

# G-Sobolev Spase, BSDE & PPDE

Shige Peng, Shandong University, China

with

with Y. SONG (M. HU, Sh. JI)

Workshop on BSDE, 22 May. 2013, Rennes

- Backward stochastic differential equations (BSDE) driven by a  $G$ -Brownian motion  $(B_t)_{t \geq 0}$  in the following form:

$$Y_t = \zeta + \int_t^T f(s, Y_s, Z_s) ds + \int_t^T g(s, Y_s, Z_s) d\langle B \rangle_s - \int_t^T Z_s dB_s - (K_T - K_t).$$

- Backward stochastic differential equations (BSDE) driven by a  $G$ -Brownian motion  $(B_t)_{t \geq 0}$  in the following form:

$$Y_t = \xi + \int_t^T f(s, Y_s, Z_s) ds + \int_t^T g(s, Y_s, Z_s) d\langle B \rangle_s - \int_t^T Z_s dB_s - (K_T - K_t).$$

- Under a Lipschitz condition of  $f$  and  $g$  in  $Y$  and  $Z$ .

- Backward stochastic differential equations (BSDE) driven by a  $G$ -Brownian motion  $(B_t)_{t \geq 0}$  in the following form:

$$Y_t = \xi + \int_t^T f(s, Y_s, Z_s) ds + \int_t^T g(s, Y_s, Z_s) d\langle B \rangle_s - \int_t^T Z_s dB_s - (K_T - K_t).$$

- Under a Lipschitz condition of  $f$  and  $g$  in  $Y$  and  $Z$ .
- The existence and uniqueness of the solution  $(Y, Z, K)$  is proved, where  $K$  is a decreasing  $G$ -martingale.

$G$ -martingale  $M$  is of the form

$$M_t = M_0 + \bar{M}_t + K_t,$$

$$\bar{M}_t := \int_0^t z_s B_s,$$

$$K_t := \int_0^t \eta_s \langle B \rangle_s - \int_0^t 2G(\eta_s) ds.$$

$$Y_t = \xi + \int_t^T f(s, Y_s, Z_s) ds + \int_t^T g(s, Y_s, Z_s) d\langle B \rangle_s \\ - \int_t^T Z_s dB_s - (K_T - K_t).$$

- $\Omega = C_0(\mathbb{R}^+, \mathbb{R})$

- $\Omega = C_0(\mathbb{R}^+, \mathbb{R})$
- $\Omega_t := \{\omega_t = (\omega(s))_{s \in [0, t]} : \omega \in \Omega\}$ .



- $\Omega = C_0(\mathbb{R}^+, \mathbb{R})$
- $\Omega_t := \{\omega_t = (\omega(s))_{s \in [0,t]} : \omega \in \Omega\}$ .
- $B(t, \omega) = \omega(t)$ .

- $\Omega = C_0(\mathbb{R}^+, \mathbb{R})$
- $\Omega_t := \{\omega_t = (\omega(s))_{s \in [0,t]} : \omega \in \Omega\}$ .
- $B(t, \omega) = \omega(t)$ .
- Definition of  $G$ -BM: given a linear space of functions of paths:

$$Lip(\Omega_T) := \{\varphi(\omega(t_1), \dots, \omega(t_n)) : t_1, \dots, t_n \in [0, T], \quad (1)$$

$$\varphi \in C_{l.Lip}(\mathbb{R}^n), \quad n \in \mathbb{N}\}, \quad (2)$$

- $G(a) := \frac{1}{2}(\bar{\sigma}^2 a^+ - \underline{\sigma}^2 a^-)$ ,  $(\underline{\sigma}^2 \leq \bar{\sigma}^2)$

- $G(a) := \frac{1}{2}(\bar{\sigma}^2 a^+ - \underline{\sigma}^2 a^-)$ , ( $\underline{\sigma}^2 \leq \bar{\sigma}^2$ )
- $\xi(\omega) \in L_{ip}(\Omega_T)$  of the form

$$\xi(\omega) = \varphi(\omega(t_1), \omega(t_2), \dots, \omega(t_n)), \quad 0 = t_0 < t_1 < \dots < t_n \leq T,$$

- $G(a) := \frac{1}{2}(\bar{\sigma}^2 a^+ - \underline{\sigma}^2 a^-)$ , ( $\underline{\sigma}^2 \leq \bar{\sigma}^2$ )
- $\xi(\omega) \in L_{ip}(\Omega_T)$  of the form

$$\xi(\omega) = \varphi(\omega(t_1), \omega(t_2), \dots, \omega(t_n)), \quad 0 = t_0 < t_1 < \dots < t_n \leq T,$$

- $\mathbb{E}_t^G[\xi] := u_k(t, \omega(t); \omega(t_1), \dots, \omega(t_{k-1}))$  for each  $t \in [t_{k-1}, t_k)$ ,  $k = 1, \dots, n$ .

