{grad} \varphi \cdot \varepsilon \vec{E} d x=-i \omega \int_{\Gamma} \varphi[\varepsilon \vec{n} \cdot \vec{E}]_{\Gamma} d o
\end{align*}
$$

From this we find $[\varepsilon \vec{n}, \vec{E}]_{\Gamma}=0$, which is the third condition in (3.7).
Conversely, assume that (3.6)-(3.8) are satisfied. Furthermore, assume that $\vec{u}_{0}$ satisfies $\left(\Delta+k_{2}^{2}\right) \vec{u}_{0}=0$ and $\operatorname{div} \vec{u}_{0}=0, \vec{E}$ is defined by (3.5), and $\vec{H}$ is defined by $\vec{H}=(1 / i \omega \mu)$ curl $\vec{E}$. Then (3.1)-(3.3) will be satisfied if and only if div $\vec{u}_{1} \equiv 0$ and $\operatorname{div} \vec{u}_{2} \equiv 0$. Therefore we define
$\rho:=\rho_{1}:=k_{1}^{-2} \operatorname{div} \vec{u}_{1} \quad$ in $\Omega_{1} ; \quad \rho:=\rho_{2}:=k_{2}^{-2} \operatorname{div} \vec{u}_{2}\left(=k_{2}^{-2} \operatorname{div}\left(\vec{u}_{0}+\vec{u}_{2}\right)\right) \quad$ in $\Omega_{2}$.
Then $\rho$ satisfies

$$
\begin{equation*}
\left(\Delta+k^{2}\right) \rho=0 \quad \text { in } \Omega_{1} \cup \Omega_{2} \tag{3.10}
\end{equation*}
$$

and

$$
\begin{equation*}
\lambda_{1} k_{1}^{2} \rho_{1}=\lambda_{2} k_{2}^{2} \rho_{2} \quad \text { on } \Gamma \tag{3.11}
\end{equation*}
$$

Furthermore, from the radiation condition (3.8), it follows ([14], [25]) that $u_{2}$ can be represented in $\Omega_{2}$ by the Stratton-Chu representation formula (see Lemma 4.3, below). This implies in particular that $\rho$ satisfies a Sommerfeld type radiation condition

$$
\begin{equation*}
\frac{x}{|x|} . \operatorname{grad} \rho-i k_{2} \rho=o\left(|x|^{-1}\right) ; \quad \rho=O\left(|x|^{-1}\right) \quad \text { as } \quad|x| \rightarrow \infty \tag{3.12}
\end{equation*}
$$

In addition, a second transmission condition for $\rho$ holds:
Define $\vec{E}_{0}:=\vec{E}+\operatorname{grad} \rho$ in $\Omega_{1} \cup \Omega_{2}$. Then

$$
\operatorname{div} \vec{E}_{0}=\operatorname{div} \vec{E}+\Delta \rho=\operatorname{div} \vec{u}-k^{2} \rho=0 \quad \text { in } \quad \Omega_{1} \cup \Omega_{2} .
$$

Hence

$$
\operatorname{curl} \vec{H}=\frac{1}{i \omega \mu} \operatorname{curl} \operatorname{curl} \vec{E}_{0}=-i \omega \varepsilon \vec{E}_{0}
$$

Thus the pair ( $\vec{E}_{0}, \vec{H}$ ) satisfies Maxwell's equations (3.1) and the transmission condition $[\vec{n} \times \vec{H}]_{\Gamma}=0$. We conclude as above (3.9) that $\left[\varepsilon \vec{n} . \vec{E}_{0}\right]_{\Gamma}=0$. Subtracting $[\varepsilon \vec{n} \cdot \vec{E}]_{\Gamma}=0$, we find

$$
\begin{equation*}
\varepsilon_{1} \partial_{n} \rho_{1}=\varepsilon_{2} \partial_{n} \rho_{2} \quad \text { on } \Gamma \text {. } \tag{3.13}
\end{equation*}
$$

Thus we have reduced the question of equivalence of the two transmission
problems to the question of unique solvability of the scalar transmission problem (3.10)-(3.13). Sufficient conditions for this uniqueness are well-known. For example, from [4, Proposition 4.7] it follows that either one of the following two conditions implies $\rho \equiv 0$ :

$$
\begin{equation*}
k_{2}>0 \quad \text { and } \quad \operatorname{Im} \lambda_{1} \overline{\lambda_{2}} \bar{\varepsilon}_{1} \varepsilon_{2} k_{1}^{2} \geqq 0 \quad \text { and } \operatorname{Im} \lambda_{1} \overline{\lambda_{1}} \bar{\varepsilon}_{1} \varepsilon_{2} \leqq 0 ; \tag{3.14}
\end{equation*}
$$

$\operatorname{Im} k_{2}>0 \quad$ or $\quad k_{2}=0$, and if there exist four numbers $\alpha, \beta, \gamma, \delta \geqq 0$ with $-\alpha \lambda_{1} \overline{\varepsilon_{1}}-\beta \lambda_{2} \overline{\varepsilon_{2}}+\gamma \lambda_{1} \overline{\varepsilon_{1}} k_{1}^{2}+\delta \lambda_{2} \bar{\varepsilon}_{2} k_{2}^{2}=0$,
then at least one of the numbers $\alpha, \beta, \gamma, \delta$ has to be zero.
Notable special cases of these conditions are:
(i) If $\lambda_{1}=\varepsilon_{1}$ and $\lambda_{2}=\varepsilon_{2}$, then $\rho \equiv 0$ follows.
(ii) If $\lambda_{1}=1 / \mu_{1} \overline{\varepsilon_{1}}$ and $\lambda_{2}=1 / \mu_{2} \overline{\varepsilon_{2}}$, then $\rho \equiv 0$ follows.
(iii) If all coefficients $\varepsilon, \lambda$, and $k_{2}$ are real, then $\rho \equiv 0$ follows.
(iv) The periodic eddy current problem:

Here $\varepsilon_{1}=i \sigma / \omega, \omega>0$, and $\sigma>0$ is the electric conductivity in $\Omega_{1}$. Also $\varepsilon_{2}>0$, hence

$$
k_{1}^{2}=i \omega \mu_{1} \sigma ; \quad k_{2}^{2}>0
$$

Therefore, (3.14) reduces to the conditions

$$
\begin{equation*}
\operatorname{Im} \frac{\lambda_{2}}{\lambda_{1}} \leqq 0 \quad \text { and } \quad \operatorname{Re} \frac{\lambda_{2}}{\lambda_{1}} \geqq 0 . \tag{3.16}
\end{equation*}
$$

Note that $\operatorname{Im}\left(k_{1}^{2} / k_{2}^{2}\right)>0$, so that in this case the natural choice

$$
\begin{equation*}
\lambda=k^{-2} \tag{3.17}
\end{equation*}
$$

does not necessarily imply $\rho \equiv 0$. The choices (i) or (ii) above, however, will also work in this case.
(v) The choice (3.17) always leads to a solution of the transmission problem (3.1)-(3.3). Namely, in this case define $\vec{E}_{0}$ as above by $\vec{E}_{0}=\vec{E}+\operatorname{grad} \rho$, then the pair ( $\vec{E}_{0}, \vec{H}$ ) satisfies Maxwell's equations (3.1) as well as the transmission conditions (3.2). However, as seen in (iv) above, the solution of the problem (3.6)-(3.8) might then be non-unique.

Besides the "physical" transmission problem, for mathematical simplicity we also consider the corresponding problem where all the coefficients $\lambda, \varepsilon$, and $\mu$ are equal to unity, i.e. the transmission conditions

$$
\left.\begin{array}{rl}
\vec{u}_{1 \tau}-\vec{u}_{2 T} & =\vec{u}_{0 T} ;  \tag{3.18}\\
\operatorname{div} \vec{u}_{1}-\operatorname{div} \vec{u}_{2}=\operatorname{div} \vec{u}_{0} ; \\
\vec{n} \cdot \vec{u}_{1}-\vec{n} \cdot \vec{u}_{2}=\vec{n} \cdot \vec{u}_{0} ; \\
\vec{n} \times \operatorname{curl} \vec{u}_{1}-\vec{n} \times \operatorname{curl} \vec{u}_{2}=\vec{n} \times \operatorname{curl} \vec{u}_{0} .
\end{array}\right\}
$$

Now we wish to apply the theory developed in Section 2 to the present case. We have the differential operators

$$
\begin{equation*}
P_{j}=-\left(\Delta+k_{j}^{2}\right)=\text { curl curl }-\operatorname{grad} \operatorname{div}-k_{j}^{2} . \tag{3.19}
\end{equation*}
$$

This representation leads to the conormal derivatives (cf. (2.31), (2.34))

$$
\begin{equation*}
\partial_{v} \vec{u}:=\partial_{v_{1}} \vec{u}=\partial_{v_{2}} \vec{u}=-\vec{n} \times \operatorname{curl} \vec{u}+\vec{n} . \operatorname{div} \vec{u} \tag{3.20}
\end{equation*}
$$

and to the well-known [14] Green formula (cf. (2.29), (2.32))

$$
\begin{array}{r}
-\int_{\Omega_{j}} \overrightarrow{\vec{u}}_{j} \cdot\left(\Delta+k_{j}^{2}\right) \vec{w}_{j} d x=\int_{\Omega_{j}}\left(\operatorname{curl} \overline{\vec{u}}_{j} \cdot \operatorname{curl} \vec{w}_{j}+\operatorname{div} \overline{\vec{u}}_{j} \operatorname{div} \vec{w}_{j}-k_{j}^{2} \overline{\vec{u}}_{j} \cdot \vec{w}_{j}\right) d x \\
+(-1)^{j} \int_{\Gamma} \overline{\vec{u}}_{j} \cdot\left(-\vec{n} \times \operatorname{curl} \vec{w}_{j}+\vec{n} \operatorname{div} \vec{w}_{j}\right) d o \tag{3.21}
\end{array}
$$

for $\vec{u}_{j}, \vec{w}_{j} \in C_{0}^{\infty}\left(\bar{\Omega}_{j} ; \mathbb{C}^{3}\right)$.
So we have the sesquilinear forms

$$
\begin{equation*}
\Phi_{i}(\vec{u}, \vec{w})=\int_{\Omega_{j}}\left(\operatorname{curl} \overline{\vec{u}} . \operatorname{curl} \vec{w}+\operatorname{div} \overline{\vec{u}} \operatorname{div} \vec{w}-k_{j}^{2} \overline{\vec{u}} . \vec{w}\right) d x \tag{3.22}
\end{equation*}
$$

and the boundary operators

$$
R \vec{u}:=R_{1} \vec{u}=R_{2} \vec{u}=\left.\binom{\vec{u}}{\partial_{v} \vec{u}}\right|_{\Gamma} ; \quad \begin{align*}
& B \vec{u}:=B_{1} \vec{u}=B_{2} \vec{u}=\left.\vec{u}\right|_{\Gamma} ;  \tag{3.23}\\
& Q \vec{u}:=Q_{1} \vec{u}=Q_{2} \vec{u}=\left.\partial_{v} \vec{u}\right|_{\Gamma} .
\end{align*}
$$