- $G(a) := \frac{1}{2}(\bar{\sigma}^2 a^+ - \underline{\sigma}^2 a^-)$ , ( $\underline{\sigma}^2 \leq \bar{\sigma}^2$ )
- $\xi(\omega) \in L_{ip}(\Omega_T)$  of the form

$$\xi(\omega) = \varphi(\omega(t_1), \omega(t_2), \dots, \omega(t_n)), \quad 0 = t_0 < t_1 < \dots < t_n \leq T,$$

- $\mathbb{E}_t^G[\xi] := u_k(t, \omega(t); \omega(t_1), \dots, \omega(t_{k-1}))$  for each  $t \in [t_{k-1}, t_k)$ ,  $k = 1, \dots, n$ .
- $u_k = u_k(t, x; x_1, \dots, x_{k-1})$  is a function of  $(t, x)$  parameterized by  $(x_1, \dots, x_{k-1}) \in \mathbb{R}^{k-1}$

- $G(a) := \frac{1}{2}(\bar{\sigma}^2 a^+ - \underline{\sigma}^2 a^-)$ , ( $\underline{\sigma}^2 \leq \bar{\sigma}^2$ )
- $\xi(\omega) \in L_{ip}(\Omega_T)$  of the form

$$\xi(\omega) = \varphi(\omega(t_1), \omega(t_2), \dots, \omega(t_n)), \quad 0 = t_0 < t_1 < \dots < t_n \leq T,$$

- $\mathbb{E}_t^G[\xi] := u_k(t, \omega(t); \omega(t_1), \dots, \omega(t_{k-1}))$  for each  $t \in [t_{k-1}, t_k)$ ,  $k = 1, \dots, n$ .
- $u_k = u_k(t, x; x_1, \dots, x_{k-1})$  is a function of  $(t, x)$  parameterized by  $(x_1, \dots, x_{k-1}) \in \mathbb{R}^{k-1}$
- Sol. of PDE

$$\partial_t u_k + G(\partial_{xx} u_k) = 0, \quad (t, x) \in [t_{k-1}, t_k) \times \mathbb{R},$$

- $G(a) := \frac{1}{2}(\bar{\sigma}^2 a^+ - \underline{\sigma}^2 a^-)$ , ( $\underline{\sigma}^2 \leq \bar{\sigma}^2$ )
- $\xi(\omega) \in L_{ip}(\Omega_T)$  of the form

$$\xi(\omega) = \varphi(\omega(t_1), \omega(t_2), \dots, \omega(t_n)), \quad 0 = t_0 < t_1 < \dots < t_n \leq T,$$

- $\mathbb{E}_t^G[\xi] := u_k(t, \omega(t); \omega(t_1), \dots, \omega(t_{k-1}))$  for each  $t \in [t_{k-1}, t_k)$ ,  $k = 1, \dots, n$ .
- $u_k = u_k(t, x; x_1, \dots, x_{k-1})$  is a function of  $(t, x)$  parameterized by  $(x_1, \dots, x_{k-1}) \in \mathbb{R}^{k-1}$
- Sol. of PDE

$$\partial_t u_k + G(\partial_{xx} u_k) = 0, \quad (t, x) \in [t_{k-1}, t_k) \times \mathbb{R},$$

- $u_n(t_n, x; x_1, \dots, x_{n-1}) = \varphi(x_1, \dots, x_{n-1}, x)$



- $G(a) := \frac{1}{2}(\bar{\sigma}^2 a^+ - \underline{\sigma}^2 a^-)$ , ( $\underline{\sigma}^2 \leq \bar{\sigma}^2$ )
- $\xi(\omega) \in L_{ip}(\Omega_T)$  of the form

$$\xi(\omega) = \varphi(\omega(t_1), \omega(t_2), \dots, \omega(t_n)), \quad 0 = t_0 < t_1 < \dots < t_n \leq T,$$

- $\mathbb{E}_t^G[\xi] := u_k(t, \omega(t); \omega(t_1), \dots, \omega(t_{k-1}))$  for each  $t \in [t_{k-1}, t_k)$ ,  $k = 1, \dots, n$ .
- $u_k = u_k(t, x; x_1, \dots, x_{k-1})$  is a function of  $(t, x)$  parameterized by  $(x_1, \dots, x_{k-1}) \in \mathbb{R}^{k-1}$
- Sol. of PDE

$$\partial_t u_k + G(\partial_{xx} u_k) = 0, \quad (t, x) \in [t_{k-1}, t_k) \times \mathbb{R},$$

- $u_n(t_n, x; x_1, \dots, x_{n-1}) = \varphi(x_1, \dots, x_{n-1}, x)$
- $u_k(t_k, x; x_1, \dots, x_{k-1}) = u_{k+1}(t_k, x; x_1, \dots, x_{k-1}, x)$ .

# The $G$ -expectation of $\tilde{\zeta}(\omega)$ :

- $\mathbb{E}^G[\tilde{\zeta}] := \mathbb{E}_0^G[\tilde{\zeta}]$ .

# The $G$ -expectation of $\tilde{\zeta}(\omega)$ :

- $\mathbb{E}^G[\tilde{\zeta}] := \mathbb{E}_0^G[\tilde{\zeta}]$ .
- $\|\tilde{\zeta}\|_{L_G^p} := \mathbb{E}^G[|\tilde{\zeta}|^p]^{1/p}$ .

# The $G$ -expectation of $\tilde{\zeta}(\omega)$ :

- $\mathbb{E}^G[\tilde{\zeta}] := \mathbb{E}_0^G[\tilde{\zeta}]$ .
- $\|\tilde{\zeta}\|_{L_G^p} := \mathbb{E}^G[|\tilde{\zeta}|^p]^{1/p}$ .
- $L_G^p(\Omega_T) := \{\text{The completion of } L_{ip}(\Omega_T) \text{ under } \|\cdot\|_{L_G^p}\}$

# The $G$ -expectation of $\tilde{\zeta}(\omega)$ :

- $\mathbb{E}^G[\tilde{\zeta}] := \mathbb{E}_0^G[\tilde{\zeta}]$ .
- $\|\tilde{\zeta}\|_{L_G^p} := \mathbb{E}^G[|\tilde{\zeta}|^p]^{1/p}$ .
- $L_G^p(\Omega_T)$ : = {The completion of  $L_{ip}(\Omega_T)$  under  $\|\cdot\|_{L_G^p}$ }
- $u(\omega_t) := \mathbb{E}_t^G[\tilde{\zeta}](\omega_t)$ ,  $t \in [0, T]$ , is a  $G$ -martingale,

# The $G$ -expectation of $\tilde{\zeta}(\omega)$ :

- $\mathbb{E}^G[\tilde{\zeta}] := \mathbb{E}_0^G[\tilde{\zeta}]$ .
- $\|\tilde{\zeta}\|_{L_G^p} := \mathbb{E}^G[|\tilde{\zeta}|^p]^{1/p}$ .
- $L_G^p(\Omega_T)$ : = {The completion of  $L_{ip}(\Omega_T)$  under  $\|\cdot\|_{L_G^p}$ }
- $u(\omega_t) := \mathbb{E}_t^G[\tilde{\zeta}](\omega_t)$ ,  $t \in [0, T]$ , is a  $G$ -martingale,
- $u(\omega_t)$  is path-dependent PDE:  $\partial_t u(\omega_t) + G(\partial_{xx} u(\omega_t)) = 0$

# The $G$ -expectation of $\tilde{\zeta}(\omega)$ :

- $\mathbb{E}^G[\tilde{\zeta}] := \mathbb{E}_0^G[\tilde{\zeta}]$ .
- $\|\tilde{\zeta}\|_{L_G^p} := \mathbb{E}^G[|\tilde{\zeta}|^p]^{1/p}$ .
- $L_G^p(\Omega_T)$ : = {The completion of  $L_{ip}(\Omega_T)$  under  $\|\cdot\|_{L_G^p}$ }
- $u(\omega_t) := \mathbb{E}_t^G[\tilde{\zeta}](\omega_t)$ ,  $t \in [0, T]$ , is a  $G$ -martingale,
- $u(\omega_t)$  is path-dependent PDE:  $\partial_t u(\omega_t) + G(\partial_{xx} u(\omega_t)) = 0$
- with terminal condition:  $u(\omega_T) = \tilde{\zeta}(\omega)$ .