By separating tangential and normal components and defining (on $\Gamma$ ) the Cauchy data

$$
\begin{align*}
& v:=\vec{n} . \vec{u} ; \vec{v}:=\vec{u}_{T}:=\vec{u}-\vec{n}(\vec{n} \cdot \vec{u})=-\vec{n} \times(\vec{n} \times \vec{u}) ; \\
& \psi:=\operatorname{div} \vec{u} ; \quad \vec{\psi}:=-\vec{n} \times \operatorname{curl} \vec{u}, \tag{3.24}
\end{align*}
$$

Green's first formula (3.21) reads

$$
\begin{equation*}
\int_{\Omega_{j}}{\overline{\vec{u}^{1}} \cdot P_{j} \vec{u}^{2} d x=\Phi_{j}\left(\vec{u}^{1}, \vec{u}^{2}\right)+(-1)^{j} \int_{\Gamma}\left(\overline{v^{1}} \psi^{2}+\overline{\vec{v}^{1}} \cdot \vec{\psi}^{2}\right) d o . ~ . ~}_{\text {. }} . \tag{3.25}
\end{equation*}
$$

The corresponding second Green's formula, obtained by antisymmetrising (3.25), and representation formula ("Stratton-Chu formula", see Section 4), obtained by inserting a fundamental solution in the latter, are also well known. Hence one can derive boundary integral equations by the method described in Section 2. Assumptions 2.5 and 2.6(a) are satisfied. Assumption 2.6(b) does not hold, however, since for harmonic vector fields $\vec{u}$ we have

$$
\Phi_{j}(\vec{u}, \vec{u})=-\int_{\Omega_{j}} k_{j}^{2}|\vec{u}|^{2} d x,
$$

which cannot be estimated from below by $\|\vec{u}\|_{H^{1}\left(\Omega ; ; c^{3}\right)}^{2}$. This well-known fact ( $[8],[25])$ implies here that the boundary integral operator $H$ is not strongly elliptic. There is, however, a strongly elliptic boundary integral operator for the transmission problem (3.6), (3.18). This gives, as the solution of the corresponding equation (2.25), not directly the set of Cauchy data as defined by (3.18) or (3.24) but a modified set. This modified set of Cauchy data is entirely equivalent to the original one in the sense that each set can be computed from the other one by application of tangential differential operators. We propose the following
modification:

$$
\left.\begin{array}{l}
\psi^{\prime}:=\psi-\operatorname{div} \vec{v}=\operatorname{div} \vec{u}-\operatorname{div}_{\top} \vec{u},  \tag{3.26}\\
\vec{\psi}^{\prime}:=\vec{\psi}+\operatorname{grad}_{T} v=-\vec{n} \times \operatorname{curl} \vec{u}-\vec{n} \times(\vec{n} \times(\operatorname{grad}(\vec{n} . \vec{u}))) .
\end{array}\right\}
$$

Thus the "electric" boundary operators are modified by

$$
\begin{equation*}
\binom{\vec{v}}{\psi^{\prime}}=\binom{\vec{v}}{\psi-\operatorname{div}_{T} \vec{v}} \Leftrightarrow\binom{\vec{v}}{\psi}=\binom{\vec{v}}{\psi^{\prime}+\operatorname{div}_{T} \vec{v}} \tag{3.27}
\end{equation*}
$$

and the "magnetic" boundary operators by

$$
\begin{equation*}
\binom{v}{\vec{\psi}^{\prime}}=\binom{v}{\vec{\psi}+\operatorname{grad}_{T} v} \Leftrightarrow\binom{v}{\vec{\psi}}=\binom{v}{\vec{\psi}^{\prime}-\operatorname{grad}_{T} v} . \tag{3.28}
\end{equation*}
$$

This modification of the Cauchy data was suggested by corresponding modifications of boundary integral operators in the case of boundary value problems in [18], which led to strongly elliptic operators.
We shall now show that with these modified boundary operators the corresponding bilinear forms $\Phi_{j}^{\prime}$ which are now defined by Green's first formula, satisfy Gărding's inequality, i.e. Assumption 2.6(b). Then all hypotheses of Theorem 2.8 are satisfied and this theorem proves the strong ellipticity of the corresponding boundary integral operator, which corresponds to the transmission problem (3.6), (3.18), (3.8).
We shall come back to the "physical" transmission conditions (3.7) in Section 5.

Theorem 3.1. Define the sesquilinear form $\boldsymbol{\Phi}_{j}^{\prime}(j=1,2)$ by

$$
\begin{equation*}
\int_{\Omega_{j}} \overline{\vec{u}}^{\overline{1}} \cdot P_{j} \vec{u}^{2} d x=\Phi_{j}^{\prime}\left(\vec{u}^{1}, \vec{u}^{2}\right)+(-1)^{j} \int_{\Gamma}\left(\overline{v^{1}} \psi^{\prime 2}+\overline{\vec{v}^{1}} \cdot \vec{\psi}^{\prime 2}\right) d o, \tag{3.29}
\end{equation*}
$$

where $P_{j}$ are defined by (3.19) and $v, \psi^{\prime}, \vec{v}, \vec{\psi}^{\prime}$ by (3.26). Then $\Phi_{j}^{\prime}$ is coercive over $H^{1}\left(\Omega_{j} ; \mathbb{C}^{3}\right)$, i.e. there exist $\lambda>0, C \in \mathbb{R}$ such that

$$
\begin{equation*}
\operatorname{Re} \Phi_{j}^{\prime}(\vec{u}, \vec{u}) \geqq \lambda\|\vec{u}\|_{H^{1}\left(\Omega_{j} ; \mathrm{C}^{3}\right)}^{2}-C\|\vec{u}\|_{L^{2}\left(\Omega_{j} ; \mathrm{C}^{3}\right)}^{2} \tag{3.30}
\end{equation*}
$$

for all $\vec{u} \in C_{0}^{\infty}\left(\overline{\Omega_{j}} ; \mathbb{C}^{3}\right)$.
Proof. There holds for $\vec{u} \in C_{0}^{\infty}\left(\overline{\Omega_{j}} ; \mathbb{C}^{3}\right)$ on $\Gamma$ :

$$
\begin{gathered}
\operatorname{div} \vec{u}-\operatorname{div}_{\mathrm{T}} \vec{u}=\operatorname{div}\left(\vec{u}-\vec{u}_{\mathrm{T}}\right)=\operatorname{div}((\vec{n} . \vec{u}) \vec{n})=\partial_{n}(\vec{n} \cdot \vec{u})+(\vec{n} \cdot \vec{u}) \operatorname{div} \vec{n} ; \\
\operatorname{grad}(\vec{n} \cdot \vec{u})-\vec{n} \times \operatorname{curl} \vec{n}=\partial_{n} \vec{u}+(\vec{u} . \operatorname{grad}) \vec{n}+\vec{u} \times \operatorname{curl} \vec{n} .
\end{gathered}
$$

This gives

$$
\begin{align*}
\bar{v} \psi^{\prime}+\overline{\vec{v}} \cdot \vec{\psi}^{\prime}= & \left(\operatorname{div} \vec{u}-\operatorname{div}_{\mathrm{T}} \vec{u}\right)\left(\vec{n} \cdot \overrightarrow{\vec{u}}^{\prime}\right)+(\operatorname{grad}(\vec{n} \cdot \vec{u})-\vec{n} \times \operatorname{curl} \vec{u}) \cdot \overline{\vec{u}}_{\mathrm{T}} \\
= & \left(\partial_{n}(\vec{u} \cdot \vec{u})\right)(\vec{n} \cdot \overrightarrow{\vec{u}})+\operatorname{div} \vec{n}(\vec{n} \cdot \vec{u})(\vec{n} \cdot \overrightarrow{\vec{u}})+\left(\partial_{n} \vec{u}\right) \overrightarrow{\vec{u}}_{\mathrm{T}} \\
& +\overrightarrow{\vec{u}}_{\mathrm{T}} \cdot(\vec{u} \cdot \operatorname{grad}) \vec{n}+\overline{\vec{u}}_{\mathrm{T}} \cdot(\vec{u} \times \operatorname{curl} \vec{n}) \\
= & \partial_{n} \vec{u} \cdot(\vec{n}(\vec{n} \cdot \vec{u}))+\vec{u} \cdot \partial_{n} \vec{n}(\vec{n} \cdot \overrightarrow{\vec{u}})+\left(\partial_{n} \vec{u}\right) \overrightarrow{\vec{u}}_{\mathrm{T}} \\
& +\operatorname{div} \vec{n}|\vec{n} \cdot \vec{u}|^{2}+\overline{\vec{u}}_{\mathrm{T}} \cdot(\vec{u} \cdot \operatorname{grad}) \vec{n}+\overrightarrow{\vec{u}}_{\mathrm{T}} \cdot(\vec{n} \times \operatorname{curl} \vec{n}) \\
= & \left(\partial_{n} \vec{u}\right) \cdot \overrightarrow{\vec{u}}+b(\vec{u}) \tag{3.31}
\end{align*}
$$

with

$$
b(\vec{u})=(\vec{n} \cdot \overline{\vec{u}}) \vec{u} \cdot \partial_{n} \vec{n}+|\vec{n} \cdot \vec{u}|^{2} \operatorname{div} \vec{n}+\overline{\vec{u}}_{\mathrm{T}} \cdot((\vec{u} \cdot \operatorname{grad}) \vec{n}+\vec{u} \times \operatorname{curl} \vec{n}) .
$$