# The $G$ -expectation of $\tilde{\zeta}(\omega)$ :

- $\mathbb{E}^G[\tilde{\zeta}] := \mathbb{E}_0^G[\tilde{\zeta}]$ .
- $\|\tilde{\zeta}\|_{L_G^p} := \mathbb{E}^G[|\tilde{\zeta}|^p]^{1/p}$ .
- $L_G^p(\Omega_T)$ : = {The completion of  $L_{ip}(\Omega_T)$  under  $\|\cdot\|_{L_G^p}$ }
- $u(\omega_t) := \mathbb{E}_t^G[\tilde{\zeta}](\omega_t)$ ,  $t \in [0, T]$ , is a  $G$ -martingale,
- $u(\omega_t)$  is path-dependent PDE:  $\partial_t u(\omega_t) + G(\partial_{xx} u(\omega_t)) = 0$
- with terminal condition:  $u(\omega_T) = \tilde{\zeta}(\omega)$ .
- “ $G$ -Sobolev space” is implicitly “given”!



## Definition

- A function  $\xi : \Omega_T \rightarrow \mathbb{R}$  is called a cylinder function of paths on  $[0, T]$  if

$$\xi(\omega_T) = \varphi(\omega(t_1), \dots, \omega(t_n)), \omega_T \in \Omega_T,$$

$$0 < t_1 < \dots < t_n,$$

## Definition

- A function  $\xi : \Omega_T \rightarrow \mathbb{R}$  is called a cylinder function of paths on  $[0, T]$  if

$$\xi(\omega_T) = \varphi(\omega(t_1), \dots, \omega(t_n)), \omega_T \in \Omega_T,$$

$$0 < t_1 < \dots < t_n,$$

- $\varphi : (\mathbb{R}^d)^n \rightarrow \mathbb{R}$ :  $C^\infty$ -function with at most polynomial growth.

## Definition

- A function  $\xi : \Omega_T \rightarrow \mathbb{R}$  is called a cylinder function of paths on  $[0, T]$  if

$$\xi(\omega_T) = \varphi(\omega(t_1), \dots, \omega(t_n)), \omega_T \in \Omega_T,$$

$$0 < t_1 < \dots < t_n,$$

- $\varphi : (\mathbb{R}^d)^n \rightarrow \mathbb{R}$ :  $C^\infty$ -function with at most polynomial growth.
- $C^\infty(\Omega_T)$ : collection of all cylinder functions of paths on  $[0, T]$ .

## Definition

A function  $\eta(\omega_t) : [0, T] \times \Omega_T \rightarrow \mathbb{R}$  is called a step process if  $\exists$  a time partition  $\{t_i\}_{i=0}^n$ ,  $0 = t_0 < t_1 < \cdots < t_n = T$ , such that for each  $t \in (t_k, t_{k+1}]$

$$\eta(\omega_t) = \varphi_k(\omega(t_1), \cdots, \omega(t_k)), \quad k = 0, 1, \cdots, n-1.$$

$\varphi_k(\omega(t_1), \cdots, \omega(t_k)) \in C^\infty(\Omega_T)$  is bounded.

We denote by  $M^0(0, T)$  the collection of all step processes.

$(\Omega_T, \mathbb{E}^G, C^\infty(\Omega_T))$ : as the  $G$ -expectation space.

- $G(A) := \frac{1}{2}\mathbb{E}^G[(AB_1, B_1)]$ .

$(\Omega_T, \mathbb{E}^G, C^\infty(\Omega_T))$ : as the  $G$ -expectation space.

- $G(A) := \frac{1}{2} \mathbb{E}^G[(AB_1, B_1)]$ .
- $\|\xi\|_{L_G^2}^2 := \mathbb{E}^G[|\xi|^2] \quad \xi \in C^\infty(\Omega_T)$

$(\Omega_T, \mathbb{E}^G, C^\infty(\Omega_T))$ : as the  $G$ -expectation space.

- $G(A) := \frac{1}{2} \mathbb{E}^G[(AB_1, B_1)]$ .
- $\|\xi\|_{L_G^2}^2 := \mathbb{E}^G[|\xi|^2] \quad \xi \in C^\infty(\Omega_T)$
- $L_G^2(\Omega_T)$ : the completion of  $C^\infty(\Omega_T)$  under  $\|\cdot\|_{L_G^2}$ .

$(\Omega_T, \mathbb{E}^G, C^\infty(\Omega_T))$ : as the  $G$ -expectation space.