In particular (this requires $\Gamma \in C^{2}$ )

$$
|b(\vec{u})(x)| \leqq C|\vec{u}(x)|^{2} \quad \text { for } \quad x \in \Gamma,
$$

hence

$$
\begin{equation*}
\left|\int_{\Gamma} b(\vec{u}) d o\right| \leqq C\left\|\left.\vec{u}\right|_{\Gamma}\right\|_{L^{2}(\Gamma)}^{2} \leqq C_{\varepsilon}\|\vec{u}\|_{H^{2}+\varepsilon\left(\Omega_{j}\right)}^{2} \quad(\varepsilon>0) . \tag{3.32}
\end{equation*}
$$

From definition (3.29) and (3.31), with Green's first formula for the scalar potential equation, now follows:

$$
\begin{aligned}
\Phi_{j}^{\prime}(\vec{u}, \vec{u})= & -\int_{\Omega_{j}} \overline{\vec{u}} \cdot \Delta \vec{u} d x-(-1)^{j} \int_{\Gamma} \overline{\vec{u}} \cdot \partial_{n} \vec{u} d o \\
& -\int_{\Omega_{j}} k_{j}^{2}|\vec{u}|^{2} d x-(-1)^{j} \int_{\Gamma} b(\vec{u}) d o \\
= & \|\vec{u}\|_{H^{1}\left(\Omega_{j} ; \mathbb{C}^{3}\right)}^{2}-\|\vec{u}\|_{L^{2}\left(\Omega_{j} ; \mathfrak{C}^{3}\right)}^{2} \\
& -k_{j}^{2}\|\vec{u}\|_{L^{2}\left(\Omega_{i} ; \mathfrak{C}^{3}\right)}^{2}-(-1)^{j} \int_{\Gamma} b(\vec{u}) d o .
\end{aligned}
$$

Together with (3.22) for some $\varepsilon \in\left(0, \frac{1}{2}\right)$, this gives (3.30).

## 4. The integral operators and their symbols

In this section we derive a boundary integral equation procedure to solve the transmission problem (3.6), (3.18), (3.8). First we give some additional notation. For $s \in \mathbb{R}$ we denote by $\mathbb{H}^{s}\left(\Omega_{j}\right)=H^{s}\left(\Omega_{j} ; \mathbb{C}^{3}\right)$, respectively $\mathbb{H}^{s}(\Gamma)=H^{s}\left(\Gamma ; \mathbb{C}^{3}\right)$, the Sobolev spaces formed by vector fields $\vec{u}$ with components which belong to $H^{s}\left(\Omega_{j}\right)$, respectively $H^{s}(\Gamma)$. As indicated by (3.24) we can decompose $\mathbb{H}^{s}(\Gamma)$ into two subspaces generated by the tangential fields to $\Gamma$ and the normal fields to $\Gamma$,

$$
\mathbb{H}^{s}(\Gamma)=T H^{s}(\Gamma) \oplus N H^{s}(\Gamma)
$$

with
$T H^{s}(\Gamma)=\left\{\vec{u} \in \mathbb{H}^{s}(\Gamma) \mid(\vec{n} \cdot \vec{u})=0\right\}, \quad N H^{s}(\Gamma)=\left\{\vec{u} \in \mathbb{H}^{s}(\Gamma) \mid \vec{u}=\vec{n} v, \quad v \in H^{s}(\Gamma)\right\}$.
The most general case where (3.6), (3.18), (3.8) can be converted into a variational problem (see Theorem 3.1) is when

$$
\left(\vec{u}_{0 T}, \operatorname{div} \vec{u}_{0}, \vec{n} \times \operatorname{curl} \vec{u}_{0}, \vec{n} \cdot \vec{u}_{0}\right) \in T H^{\frac{1}{2}}(\Gamma)+H^{-\frac{1}{2}}(\Gamma) \times T H^{-\frac{1}{2}}(\Gamma) \times H^{\frac{1}{2}}(\Gamma)=: \mathscr{H}^{0} .
$$

Then we look for $\vec{u} \in L_{j}(j=1,2)$ where

$$
\begin{align*}
& L_{1}:=\left\{\vec{u} \in \mathbb{H}^{1}\left(\Omega_{1}\right) \mid\left(\Delta+k_{1}^{2}\right) \vec{u}=0 \text { in } \Omega_{1}\right\},  \tag{4.1}\\
& L_{2}:=\left\{\vec{u} \in \mathbb{H}^{1}\left(\Omega_{2}\right) \mid\left(\Delta+k_{2}^{2}\right) \vec{u}=0 \text { in } \Omega_{2}, \vec{u} \text { satisfies }(3.8)\right\} .
\end{align*}
$$

According to (3.24), (3.25), the Cauchy data for (3.6), (3.18), (3.8) are defined as follows:

Definition 4.1. Let $\vec{u} \in L_{j}, j=1,2$. Then the Cauchy data $(\vec{v}, \psi, \vec{\psi}, v) \in \mathscr{H}^{0}$ of
$\vec{u}$ are defined via (3.25) by the traces

$$
\vec{v}:=-\vec{n} \times\left.(\vec{n} \times \vec{u})\right|_{\Gamma}, \quad \psi:=\left.\operatorname{div} \vec{u}\right|_{\Gamma}, \quad \vec{\psi}:=-\vec{n} \times\left.\operatorname{curl} \vec{u}\right|_{\Gamma}, \quad v:=\left.\vec{n} \cdot \vec{u}\right|_{\Gamma} .
$$

Before we give our solution procedure, let us briefly recall the idea of layer potentials by introducing the fundamental solution

$$
\begin{equation*}
\Phi_{j}(x, y)=\frac{e^{i k_{j}|x-y|}}{4 \pi|x-y|} \tag{4.2}
\end{equation*}
$$

of $\left(\Delta+k_{j}^{2}\right) \vec{u}=0$ in $\Omega_{j} ; j=1,2$.
DEfinition 4.2. Let $\vec{u} \in C^{\infty}\left(\Gamma ; \mathbb{C}^{3}\right)$. Then for any complex number $k_{j}$, ( $0 \leqq$ $\left.\arg k_{j}<\pi\right)$ and for $x \in \Omega_{j}$ we define

$$
\left.\begin{array}{l}
V_{\Omega_{j}} \vec{u}(x):=-2 \int_{\Gamma} \Phi_{j}(x, y) \vec{u}(y) d o(y),  \tag{4.3}\\
K_{\Omega_{j}} \vec{u}(x):=2 \operatorname{curl}_{x} \int_{\Gamma} \Phi_{j}(x, y) \vec{u}(y) d o(y) .
\end{array}\right\}
$$

The same definition of the single and double layer potential is valid for arbitrary distributions $\vec{u}$ on $\Gamma$, since for $x \neq \Gamma$ the above kernel $\Phi_{j}$ is a $C^{\infty}$-function on $\Gamma$.

With these potentials there holds the Stratton-Chu representation formula for the solution of the homogeneous Helmholtz equation in $\Omega_{j}$ (for classical solutions see [14], for weak solutions see [25]).

Lemma 4.3. For $\vec{u} \in L_{j}$ with Cauchy data $(\vec{v}, \psi, \vec{\psi}, v) \in \mathscr{H}^{0}$ and for $x \in \Omega_{j}$, $j=1,2$, there holds

$$
\begin{equation*}
\vec{u}(x)=\frac{(-1)^{j}}{2}\left(-\operatorname{curl} V_{\Omega_{j}}(\vec{n} \times \vec{v})+V_{\Omega_{j}}(\vec{n} \psi)+V_{\Omega_{j}} \vec{\psi}+\operatorname{grad} V_{\Omega_{j}} v\right)(x) \tag{4.4}
\end{equation*}
$$

In order to formulate the boundary values (jump relations) for the potential (4.4) we define the following boundary integral operators:

Definition 4.4. Let $\vec{u}$ be a $C^{\infty}$ vector field on $\Gamma$. Then for $x \in \Gamma$ and $x_{j} \in \Omega_{j}$

$$
\left.\begin{array}{l}
V_{j} \vec{u}(x):=-2 \int_{\Gamma} \Phi_{j}(x, y) \vec{u}(y) d o(y),  \tag{4.5}\\
\vec{K}_{j} \vec{u}(x):=2 \operatorname{curl}_{\top} \int_{\Gamma} \Phi_{j}(x, y)(\vec{n} \times \vec{u})(y) d o(y), \\
D_{j} \vec{u}(x):=\lim _{x_{j} \rightarrow x}\left(\vec{n} \times \operatorname{curl} \operatorname{curl} V_{\Omega_{j}}(\vec{n} \times \vec{u})\right)\left(x_{j}\right),
\end{array}\right\}
$$

and, correspondingly, for $u \in C^{\infty}(\Gamma)$

$$
\left.\begin{array}{rl}
V_{j} u(x) & :=-2 \int_{\Gamma} y(y) \Phi_{j}(x, y) d o(y)  \tag{4.6}\\
K_{j} u(x) & :=-2 \int_{\Gamma} u(y) \partial_{n(y)} \Phi_{j}(x, y) d o(y) \\
K_{j}^{\prime} u(x) & :=-2 \int_{\Gamma} u(y) \partial_{n(x)} \Phi_{j}(x, y) d o(x)
\end{array}\right\}
$$

Using the well-known jump relations for smooth layers ([10], [2]) and approximating the Cauchy data in $\mathscr{H}^{0}$ by smooth functions, we find for the traces of the potential (4.4) a system of second kind Fredholm integral equations on the boundary $\Gamma$ :

$$
\begin{align*}
\left.2(-1)^{j}(-\vec{n} \times(\vec{n} \times \vec{u}))\right|_{\Gamma} & =\left((-1)^{j}-\vec{K}_{j}\right) \vec{v}-\vec{n} \times\left(\vec{n} \times V_{j}(\vec{n} \psi)\right)+V_{j} \vec{\psi}+\operatorname{grad}_{\mathrm{T}} V_{j} v, \\
\left.2(-1)^{j} \operatorname{div} \vec{u}\right|_{\Gamma} & =\left((-1)^{j}-K_{j}\right) \psi+V_{j} \operatorname{div}_{\mathrm{T}} \vec{\psi}-k_{j}^{2} V_{j} v, \\
\left.2(-1)^{j}(-\vec{n} \times \operatorname{curl} \vec{u})\right|_{\Gamma} & =D_{j} \vec{v}-\vec{n} \times \operatorname{curl} V_{j}(\vec{n} \psi)+(-1)^{j} \vec{\psi}-\vec{n} \times \vec{K}_{j}(\vec{n} \times \vec{\psi}), \\
2(-1)^{i} \vec{n} .\left.\vec{u}\right|_{\Gamma} & =-\vec{n} . \operatorname{curl} V_{j}(\vec{n} \times \vec{v})+\vec{n} . V_{j}(\vec{n} \psi)+\vec{n} . V_{j} \vec{\psi}+\left((-1)^{j}+K_{j}^{\prime}\right) v . \tag{4.7}
\end{align*}
$$

The right-hand side of (4.7) defines (up to a factor $2(-1)^{j}$ ) the Calderon projection operator $\tilde{C}_{j}$ (cf. Lemma 2.1 and equation (2.24)) for the problem (3.6), (3.18), (3.8). Thus it is a matrix of pseudodifferential operators whose principal symbol we shall now compute. As is known from the calculus of pseudodifferential operators, the principal symbol gives easy criteria for continuity of the operators in Sobolev spaces, for their ellipticity (Fredholm properties) and also strong ellipticity. By introducing a basis of orthonormal coordinates in the cotangent bundle $T^{*}(\Gamma)$ (see $[7, \mathrm{p} .255]$ ), for the pseudodifferential operators on the closed, smooth, bounded manifold $\Gamma$ we obtain the same principal symbols as in the half-space case. Thus we may simply assume that $\Gamma$ is a plane. Then the principal symbols of the pseudodifferential operators in (4.7) are easily obtained by use of Fourier transformation.
Let $\Omega_{1}$ coincide with $\mathbb{R}_{3}^{-}:=\left\{x \in \mathbb{R}^{3} \mid x=\left(x_{1}, x_{2}, x_{3}\right), x_{3}<0\right\}$ and $\Omega$ with $\mathbb{R}_{3}^{+}:=\left\{x \in \mathbb{R}^{3} \mid x_{3}>0\right\}$ and $\vec{n}=(0,0,1)$, yielding $\vec{n} \times \vec{a}=\left(-a_{2}, a_{1}\right)$ for any vector $\vec{a}=\left(a_{1}, a_{2}, a_{3}\right) \in \mathbb{R}^{3}$.
In the following lemma we list the principal symbols of those pseudodifferential operators on $\Gamma$ which arise in our solution procedure. The orders of the operators are those given by Lemma 2.1 , namely $-1,0$, or +1 , respectively. Thus, for example, the operator $\vec{K}_{j}$ has a vanishing principal symbol, because in our Agmon-Douglis-Nirenberg-elliptic system (4.7), $\vec{K}_{j}$ is considered as an operator of order 0 , whereas it is in fact a pseudodifferential operator of order -1 .

Lemma 4.5. For any $\xi \in \mathbb{R}^{2}, \xi \neq(0,0)$ with $|\xi|=\sqrt{\xi_{1}^{2}+\xi_{2}^{2}}$ for the principal symbols $\sigma_{m}$ of order $m$ there holds:

$$
\begin{aligned}
\sigma_{-1}\left(V_{j}\right)(\xi) & =-\frac{1}{|\xi|} ; \quad \sigma_{0}\left(K_{j}\right)(\xi)=0=\sigma_{0}\left(K_{j}^{\prime}\right)(\xi) ; \quad \sigma_{0}(\vec{n} \times \cdot)(\xi)=\left(\begin{array}{cc}
0 & -1 \\
1 & 0
\end{array}\right) \\
\sigma_{1}\left(\operatorname{grad}_{\mathrm{T}}\right)(\xi) & =i\binom{\xi_{1}}{\xi_{2}} ; \quad \sigma_{1}(\vec{n} \cdot \operatorname{curl})(\xi)=i\left(-\xi_{2}, \xi_{1}\right) ; \quad \sigma_{1}\left(\operatorname{div}_{\mathrm{T}}\right)(\xi)=i\left(\xi_{1}, \xi_{2}\right) \\
\sigma_{1}\left(D_{j}\right)(\xi) & =-\frac{1}{|\xi|}\left(\begin{array}{cc}
\xi_{2}^{2} & -\xi_{1} \xi_{2} \\
-\xi_{1} \xi_{2} & \xi_{1}^{2}
\end{array}\right) ; \quad \sigma_{0}\left(-\vec{n} \times \operatorname{curl} V_{j} \vec{n} \cdot\right)(\xi)=\frac{i}{|\xi|}\binom{\xi_{1}}{\xi_{2}} \\
\sigma_{0}\left(\vec{K}_{j}\right)(\xi) & =\left(\begin{array}{ll}
0 & 0 \\
0 & 0
\end{array}\right)
\end{aligned}
$$

$$
\begin{aligned}
\sigma_{0}\left(-\vec{n} \times \operatorname{curl} V_{j} \vec{n} \operatorname{div}_{\mathrm{T}}\right)(\xi) & =-\frac{1}{|\xi|}\left(\begin{array}{cc}
\xi_{1}^{2} & \xi_{1} \xi_{2} \\
\xi_{1} \xi_{2} & \xi_{2}^{2}
\end{array}\right) \\
& =\sigma_{0}\left(-\operatorname{grad}_{\mathrm{T}} \vec{n} \cdot \operatorname{curl} V_{j}(\vec{n} \times \cdot)\right)(\xi) \\
& =-\sigma_{0}\left(-\operatorname{grad}_{\mathrm{T}} \vec{n} \cdot V_{j} \vec{n} \operatorname{div}_{\mathrm{T}}\right)(\xi)
\end{aligned}
$$

Proof. The general calculus of pseudodifferential operators ([7], [27]) shows that the pseudodifferential operators on a smooth manifold $\Gamma$ have the same principal symbols as the corresponding operators of the half-space case. Furthermore, exchanging points of integration and restriction in the boundary integral operators causes perturbations of lower order only. In particular, we know from [19] that $W_{j} \vec{u}:=\vec{n} V_{j}(\vec{n} \cdot \vec{u})-V_{j}(\vec{n} \cdot \vec{n}) \vec{u}$ defines a pseudodifferential operator of order -2 . Similarly, $\sigma_{-1}\left(\vec{n} \times V_{j}(\vec{n} \cdot)\right)(\xi)=\sigma_{-1}\left(V_{j}(\vec{n} \times(\vec{n} \cdot))\right)(\xi)=0$.

From [13] and [19], $\sigma_{-1}\left(V_{j}\right)(\xi)=-1 /|\xi|$ follows by taking the Fourier transform of the fundamental solution of the Laplacian $1 /(4 \pi|x-y|)$ which is the leading term in the Taylor series expansion of (4.2). From the identity $\Delta \vec{u}=\operatorname{grad} \operatorname{div} \vec{u}-$ curl curl $\vec{u}$ we obtain, for any smooth tangential field $\vec{v}$,

$$
D_{j} \vec{v}=k_{j}^{2}\left(\vec{n} \times V_{j}(\vec{n} \times \vec{v})\right)+\vec{n} \times \operatorname{grad} V_{j} \operatorname{div}_{\mathrm{T}}(\vec{n} \times \vec{v})
$$

Thus

$$
\sigma_{1}\left(D_{j}\right)(\xi)=\sigma_{1}\left(\vec{n} \times \operatorname{grad}_{\mathrm{T}}\right)(\xi) \cdot \sigma_{-1}\left(V_{j}\right)(\xi) \cdot \sigma_{1}\left(\operatorname{div}_{\mathrm{T}}(\vec{n} \times \cdot)\right)(\xi)
$$

yields the result for $\sigma_{1}\left(D_{j}\right)(\xi)$. The other symbols are computed similarly.
Applying the general results of Section 2, we see that the Calderón projector from the system (4.7) has the form

$$
\begin{equation*}
\tilde{C}_{j}=\frac{1}{2}\left(1+(-1)^{j} A_{j}\right) \tag{4.8}
\end{equation*}
$$

where the operator $A_{j}$ is given by

$$
A_{j}\left(\begin{array}{c}
\vec{v}  \tag{4.9}\\
\psi \\
\vec{\psi} \\
v
\end{array}\right)=\left(\begin{array}{c}
-\vec{K}_{j} \vec{v}+\left(V_{j}(\vec{n} \psi)\right)_{\mathrm{T}}+V_{j} \vec{\psi}+\operatorname{grad}_{\mathrm{T}} V_{j} v \\
-K_{j} \psi+V_{j} \operatorname{div}_{\mathrm{T}} \vec{\psi}-k_{j}^{2} V_{j} v \\
D_{j} \vec{v}-\vec{n} \times \operatorname{curl} V_{j}(\vec{n} \psi)-\vec{n} \times \vec{K}_{j}(\vec{n} \times \vec{\psi}) \\
-\vec{n} . \operatorname{curl} V_{j}(\vec{n} \times \vec{v})+\vec{n} . V_{j}(\vec{n} \psi)+\vec{n} . V_{j} \vec{\psi}+K_{j}^{\prime} v
\end{array}\right) .
$$

The operator $H$ from (2.25) is given by

$$
\begin{equation*}
H=\tilde{C}_{1}-\tilde{C}_{2}=-\frac{1}{2}\left(A_{1}+A_{2}\right) \tag{4.10}
\end{equation*}
$$

Hence with Lemma 4.5 its principal symbol is given by

$$
\sigma(H)(\xi)=-\sigma\left(A_{j}\right)(\xi)=\frac{1}{|\xi|}\left(\begin{array}{cccccc}
0 & 0 & 0 & 1 & 0 & i \xi_{1}  \tag{4.11}\\
0 & 0 & 0 & 0 & 1 & i \xi_{2} \\
0 & 0 & 0 & i \xi_{1} & i \xi_{2} & 0 \\
\xi_{2}^{2} & -\xi_{1} \xi_{2} & -i \xi_{1} & 0 & 0 & 0 \\
-\xi_{1} \xi_{2} & \xi_{1}^{2} & -i \xi_{2} & 0 & 0 & 0 \\
-i \xi_{1} & -i \xi_{2} & 1 & 0 & 0 & 0
\end{array}\right)
$$