- $G(A) := \frac{1}{2} \mathbb{E}^G[(AB_1, B_1)]$ .
- $\|\xi\|_{L_G^2}^2 := \mathbb{E}^G[|\xi|^2] \quad \xi \in C^\infty(\Omega_T)$
- $L_G^2(\Omega_T)$ : the completion of  $C^\infty(\Omega_T)$  under  $\|\cdot\|_{L_G^2}$ .
- For a step process  $\eta \in M^0(0, T)$ , set  $\|\eta\|_{M_G^2}^2 := \mathbb{E}^G[\int_0^T |\eta_s|^2 ds]$ .



$(\Omega_T, \mathbb{E}^G, C^\infty(\Omega_T))$ : as the  $G$ -expectation space.

- $G(A) := \frac{1}{2} \mathbb{E}^G[(AB_1, B_1)]$ .
- $\|\xi\|_{L_G^2}^2 := \mathbb{E}^G[|\xi|^2] \quad \xi \in C^\infty(\Omega_T)$
- $L_G^2(\Omega_T)$ : the completion of  $C^\infty(\Omega_T)$  under  $\|\cdot\|_{L_G^2}$ .
- For a step process  $\eta \in M^0(0, T)$ , set  $\|\eta\|_{M_G^2}^2 := \mathbb{E}^G[\int_0^T |\eta_s|^2 ds]$ .
- $M_G^2(0, T)$ : the completion of  $M^0(0, T)$  under  $\|\cdot\|_{M_G^2}$ .

$(\Omega_T, \mathbb{E}^G, C^\infty(\Omega_T))$ : as the  $G$ -expectation space.

- $G(A) := \frac{1}{2} \mathbb{E}^G[(AB_1, B_1)]$ .
- $\|\xi\|_{L_G^2}^2 := \mathbb{E}^G[|\xi|^2] \quad \xi \in C^\infty(\Omega_T)$
- $L_G^2(\Omega_T)$ : the completion of  $C^\infty(\Omega_T)$  under  $\|\cdot\|_{L_G^2}$ .
- For a step process  $\eta \in M^0(0, T)$ , set  $\|\eta\|_{M_G^2}^2 := \mathbb{E}^G[\int_0^T |\eta_s|^2 ds]$ .
- $M_G^2(0, T)$ : the completion of  $M^0(0, T)$  under  $\|\cdot\|_{M_G^2}$ .
- In linear case:  $(\Omega_T, \mathcal{F}, \{\mathcal{F}_t\}, P)$ :  $\|\cdot\|_{L_P^2}$ ,  $L_P^2(\Omega_T)$ ,  $\|\cdot\|_{M_P^2}$  and  $M_P^2(0, T)$ .

## Definition

- A function  $u(\omega_t) : [0, T] \times \Omega_T \rightarrow \mathbb{R}$  is called a cylinder path process if  $\exists$  a time partition  $\{t_i\}_{i=0}^n$  with  $0 = t_0 < t_1 < \cdots < t_n = T$ , s.t.

## Definition

- A function  $u(\omega_t) : [0, T] \times \Omega_T \rightarrow \mathbb{R}$  is called a cylinder path process if  $\exists$  a time partition  $\{t_i\}_{i=0}^n$  with  $0 = t_0 < t_1 < \cdots < t_n = T$ , s.t.
- for each  $k = 0, 1, \dots, n-1$  and  $t \in (t_k, t_{k+1}]$ ,

$$u(\omega_t) = u_k(t, \omega(t); \omega(t_1), \dots, \omega(t_k)).$$

## Definition

- A function  $u(\omega_t) : [0, T] \times \Omega_T \rightarrow \mathbb{R}$  is called a cylinder path process if  $\exists$  a time partition  $\{t_i\}_{i=0}^n$  with  $0 = t_0 < t_1 < \cdots < t_n = T$ , s.t.
- for each  $k = 0, 1, \dots, n-1$  and  $t \in (t_k, t_{k+1}]$ ,

$$u(\omega_t) = u_k(t, \omega(t); \omega(t_1), \dots, \omega(t_k)).$$

- $u_k : [t_k, t_{k+1}] \times (\mathbb{R}^d)^{(k+1)} \rightarrow \mathbb{R}$  is a  $C^\infty$ -function with

$$u_k(t_k, x; x_1, \dots, x_{k-1}, x) = u_{k-1}(t_k, x; x_1, \dots, x_{k-1})$$

## Definition

- A function  $u(\omega_t) : [0, T] \times \Omega_T \rightarrow \mathbb{R}$  is called a cylinder path process if  $\exists$  a time partition  $\{t_i\}_{i=0}^n$  with  $0 = t_0 < t_1 < \dots < t_n = T$ , s.t.
- for each  $k = 0, 1, \dots, n-1$  and  $t \in (t_k, t_{k+1}]$ ,

$$u(\omega_t) = u_k(t, \omega(t); \omega(t_1), \dots, \omega(t_k)).$$

- $u_k : [t_k, t_{k+1}] \times (\mathbb{R}^d)^{(k+1)} \rightarrow \mathbb{R}$  is a  $C^\infty$ -function with

$$u_k(t_k, x; x_1, \dots, x_{k-1}, x) = u_{k-1}(t_k, x; x_1, \dots, x_{k-1})$$

- all derivatives of  $u_k$  have at most polynomial growth.

## Definition

- A function  $u(\omega_t) : [0, T] \times \Omega_T \rightarrow \mathbb{R}$  is called a cylinder path process if  $\exists$  a time partition  $\{t_i\}_{i=0}^n$  with  $0 = t_0 < t_1 < \dots < t_n = T$ , s.t.
- for each  $k = 0, 1, \dots, n-1$  and  $t \in (t_k, t_{k+1}]$ ,

$$u(\omega_t) = u_k(t, \omega(t); \omega(t_1), \dots, \omega(t_k)).$$

- $u_k : [t_k, t_{k+1}] \times (\mathbb{R}^d)^{(k+1)} \rightarrow \mathbb{R}$  is a  $C^\infty$ -function with

$$u_k(t_k, x; x_1, \dots, x_{k-1}, x) = u_{k-1}(t_k, x; x_1, \dots, x_{k-1})$$

- all derivatives of  $u_k$  have at most polynomial growth.
- $\mathcal{C}^\infty(0, T) :=$  the collection of all cylinder path processes.

## Proposition.

Let  $\eta, \zeta$  be step processes. Then

$$u(\omega_t) := \int_0^t \eta(\omega_s) ds + \int_0^t \zeta(\omega_s) dB_s$$

belongs to  $\mathcal{C}^\infty(0, T)$ .





For  $t \in [t_k, t_{k+1})$ ,  $n \in \mathbb{N}$ , we denote

$$D_t^{(n)} u(\omega_t) := \partial_{t+}^{(n)} u_k(t, x; x_1, \dots, x_k) \Big|_{x=\omega(t), x_1=\omega(t_1), \dots, x_k=\omega(t_k)}.$$

We denote  $D_t = D_t^{(1)}$  for simplicity.

- For  $t \in (t_k, t_{k+1}]$ , we denote

$$D_x u(\omega_t) := \partial_x u_k(t, x; x_1, \dots, x_k) \Big|_{x=\omega(t), x_1=\omega(t_1), \dots, x_k=\omega(t_k)}, \quad (3)$$

$$D_x^2 u(\omega_t) := \partial_x^2 u_k(t, x; x_1, \dots, x_k) \Big|_{x=\omega(t), x_1=\omega(t_1), \dots, x_k=\omega(t_k)}, \quad (4)$$

$$\Delta_x u(\omega_t) := \text{tr} D_x^2 u(\omega_t). \quad (5)$$

- For  $t \in (t_k, t_{k+1}]$ , we denote

$$D_x u(\omega_t) := \partial_x u_k(t, x; x_1, \dots, x_k) \Big|_{x=\omega(t), x_1=\omega(t_1), \dots, x_k=\omega(t_k)}, \quad (3)$$

$$D_x^2 u(\omega_t) := \partial_x^2 u_k(t, x; x_1, \dots, x_k) \Big|_{x=\omega(t), x_1=\omega(t_1), \dots, x_k=\omega(t_k)}, \quad (4)$$

$$\Delta_x u(\omega_t) := \text{tr} D_x^2 u(\omega_t). \quad (5)$$

- Let  $\mathbb{D}$  be the Malliavin derivative operator. For  $u \in \mathcal{C}^\infty(0, T)$ , we have

$$\mathbb{D}_t u_t(\omega) = D_x u(\omega_t).$$

- The above definition derivatives corresponds perfectly with Dupire's one, introduced in his insightful paper (2009) (see also [CF2010]).

- The above definition derivatives corresponds perfectly with Dupire's one, introduced in his insightful paper (2009) (see also [CF2010]).
- An advantage of our this formulation: is that we do not need to define of our derivatives on a space of right continuous paths with left limit.