Thus, $H: \mathscr{H}^{s} \rightarrow \mathscr{H}^{s}$ is continuous for any real $s$ where

$$
\mathscr{H}^{s}:=T H^{s+\frac{1}{2}}(\Gamma) \times H^{s-\frac{1}{2}}(\Gamma) \times T H^{s-\frac{1}{2}}(\Gamma) \times H^{s+\frac{1}{2}}(\Gamma) .
$$

We remark that the off-diagonal blocks of $\sigma(H)(\xi)$ in (4.11), namely the matrices

$$
E=\frac{1}{|\xi|}\left(\begin{array}{ccc}
1 & 0 & i \xi_{1}  \tag{4.12}\\
0 & 1 & i \xi_{2} \\
i \xi_{1} & i \xi_{2} & 0
\end{array}\right), \quad M=\frac{1}{|\xi|}\left(\begin{array}{ccc}
\xi_{2}^{2} & -\xi_{1} \xi_{2} & -i \xi_{1} \\
-\xi_{1} \xi_{2} & \xi_{1}^{2} & -i \xi_{2} \\
-i \xi_{1} & -i \xi_{2} & 1
\end{array}\right),
$$

are also the principal symbols of the integral operators which arise via the direct method for the "electric" and "magnetic" boundary value problems, respectively [25], [24].
The natural duality on $\mathscr{H}^{0}$ is given by

$$
\left(\left(\begin{array}{c}
\vec{v}  \tag{4.13}\\
\psi \\
\vec{\psi} \\
v
\end{array}\right),\left(\begin{array}{c}
\vec{w} \\
\chi \\
\vec{\chi} \\
w
\end{array}\right)\right)_{\mathscr{O}}:=\int_{\Gamma}\{\overline{\vec{v}} \cdot \vec{\chi}+\bar{\psi} w+\overrightarrow{\vec{\psi}} \cdot \vec{w}+\bar{v} \chi\} d o
$$

for smooth elements in $\mathscr{H}^{0}$ (cf. (2.35)); this also corresponds to Green's formula (3.25).

Therefore, with respect to this sesquilinear form, the operator $H$ in (4.10) is strongly elliptic, i.e. satisfies a Gårding inequality, if and only if the matrices $E$ and $M$ in (4.12) define positive definite quadratic forms on $\mathbb{C}^{3}$, i.e. their selfadjoint parts are positive definite matrices. That this is not the case can easily be seen as follows: from equations (4.11)-(4.13) we see that in the half-space case, i.e. on the symbol level, there holds for $\Psi:=(\vec{v}, \psi, \vec{\psi}, v)^{\top}$,

$$
\begin{equation*}
(\Psi, H \Psi)_{\mathscr{H}^{0}}=\int\left\{\overline{(\vec{v}, \psi)} M\binom{\vec{v}}{\psi}+\overline{(\vec{\psi}, v)} E\binom{\vec{\psi}}{v}\right\} d \xi_{1} d \xi_{2} . \tag{4.14}
\end{equation*}
$$

Furthermore, the selfadjoint parts of both $M$ and $E$ are singular matrices:

$$
\frac{1}{2}\left(E+\overline{E^{\top}}\right)=\frac{1}{|\xi|}\left(\begin{array}{lll}
1 & 0 & 0 \\
0 & 1 & 0 \\
0 & 0 & 0
\end{array}\right), \quad \frac{1}{2}\left(M+\overline{M^{\top}}\right)=\frac{1}{|\xi|}\left(\begin{array}{ccc}
\xi_{2}^{2} & -\xi_{1} \xi_{2} & 0 \\
-\xi_{1} \xi_{2} & \xi_{2}^{2} & 0 \\
0 & 0 & 1
\end{array}\right) .
$$

Note that the matrices $E$ and $M$ themselves are non-singular which corresponds to the ellipticity of the corresponding pseudodifferential operator. Likewise, the operator $H$ in (4.10) is an elliptic pseudodifferential operator and hence a Fredholm operator in the space $\mathscr{H}^{s}, s \in \mathbb{R}$.
Thus, using standard arguments from the calculus of elliptic pseudodifferential operators, one can derive a priori estimates for $H$ and thus obtain regularity results for the solution $\Psi \in \mathscr{H}^{s}$ of the system

$$
\begin{equation*}
H \Psi:=-\frac{1}{2}\left(A_{1}+A_{2}\right) \Psi=\frac{1}{2}\left(1-A_{2}\right) \Psi_{0} \tag{4.15}
\end{equation*}
$$

for given $\Psi_{0} \in \mathscr{H}^{s}$ with $A_{j}$ in (4.9), $j=1,2$.

We note that equation (4.15) follows from (2.22)-(2.25) together with the Calderon projector (4.8). Therefore, application of Theorem 2.4 shows that the solution of (4.15) is the set of the Cauchy data of the refracted field in (3.6), (3.18) (see also [25], [4]).

According to the general results in [23], the least squares method for (4.15) - with regular finite elements on the interface manifold $\Gamma$ - converges with quasi-optimal order. However, its convergence rate is considerably smaller compared with that of the Galerkin method. Therefore, we are more interested in a suitable Galerkin procedure. Unfortunately, $H$ is not strongly elliptic with respect to the energy form $(\cdot, \cdot)_{\mathscr{H}}$ in (4.13), as we have shown above. But strong ellipticity is necessary and sufficient for the convergence of general Galerkin procedures [12], [28], [29], [30].

In order to obtain a strongly elliptic boundary integral operator for the transmission problem (3.6), (3.18), (3.8), we modify the Cauchy data as in (3.26) and insert them into the system (4.7). For the new Cauchy data

$$
\begin{equation*}
\Psi^{\prime}:=\left(\vec{v}, \psi^{\prime}, \vec{\psi}^{\prime}, v\right)^{\top} \in \mathscr{H}^{0}, \quad \psi^{\prime}:=\psi-\operatorname{div}_{\mathrm{T}} \vec{v}, \quad \vec{\psi}^{\prime}:=\vec{\psi}+\operatorname{grad}_{\mathrm{T}} v \tag{4.16}
\end{equation*}
$$

with $\vec{v}, \psi, \vec{\psi}, v$ as in Definition 4.1, the system (4.7) takes the form

$$
\left.\begin{array}{rl}
2(-1)^{j} \vec{v}= & \left((-1)^{j}-\vec{K}_{j}\right) \vec{v}+\left(V_{j}\left(\vec{n} \operatorname{div}_{\mathrm{T}} \vec{v}\right)\right)_{\mathrm{T}}+\left(V_{j}\left(\vec{n} \psi^{\prime}\right)\right)_{\mathrm{T}} \\
& +V_{j} \vec{\psi}^{\prime}-V_{j} \operatorname{grad}_{\mathrm{T}} v+\operatorname{grad}_{\mathrm{T}} V_{j} v, \\
2(-1)^{j} \psi^{\prime}= & \left.L_{j} \vec{v}+\left((-1)^{j}-K_{j}\right) \psi^{\prime}-\operatorname{div}_{\mathrm{T}}\left(V_{j} \vec{n} \psi^{\prime}\right)\right)_{\mathrm{T}} \\
& +V_{j} \operatorname{div}_{\mathrm{T}} \vec{\psi}^{\prime}-\operatorname{div}_{\mathrm{T}} V_{j} \vec{\psi}^{\prime}+M_{j} v, \\
2(-1)^{j} \vec{\psi}^{\prime}= & N_{j} \vec{v}+\operatorname{grad}_{\mathrm{T}} \vec{n} \cdot V_{j}\left(\vec{n} \psi^{\prime}\right)-\vec{n} \times \operatorname{curl} V_{j}\left(\vec{n} \psi^{\prime}\right)  \tag{4.17}\\
& +(-1)^{j} \vec{\psi}^{\prime}-\vec{n} \times \vec{K}_{j}\left(\vec{n} \times \vec{\psi}^{\prime}\right)+\operatorname{grad}_{\mathrm{T}} \vec{n} \cdot V_{j} \vec{\psi}^{\prime}+R_{j} v, \\
2(-1)^{j} v= & -\vec{n} \cdot \operatorname{curl} V_{j}(\vec{n} \times \vec{v})+\vec{n} \cdot V_{j}\left(\vec{n} \operatorname{div}_{\mathrm{T}} \vec{v}\right) \\
& +\vec{n} \cdot V_{j}\left(\vec{n} \psi^{\prime}\right)+\vec{n} \cdot V_{j} \vec{\psi}^{\prime}-\vec{n} \cdot V_{j} \operatorname{grad}_{\mathrm{T}} v+\left((-1)^{j}+K_{j}^{\prime}\right) v,
\end{array}\right\}
$$

with

$$
\left.\begin{array}{rl}
L_{j} \vec{v}: & =\operatorname{div}_{\mathrm{T}} K_{j} \vec{v}-K_{j} \operatorname{div}_{\mathrm{T}} \vec{v}-\operatorname{div}\left(V_{j}\left(\vec{n} \operatorname{div}_{\mathrm{T}} \vec{v}\right)\right)_{\mathrm{T}},  \tag{4.18}\\
M_{j} v:= & \operatorname{div}_{\mathrm{T}} V_{j} \operatorname{grad}_{\mathrm{T}} v-V_{j} \operatorname{div}_{\mathrm{T}} \operatorname{grad}_{\mathrm{T}} v-k_{j}^{2} V_{j} v-\operatorname{div}_{\mathrm{T}} \operatorname{grad}_{\mathrm{T}} V_{j} v, \\
N_{j} \vec{v}:= & D_{j} \vec{v}-\vec{n} \times \operatorname{curl} V_{j}\left(\vec{n} \operatorname{div}_{\mathrm{T}} \vec{v}\right) \\
& +\operatorname{grad}_{\mathrm{T}}\left(-\vec{n} \cdot \operatorname{curl} V_{j}(\vec{n} \times \vec{v})\right)+\operatorname{grad}_{\mathrm{T}} \vec{n} \cdot V_{j}\left(\vec{n} \operatorname{div}_{\mathrm{T}} \vec{v}\right), \\
R_{j} v:= & \vec{n} \times K_{j}\left(\vec{n} \times \operatorname{grad}_{\mathrm{T}} v\right)-\operatorname{grad}_{\mathrm{T}} \vec{n} \cdot V_{j} \operatorname{grad}_{\mathrm{T}} v+\operatorname{grad}_{\mathrm{T}} K_{j}^{\prime} v .
\end{array}\right\}
$$