# Wiener probability space $(\Omega, \mathcal{F}, P)$

- For the case  $G(A) = \frac{1}{2}\text{tr}(A)$ ,  $G$ -expectation  $= E_P$  of the exp. in Wiener Prob. space  $(\Omega, \mathcal{F}, P)$  and the  $G$ -BM  $B$  becomes the Wiener process.

# Wiener probability space $(\Omega, \mathcal{F}, P)$

- For the case  $G(A) = \frac{1}{2}\text{tr}(A)$ ,  $G$ -expectation  $= E_P$  of the exp. in Wiener Prob. space  $(\Omega, \mathcal{F}, P)$  and the  $G$ -BM  $B$  becomes the Wiener process.
- In this case  $u \in C^\infty(0, \infty)$  has the following decomposition:

# Wiener probability space $(\Omega, \mathcal{F}, P)$

- For the case  $G(A) = \frac{1}{2}\text{tr}(A)$ ,  $G$ -expectation  $= E_P$  of the exp. in Wiener Prob. space  $(\Omega, \mathcal{F}, P)$  and the  $G$ -BM  $B$  becomes the Wiener process.
- In this case  $u \in C^\infty(0, \infty)$  has the following decomposition:

## Proposition.

For each given  $u \in C^\infty(0, \infty)$  we have

$$u(\omega_t) = u(\omega_0) + \int_0^t \mathcal{A}u(\omega_s) ds + \int_0^t D_x u(\omega_s) dB_s,$$

where

$$\mathcal{A}u(\omega_s) := D_s u(\omega_s) + \frac{1}{2} \Delta_x u(\omega_s).$$





## Definition

- For  $u \in C^\infty(0, T)$ , set

$$\|u\|_{S_P^2}^2 = E_P \left[ \sup_{s \in [0, T]} |u_s|^2 \right].$$

## Definition

- For  $u \in C^\infty(0, T)$ , set

$$\|u\|_{S_P^2}^2 = E_P \left[ \sup_{s \in [0, T]} |u_s|^2 \right].$$

- $S_P^2(0, T)$ : the completion of  $C^\infty(0, T)$  under the norm  $\|\cdot\|_{S_P^2}$ .

## Definition

- For  $u \in C^\infty(0, T)$ , set

$$\|u\|_{S_P^2}^2 = E_P \left[ \sup_{s \in [0, T]} |u_s|^2 \right].$$

- $S_P^2(0, T)$ : the completion of  $C^\infty(0, T)$  under the norm  $\|\cdot\|_{S_P^2}$ .
- For  $u \in C^\infty(0, T)$ , set

$$\|u\|_{W_P^1}^2 = E_P \left[ \sup_{s \in [0, T]} |u_s|^2 + \int_0^T (|\mathcal{A}u_s|^2 + |D_x u_s|^2) ds \right].$$

## Proposition.

The norm  $\|\cdot\|_{W^1_p(0,T)}$  is closable in the space  $S^2_p(0,T)$ : Let  $u^n \in C^\infty(0,T)$  be a Cauchy sequence w.r.t. the norm  $\|\cdot\|_{W^1_p}$ . If  $\|u^n\|_{S^2_p} \rightarrow 0$ , we have  $\|u^n\|_{W^1_p} \rightarrow 0$ . □

## Proposition.

The norm  $\|\cdot\|_{W_P^1(0,T)}$  is closable in the space  $S_P^2(0,T)$ : Let  $u^n \in C^\infty(0,T)$  be a Cauchy sequence w.r.t. the norm  $\|\cdot\|_{W_P^1}$ . If  $\|u^n\|_{S_P^2} \rightarrow 0$ , we have  $\|u^n\|_{W_P^1} \rightarrow 0$ . □

## Proof.

The proposition follows directly from the uniqueness of the decomposition for Itô processes. □

Denote by  $W_P^1(0, T)$  the closure of  $C^\infty(0, T)$  w.r.t. the norm  $\|\cdot\|_{W_P^1}$  in  $S_P^2(0, T)$ . Now the operators  $\mathcal{A}$ ,  $D_x$  can be continuously extended to the space  $W_P^1(0, T)$ .

# A new point of view for Itô processes:

## Proposition.

Assume  $u \in S_P^2(0, T)$ . Then the following two conditions are equivalent:



## Proposition.

Assume  $u \in S_P^2(0, T)$ . Then the following two conditions are equivalent:

- (i)  $u \in W_P^1(0, T)$ ;





## Proposition.

Assume  $u \in S_P^2(0, T)$ . Then the following two conditions are equivalent:

- (i)  $u \in W_P^1(0, T)$ ;
- (ii)  $u(\omega_t) = u(\omega_0) + \int_0^t \eta(\omega_s) ds + \int_0^t v(\omega_s) dB_s$  with  $\eta, v \in M_P^2(0, T)$ .