Therefore the operator $H^{\prime}$ from (2.25) has the form

$$
\begin{equation*}
H^{\prime}=-\frac{1}{2}\left(A_{1}^{\prime}+A_{2}^{\prime}\right), \tag{4.19}
\end{equation*}
$$

where

$$
\begin{align*}
& A_{j}^{\prime}\left(\begin{array}{c}
\vec{v} \\
\psi^{\prime} \\
\vec{\psi}^{\prime} \\
v
\end{array}\right) \\
= & \left(\begin{array}{c}
-\vec{K}_{j} \vec{v}+\left(V_{j}\left(\vec{n} \operatorname{div}_{\mathrm{T}} \vec{v}\right)\right)_{\mathrm{T}}+\left(V_{i}\left(\vec{n} \psi^{\prime}\right)\right)_{\mathrm{T}}+V_{j} \vec{\psi}^{\prime}-V_{j} \operatorname{grad}_{\mathrm{T}} v+\operatorname{grad}_{\mathrm{T}} V_{j} v \\
\left.L_{j} \vec{v}-K_{j} \psi^{\prime}-\operatorname{div}_{\mathrm{T}}\left(V_{j} \vec{n} \psi^{\prime}\right)\right)_{\mathrm{T}}+V_{j} \operatorname{div}_{\mathrm{T}} \vec{\psi}^{\prime}-\operatorname{div}_{\mathrm{T}} V_{j} \vec{\psi}^{\prime}+M_{j} v \\
N_{j} \vec{v}+\operatorname{grad}_{\mathrm{T}} \vec{n} \cdot V_{j}\left(\vec{n} \psi^{\prime}\right)-\vec{n} \times \operatorname{curl} V_{j}\left(\vec{n} \psi^{\prime}\right) \\
-\vec{n} \times \vec{K}_{j}\left(\vec{n} \times \vec{\psi}^{\prime}\right)+\operatorname{grad}_{\mathrm{T}} \vec{n} \cdot V_{j} \vec{\psi}^{\prime}+R_{j} v \\
-\vec{n} \cdot \operatorname{curl} V_{j}(\vec{n} \times \vec{v})+\vec{n} \cdot V_{j}\left(\vec{n} \operatorname{div}_{\mathrm{T}} \vec{v}\right)+\vec{n} \cdot V_{j}\left(\vec{n} \psi^{\prime}\right) \\
+\vec{n} \cdot V_{j} \vec{\psi}^{\prime}-\vec{n} \cdot V_{j} \operatorname{grad}_{\mathrm{T}} v+K_{j}^{\prime} v
\end{array}\right) . \tag{4.20}
\end{align*}
$$

Hence with Lemma 4.5 and equation (4.11) the principal symbol of $H^{\prime}$ is given by

$$
\sigma\left(H^{\prime}\right)(\xi)=\frac{1}{|\xi|}\left(\begin{array}{cccccc}
0 & 0 & 0 & 1 & 0 & 0  \tag{4.21}\\
0 & 0 & 0 & 0 & 1 & 0 \\
0 & 0 & 0 & 0 & 0 & |\xi|^{2} \\
|\xi|^{2} & 0 & 0 & 0 & 0 & 0 \\
0 & |\xi|^{2} & 0 & 0 & 0 & 0 \\
0 & 0 & 1 & 0 & 0 & 0
\end{array}\right)
$$

The principal symbol shows that $H^{\prime}$ is continuous from $\mathscr{H}^{s}$ into itself for any real $s$. Furthermore, its off-diagonal blocks

$$
E^{\prime}=\left(\begin{array}{ccc}
|\xi|^{-1} & 0 & 0  \tag{4.22}\\
0 & |\xi|^{-1} & 0 \\
0 & 0 & |\xi|
\end{array}\right), \quad M^{\prime}=\left(\begin{array}{ccc}
|\xi| & 0 & 0 \\
0 & |\xi| & 0 \\
0 & 0 & |\xi|^{-1}
\end{array}\right)
$$

obviously define positive quadratic forms on $\mathbb{C}^{3}$. We note that $E^{\prime}$ and $M^{\prime}$ are used in [25], [24] to derive the "edge behaviour" of the "electric" and the "magnetic" fields, respectively, since the components of the fields are decoupled in first order, i.e. they are only coupled via compact perturbations in (4.20).

From standard results on pseudodifferential operators [27], [30] we deduce that the form (4.21) of the principal symbol $\sigma\left(H^{\prime}\right)$ implies the coerciveness of $H^{\prime}$ in the sense of a Gårding inequality in $\mathscr{H}^{0}$.

Lemma 4.6. There exists a real $\gamma>0$ such that (with the duality (4.13))

$$
\begin{equation*}
\operatorname{Re}\left(\Psi, H^{\prime} \Psi\right)_{\mathscr{H}^{0}} \geqq \gamma\|\Psi\|_{\mathscr{H}^{0}}^{2}-|k(\Psi, \Psi)| \tag{4.23}
\end{equation*}
$$

for all $\Psi \in \mathscr{H}^{0}$ with a compact bilinear form $k(\cdot, \cdot)$ on $\mathscr{H}^{0} \times \mathscr{H}^{0}$.
Proof. The arguments following (4.13) show that in the half-space case (4.14) holds with $E^{\prime}$ and $M^{\prime}$ instead of $E$ and $M$ yielding (4.23) due to (4.22). The
compact bilinear form $k(\cdot, \cdot)$ arises in (4.23) since $H^{\prime}$ acts on functions on a bounded manifold $\Gamma$ which causes a compact perturbation to the half-space situation.

Now we concentrate on the connection between our strongly elliptic pseudodifferential operator $H^{\prime}$ and the original interface problem (3.6), (3.18), (3.8). Following (2.22)-(2.25), for (3.6), (3.18), (3.8) we obtain the system of integral equations

$$
\begin{equation*}
H^{\prime} \Psi^{\prime}=-\left(1-\tilde{C}_{2}^{\prime}\right) \Psi_{0}^{\prime} \quad \text { with } \quad H^{\prime}:=\tilde{C}_{1}^{\prime}-\tilde{C}_{2}^{\prime}, \tag{4.24}
\end{equation*}
$$

where $\Psi_{0}^{\prime}:=\left(\vec{v}_{0}, \psi_{0}^{\prime}, \vec{\psi}^{\prime}, v_{0}\right)^{\top}$ are the modified Cauchy data (4.16) of the incident field $\vec{u}_{0}$ and $\bar{C}_{j}^{\prime}=\frac{1}{2}\left(1+(-1)^{i} A_{j}^{\prime}\right)$ is the Calderón projector (corresponding to the wave number $k_{j}$ ) of $A_{j}^{\prime}$ in (4.20). Application of Theorem 2.4 to (4.24) yields the following equivalence between the transmission problem (3.6), (3.18), (3.8) and the boundary integral equations (4.24). (The proof is identical to the proof of Theorem 2.4 and is therefore omitted.)
Theorem 4.7. Let $\vec{u}_{0} \in \mathscr{H}^{s}$ be given.
(i) If $\vec{u}_{j} \in L_{j}(j=1,2)$ as defined in (4.1) solve the transmission problem (3.6), (3.18), (3.8), then

$$
\left(\left(\vec{u}_{1}\right)_{T}, \operatorname{div} \vec{u}_{1}-\operatorname{div}_{T}\left(\vec{u}_{1}\right)_{T},-\vec{n} \times \operatorname{curl} \vec{u}_{1}+\operatorname{grad}_{T}\left(\vec{n} \cdot \vec{u}_{1}\right), \vec{n} \cdot \vec{u}_{1}\right)^{\top} \in \mathscr{H}^{s}
$$

solves the equation (4.24).
(ii) If $\Psi^{\prime}:=\left(\vec{v}, \psi^{\prime}, \vec{\psi}^{\prime}, v\right)^{\top} \in \mathscr{H}^{s}$ solves (4.24) with $\Psi_{0}^{\prime}:=\left(\vec{v}_{0}, \psi_{0}^{\prime}, \vec{\psi}_{0}^{\prime}, v_{0}\right)^{\top}$, i.e.

$$
-\frac{1}{2}\left(A_{1}^{\prime}+A_{2}^{\prime}\right) \Psi^{\prime}=\frac{1}{2}\left(A_{2}^{\prime}-1\right) \Psi_{0}^{\prime}
$$

then with

$$
\begin{equation*}
\Psi_{1}^{\prime}:=\tilde{C}_{1}^{\prime} \Psi^{\prime}, \quad \Psi_{2}^{\prime}:=\tilde{C}_{2}^{\prime}\left(\Psi^{\prime}+\Psi_{0}^{\prime}\right) \tag{4.25}
\end{equation*}
$$

and

$$
\begin{equation*}
\vec{u}_{j}:=K_{j} \mathscr{P}_{j} R_{j}^{-1} \Psi_{j}^{\prime} \quad \text { in } \Omega_{j} \quad(\text { see }(2.18)), \tag{4.26}
\end{equation*}
$$

$\vec{u}_{j} \in L_{j}$ solve the transmission problem (3.6), (3.18), (3.8).
Remark. In (4.26), $\vec{u}_{j}$ is given by the Stratton-Chu formula (4.4) applied to ( $\vec{v}_{j}, \psi_{j}, \vec{\psi}_{j}, v_{j}$ ) which are connected with $\Psi_{j}^{\prime}$ via (4.16), (3.27), (3.28). By Gårding's inequality (4.23), $H^{\prime}$ is a Fredholm operator of index zero from $\mathscr{H}^{0}$ into itself and thus also from $\mathscr{H}^{s}$ into itself for any $s$. Therefore we obtain existence of a solution of (4.24) as soon as we know its uniqueness, and Theorem 4.7 then implies the existence of a solution of the transmission problem. For the question of unique solvability of the transmission problem (3.6), (3.18), (3.8) and therefore of our boundary integral equation (4.24) we refer to $[\mathbf{2 , 4 , 1 5}, \mathbf{2 0}, \mathbf{2 5}]$. In the case of the "physical" transmission conditions (3.7), we discuss this question in more detail in Section 5. From the discussion in [4] and [25] we have the following result:

Proposition 4.8. Assume that the homogeneous transmission problem (3.6), (3.18), (3.8) and an associated homogeneous adjoint problem with interchanged wave numbers have only the trivial solution in $L_{j}$ (defined in (4.1)). Then for given $\Psi_{0} \in \mathscr{H}^{s}$ there exists exactly one solution $\Psi^{\prime} \in \mathscr{H}^{s}$ of the integral equation (4.24) yielding exactly one solution of (3.6), (3.18), (3.8) via (4.26).

## 5. Integral equations for the electromagnetic transmission problem

In this section we study the integral equations corresponding to the "physical" transmission conditions (3.7). Instead of repeating all the arguments of the preceding section, we only point out the necessary modifications.
We define, according to (3.7), the "physical" Cauchy data on $\Gamma$ :

$$
\left.\begin{array}{cl}
\tilde{v}_{j}:=\varepsilon_{j} v_{j}=\varepsilon_{j} \vec{n} \cdot \vec{u}_{j} ; \quad \vec{v}_{j}=\vec{u}_{j} ;  \tag{5.1}\\
\tilde{\psi}_{j}:=\lambda_{j} \psi_{j}=\lambda_{j} \operatorname{div} \vec{u}_{j} ; \quad & \vec{\psi}_{j}:=\frac{1}{\mu_{j}} \vec{\psi}_{j}=-\frac{1}{\mu_{j}} \times \operatorname{curl} \vec{u}_{j} .
\end{array}\right\}
$$

We want to use the results of the previous section. Therefore we write

$$
\Psi:=(\vec{v}, \psi, \vec{\psi}, v)^{\top} ; \quad \tilde{\Psi}_{j}:=\left(\tilde{v}_{j}, \tilde{\psi}_{j}, \overrightarrow{\tilde{\psi}}_{j}, \tilde{v}_{j}\right)^{\top} .
$$

Thus, with the obvious block notation, we have

$$
\begin{equation*}
\tilde{\Psi}_{j}=B_{j} \Psi ; \quad B_{j}=\operatorname{diag}\left(1, \lambda, \frac{1}{\mu_{j}}, \varepsilon_{j}\right) . \tag{5.2}
\end{equation*}
$$

Now we can insert these Cauchy data into the representation formula as before and obtain, instead of (4.8), the Calderón projectors

$$
\begin{equation*}
\tilde{C}_{j}=\frac{1}{2}\left(1+(-1)^{j} \tilde{A}_{j}\right) ; \quad \bar{A}_{j}=B_{j} A_{j} B_{j}^{-1} . \tag{5.3}
\end{equation*}
$$

The boundary integral operators $A_{j}$ are given explicitly in (4.9). The procedure described in the previous section then leads to a boundary integral equation corresponding to (2.25). The matrix of integral operators is given by

$$
\begin{equation*}
\tilde{H}=\tilde{C}_{1}-\tilde{C}_{2}=-\frac{1}{2}\left(\tilde{A}_{1}+\tilde{A}_{2}\right)=-\frac{1}{2}\left(B_{1} A_{1} B_{1}^{-1}+B_{2} A_{2} B_{2}^{-1}\right) . \tag{5.4}
\end{equation*}
$$

From Lemma 4.5 and (4.11) we find the principal symbol (in block form)

$$
\sigma(\tilde{H})(\xi)=\left(\begin{array}{cc}
0 & \tilde{E}  \tag{5.5}\\
\tilde{M} & 0
\end{array}\right)
$$

with

$$
\tilde{E}=\frac{1}{|\xi|}\left(\begin{array}{ccc}
\mu_{e} & 0 & i \xi_{1} \varepsilon_{e}  \tag{5.6}\\
0 & \mu_{e} & i \xi_{2} \varepsilon_{e} \\
i \xi_{1} \lambda_{e} & i \xi_{2} \lambda_{e} & 0
\end{array}\right), \quad \tilde{M}=\frac{1}{|\xi|}\left(\begin{array}{ccc}
\xi_{2}^{2} \mu_{m} & -\xi_{1} \xi_{2} \mu_{m} & -i \xi_{1} \lambda_{m} \\
-\xi_{1} \xi_{2} \mu_{m} & \xi_{1}^{2} \mu_{m} & -i \xi_{2} \lambda_{m} \\
-i \xi_{1} \varepsilon_{m} & -i \xi_{2} \varepsilon_{m} & v_{m}
\end{array}\right) .
$$

Here we used the abbreviations

$$
\left.\begin{array}{lll}
\mu_{e}=\frac{1}{2}\left(\mu_{1}+\mu_{2}\right) ; & \varepsilon_{e}=\frac{1}{2}\left(\frac{1}{\varepsilon_{1}}+\frac{1}{\varepsilon_{2}}\right) ; \quad \lambda_{e}=\frac{1}{2}\left(\lambda_{1} \mu_{1}+\lambda_{2} \mu_{2}\right) ; \quad v_{e}=\frac{1}{2}\left(\frac{\lambda_{1}}{\varepsilon_{1}}+\frac{\lambda_{2}}{\varepsilon_{2}}\right) ; \\
\mu_{m}=\frac{1}{2}\left(\frac{1}{\mu_{1}}+\frac{1}{\mu_{2}}\right) ; \quad \varepsilon_{m}=\frac{1}{2}\left(\varepsilon_{1}+\varepsilon_{2}\right) ; \quad \lambda_{m}=\frac{1}{2}\left(\frac{1}{\lambda_{1} \mu_{1}}+\frac{1}{\lambda_{2} \mu_{2}}\right) ; \quad v_{m}=\frac{1}{2}\left(\frac{\varepsilon_{1}}{\lambda_{1}}+\frac{\varepsilon_{2}}{\lambda_{2}}\right) . \tag{5.7}
\end{array}\right\}
$$

Again, as in the previous section, the matrices $\tilde{E}$ and $\tilde{M}$ are, in general, not positive, hence the operator $\tilde{H}$ will not be strongly elliptic. Therefore we modify
the Cauchy data (5.1) analogously to (3.26), (4.16):

$$
\tilde{\Psi}_{j}^{\prime}:=\left(\vec{v}_{j}, \tilde{\psi}_{j}^{\prime}, \overrightarrow{\tilde{\psi}}_{j}^{\prime}, \tilde{v}_{j}^{\prime}\right)^{\top}
$$

with

$$
\left.\begin{array}{l}
\tilde{\psi}_{j}^{\prime}:=\eta \tilde{\psi}_{j}-\operatorname{div}_{\mathrm{T}} \overrightarrow{\tilde{v}}_{j}=\eta \lambda_{j} \psi_{j}^{\prime}+\left(\eta \lambda_{j}-1\right) \operatorname{div}_{\mathrm{T}} \vec{v}_{j}=\eta \lambda_{j} \psi_{j}-\operatorname{div}_{\mathrm{T}} \vec{v}_{j} ;  \tag{5.8}\\
\vec{\psi}_{j}^{\prime}:=\vec{\psi}_{j}+\vartheta \operatorname{grad}_{\mathrm{T}} \tilde{v}_{j}=\frac{1}{\mu_{j}} \vec{\psi}_{j}^{\prime}+\left(\vartheta \varepsilon_{j}-\frac{1}{\mu_{j}}\right) \operatorname{grad}_{\mathrm{T}} v_{j}=\frac{1}{\mu_{j}} \vec{\psi}_{j}+\vartheta \varepsilon_{j} \operatorname{grad}_{\mathrm{T}} v_{j} ; \\
\tilde{v}_{j}^{\prime}:=\vartheta \tilde{v}_{j}=\vartheta \varepsilon_{j} v_{j} .
\end{array}\right\}
$$

Here we introduce two new complex parameters $\eta$ and $\vartheta$ which will be fixed later on (see (5.11) and (5.13)). It turns out that they can always be chosen in such a way that the resulting boundary integral operator is strongly elliptic.

It is obvious how to insert these constants into the system of integral equations (4.17). Therefore we need not repeat this explicit representation here. In short notation, the modified system of integral operators is

$$
\begin{equation*}
\tilde{H}^{\prime}=\tilde{C}_{1}^{\prime}-\tilde{C}_{2}^{\prime}=-\frac{1}{2}\left(\tilde{A}_{1}^{\prime}+\tilde{A}_{2}^{\prime}\right)=-\frac{1}{2}\left(B_{1}^{\prime} A_{1}^{\prime} B_{1}^{\prime-1}+B_{2}^{\prime} A_{2}^{\prime} B_{2}^{\prime-1}\right) \tag{5.9}
\end{equation*}
$$

with $A_{j}^{\prime}$ as defined in (4.20) and, according to (5.8),

$$
B_{j}^{\prime}=\left(\begin{array}{cccc}
1 & 0 & 0 & 0 \\
\left(\eta \lambda_{j}-1\right) \operatorname{div}_{\mathrm{T}} & \eta \lambda_{j} & 0 & 0 \\
0 & 0 & \mu_{j}^{-\mathbf{1}} & \left(\vartheta \varepsilon_{j}-\mu_{j}^{-1}\right) \operatorname{grad}_{\mathrm{T}} \\
0 & 0 & 0 & \vartheta \varepsilon_{j}
\end{array}\right)
$$

with the obvious block notation.
For the computation of the principal symbols, we can take advantage of (4.21), (4.22). The result is

$$
\sigma\left(\tilde{H}^{\prime}\right)(\xi)=\left(\begin{array}{cc}
0 & \tilde{E}^{\prime} \\
\tilde{M}^{\prime} & 0
\end{array}\right)
$$

with $\tilde{E}^{\prime}=\frac{1}{2}\left(\tilde{E}_{1}^{\prime}+\tilde{E}_{2}^{\prime}\right) ; \tilde{M}^{\prime}=\frac{1}{2}\left(\tilde{M}_{1}^{\prime}+\tilde{M}_{2}^{\prime}\right)$ and

$$
\tilde{E}_{j}^{\prime}=\frac{1}{|\xi|}\left(\begin{array}{ccc}
\mu_{j} & 0 & i a \xi_{1} \\
0 & \mu_{j} & i a \xi_{2} \\
i b \xi_{1} & i b \xi_{2} & c|\xi|^{2}
\end{array}\right) ; \quad \tilde{M}_{j}^{\prime}=\left(\tilde{E}_{j}^{\prime}\right)^{-1},
$$

where

$$
a=\left(\vartheta \varepsilon_{j}\right)^{-1}-\mu_{j} ; \quad b=\mu_{j}\left(\eta \lambda_{j}-1\right) ; \quad c=a+b+\mu_{j} .
$$

For simplicity, we now make the choices,

$$
\begin{equation*}
\lambda_{j}=\left(\mu_{j} \bar{\varepsilon}_{j}\right)^{-1} \quad \text { (compare case (ii) of Section 3), } \tag{5.10}
\end{equation*}
$$

and

$$
\begin{equation*}
\boldsymbol{\vartheta}=(\bar{\eta})^{-1} \tag{5.11}
\end{equation*}
$$

This gives $b=\bar{a}, c=\bar{c}$; hence, with $d_{j}=2 \operatorname{Re}\left(\bar{\eta} \varepsilon_{j}^{-1}\right)-\mu_{j}, e_{j}=\left|\mu_{j} \bar{\varepsilon}_{j} \eta^{-1}-1\right|^{2}$, one
obtains

$$
\begin{gathered}
\frac{1}{2}\left(\tilde{E}_{j}^{\prime}+\overline{\left(\tilde{E}_{j}^{\prime}\right)^{\top}}\right)=\frac{1}{|\xi|}\left(\begin{array}{ccc}
\mu_{j} & 0 & 0 \\
0 & \mu_{j} & 0 \\
0 & 0 & d_{j}|\xi|^{2}
\end{array}\right) ; \\
\frac{1}{2}\left(\tilde{M}_{j}^{\prime}+\overline{\left(\bar{M}_{j}^{\prime}\right)^{\top}}\right)=\frac{1}{\mu_{j}|\xi|}\left(\begin{array}{ccc}
|\xi|^{2}-e_{j} \xi_{1}^{2} & -e_{j} \xi_{1} \xi_{2} & 0 \\
-e_{j} \xi_{1} \xi_{2} & |\xi|^{2}-e_{j} \xi_{2}^{2} & 0 \\
0 & 0 & \left|\mu_{j} \xi_{j} / \eta\right|^{2}
\end{array}\right) .
\end{gathered}
$$

Because we assumed $\mu_{j}>0$, the positivity of both matrices depends only on the positivity of $d_{j}$.

Lemma 5.1. The operator $\tilde{H}^{\prime}$ is strongly elliptic, i.e. there exists a $\gamma>0$ such that

$$
\begin{equation*}
\operatorname{Re}\left(\Psi, \tilde{H}^{\prime} \Psi\right)_{\mathscr{H}^{0}} \geqq \gamma\|\Psi\|_{\mathscr{R}^{0}}^{2}-|k(\Psi, \Psi)| \tag{5.12}
\end{equation*}
$$

for all $\Psi \in \mathscr{H}^{0}$ with a compact bilinear form $k(\cdot, \cdot)$ on $\mathscr{H}^{0} \times \mathscr{H}^{0}$, if and only if

$$
\left.\begin{array}{l}
2 \operatorname{Re} \bar{\eta}\left(\frac{1}{\varepsilon_{1}}+\frac{1}{\varepsilon_{2}}\right)>\mu_{1}+\mu_{2} \text { and }  \tag{5.13}\\
2 \operatorname{Re} \eta\left(\varepsilon_{1}+\varepsilon_{2}\right)>\mu_{1}\left|\varepsilon_{1}\right|^{2}+\mu_{2}\left|\varepsilon_{2}\right|^{2} .
\end{array}\right\}
$$

Remark. Condition (5.13) can always be satisfied by a suitable choice of $\eta$, under assumption (3.4) and also, for the eddy current problem (see case (iv) in Section 3), even by a large enough real $\eta$.

Let us write the system of integral equations as

$$
\begin{equation*}
\tilde{H}^{\prime} \tilde{\Psi}^{\prime}=-\left(1-\tilde{C}_{2}^{\prime}\right) \tilde{\Psi}_{0}^{\prime} \tag{5.14}
\end{equation*}
$$

We summarise the results of this section in the following theorem.
Theorem 5.2. Let the assumptions (3.4), (5.10), (5.11), and (5.13) for the coefficients be satisfied. Then for given $\Psi_{0}:=\left(\vec{v}_{0}, \psi_{0}, \vec{\psi}_{0}, v_{0}\right)^{\top} \in \mathscr{L}^{0}$, the transmission problem (3.6)-(3.8) has a unique solution $\vec{u}$ with $\vec{u}_{j} \in L_{j}, j=1,2$. This solution corresponds via (5.1), (5.8) to the unique solution $\bar{\Psi}^{\prime} \in \mathscr{H}^{0}$ of the system (5.14) of boundary integral equations. The boundary integral equations are a strongly elliptic system of pseudodifferential equations on $\Gamma$.

## Acknowledgment

We thank the referee for his helpful remarks on the choice of the appropriate transmission conditions. The second author was partially supported by NSF grant DMS 8603954.

## References

1 J. Chazarain and A. Piriou. Introduction à la Thórie des Equations aux Dérivées Partielles Linéaires (Paris: Gauthier-Villars, 1981).
2 P. Colton and R. Kress. Integral Equation Methods in Scattering Theory. Pure and Applied Mathematics (New York: John Wiley, 1983).
3 M. Costabel. Starke Elliptizität von Randintegraloperatoren erster Art (Habilitationsschrift, Technische Hochschule Darmstadt, 1984).

4 M. Costabel and E. P. Stephan. A direct boundary integral equation method for transmission problems. J. Math. Anal. Appl. 106 (1985), 367-413.
5 M. Costabel and W. L. Wendland. Strong ellipticity of boundary integral operators. J. Reine Angew. Math. 372 (1986), 39-63.
6 J. Dieudonné. Eléments d'analyse, Vol. 8 (Paris: Gauthier-Villars, 1978).
7 G. I. Eskin. Boundary Problems for Elliptic Pseudo-Differential Operators. Translations of Mathematical Monographs 52 (Providence, R.I.: American Mathematical Society, 1981).
8 V. Girault and D. A. Raviart. Finite Element Approximation of the Navier-Stokes Equations. Lecture Notes in Mathematics 149 (Berlin: Springer, 1979).
9 J. Giroire and J. C. Nedelec. Numerical solution of an exterior Neumann problem using a double layer potential. Math. Comp. 32 (1978), 973-990.
10 N. M. Günther. Potential Theory and its Applications to Basic Problems of Mathematical Physics (New York: Ungar, 1967).
11 S. L. Hariharan and E. Stephan. A boundary element method for a two-dimensional interface problem in electromagnetics. Numer. Math. 42 (1983), 311-322.
12 S. Hildebrandt and E. Wienholtz. Constructive proofs of representation theorems in separable Hilbert space. Comm. Pure. Appl. Math. 17 (1964), 369-373.
13 G. C. Hsiao and W. L. Wendland. A finite element method for some integral equations of the first kind. J. Math. Anal. Appl. 58 (1977), 449-481.
14 W. Knauff and R. Kress. On the exterior boundary value problem for the time-harmonic Maxwell equations. J. Math. Anal. Appl. 72 (1979), 215-235.
15 R. Kress and G. F. Roach. Transmission problems for the Helmholtz equation. J. Math. Phys. 19 (1978), 1433-1437.

16 W. D. Kupradze. Randwertaufgaben der Schwingungstheorie und Integralgleichungen (Berlin: VEB DVW, 1956).
17 J. L. Lions and E. Magenes. Non-Homogeneous Boundary Value Problems and Applications, Vol. I (Berlin: Springer, 1972).
18 R. C. MacCamy and E. P. Stephan. A boundary element method for an exterior problem for three-dimensional Maxwell's equations. Appl. Anal. 16 (1983), 141-163.
19 R. C. MacCamy and E. P. Stephan. Solution procedures for three-dimensional eddy current problems. J. Math. Anal. Appl. 101 (1984), 348-379.
20 C. Müller, Foundations of the Mathematical Theory of Electromagnetic Waves (Berlin: Springer, 1969).

21 T. von Petersdorff. Randintegralgleichungen für kombinierte Dirichlet-, Neumann und Transmissionsprobleme (Diploma Thesis, Technische Hochschule Darmstadt, 1987).
22 R. T. Seeley. Singular integrals and boundary value problems. Amer. J. Math. 88 (1966), 781-809.
23 E. Stephan and W. L. Wendland. Remarks to Galerkin and least squares methods with finite elements for general elliptic problems. Manuscripta Geodaetica 1 (1976), 93-123.
24 E. P. Stephan. Boundary integral equations for magnetic screens in $\mathbb{R}^{3}$. Proc. Roy. Soc. Edinburgh Sect. A 102 (1986), 189-210.
25 E. P. Stephan. Boundary Integral Equations for Mixed Boundary Value Problems, Screen and Transmission Problems in $\mathbb{R}^{3}$ (Habilitationsschrift, Technische Hochschule Darmstadt, 1984).
26 E. P. Stephan. Solution procedures for interface problems in acoustics and electromagnetics. In Theoretical Acoustics and Numerical Techniques, CISM Courses 277, ed. P. Filippi, pp. 291-348 (Wien-New York: Springer, 1983).
27 M. Taylor. Pseudodifferential Operators (Princeton: University Press, 1981).
28 G. Vainikko. On the question of convergence of Galerkin's method. Tartu Riikl. Ul. Toimetised 177 (1965), 148-152.
29 W. L. Wendland. Asymptotic convergence of boundary element methods. In Lectures on the Numerical Solution of Partial Differential Equations, eds. I. Babuška, T. P. Liu and J. Osborn, pp. 435-528, Lecture Notes \#20 (College Park, MD: University of Maryland, 1981).
30 W. L. Wendland. Boundary element methods and their asymptotic convergence. In Theoretical Acoustics and Numerical Techniques, CISM Courses 277, ed. P. Filippi, pp. 135-216 (Wien: Springer, 1983).
31 W. L. Wendland. On some mathematical aspects of boundary element methods for elliptic problems. In Mathematics of Finite Elements and Applications V, ed. J. Whiteman, pp. 193-227 (London: Academic Press, 1985).


[^0]:    * Supported by the NSF grant DMS-8603954.