Moreover, we have

$$\mathcal{A}u(\omega_t) = \eta(\omega_t), \quad D_x u(\omega_t) = v(\omega_t).$$



## Proof.

(i)  $\implies$  (ii) is obvious. Let's prove (ii)  $\implies$  (i). Choose step processes  $\eta^n, v^n$  such that  $\|\eta^n - \eta\|_{M_P^2} \rightarrow 0$  and  $\|v^n - v\|_{M_P^2} \rightarrow 0$ . Set

$$u^n(\omega_t) := u(\omega_0) + \int_0^t \eta^n(\omega_s) ds + \int_0^t v^n(\omega_s) dB_s.$$

Clearly  $u^n$  belongs to  $C^\infty(0, T)$  by Proposition 12. By Proposition 16 and the uniqueness of the decomposition for Itô processes, we have

$$\mathcal{A}u^n(\omega_t) = \eta^n(\omega_t), \quad D_x u^n(\omega_t) = v^n(\omega_t).$$

So  $u$  belongs to  $W_P^1(0, T)$  with

$$\mathcal{A}u(\omega_t) = \eta(\omega_t), \quad D_x u(\omega_t) = v(\omega_t).$$



## Proposition.

- For each given  $u \in C^\infty(0, \infty)$  we have

$$\begin{aligned} & u(\omega_t) \\ &= u(\omega_0) + \int_0^t D_s u(\omega_s) ds + \int_0^t D_x u(\omega_s) dB_s + \frac{1}{2} \int_0^t D_x^2 u(\omega_s) d\langle B \rangle_s \\ &= u(\omega_0) + \int_0^t \mathcal{A}_G u(\omega_s) ds + \int_0^t D_x u(\omega_s) dB_s + K_t, \end{aligned}$$



## Proposition.

- For each given  $u \in C^\infty(0, \infty)$  we have

$$\begin{aligned} & u(\omega_t) \\ &= u(\omega_0) + \int_0^t D_s u(\omega_s) ds + \int_0^t D_x u(\omega_s) dB_s + \frac{1}{2} \int_0^t D_x^2 u(\omega_s) d\langle B \rangle_s \\ &= u(\omega_0) + \int_0^t \mathcal{A}_G u(\omega_s) ds + \int_0^t D_x u(\omega_s) dB_s + K_t, \end{aligned}$$

- where

$$\mathcal{A}_G u(\omega_s) := D_s u(\omega_s) + G(D_x^2 u(\omega_s)),$$



## Proposition.

- For each given  $u \in C^\infty(0, \infty)$  we have

$$\begin{aligned} & u(\omega_t) \\ &= u(\omega_0) + \int_0^t D_s u(\omega_s) ds + \int_0^t D_x u(\omega_s) dB_s + \frac{1}{2} \int_0^t D_x^2 u(\omega_s) d\langle B \rangle_s \\ &= u(\omega_0) + \int_0^t \mathcal{A}_G u(\omega_s) ds + \int_0^t D_x u(\omega_s) dB_s + K_t, \end{aligned}$$

- where

$$\mathcal{A}_G u(\omega_s) := D_s u(\omega_s) + G(D_x^2 u(\omega_s)),$$

- 

$$K_t := \frac{1}{2} \int_0^t D_x^2 u(\omega_s) d\langle B \rangle_s - \int_0^t G(D_x^2 u(\omega_s)) ds$$

$K$  is a non-increasing G-martingale.



## Definition

- 1) For  $u \in C^\infty(0, T)$ , we set

$$\|u\|_{S_G^2}^2 = \mathbb{E}^G \left[ \sup_{s \in [0, T]} |u_s|^2 \right].$$

## Definition

- 1) For  $u \in C^\infty(0, T)$ , we set

$$\|u\|_{S_G^2}^2 = \mathbb{E}^G \left[ \sup_{s \in [0, T]} |u_s|^2 \right].$$

- We denote by  $S_G^2(0, T)$  the completion of  $u \in C^\infty(0, T)$  w.r.t. the norm  $\|\cdot\|_{S_G^2}$ .

## Definition

- 1) For  $u \in C^\infty(0, T)$ , we set

$$\|u\|_{S_G^2}^2 = \mathbb{E}^G \left[ \sup_{s \in [0, T]} |u_s|^2 \right].$$

- We denote by  $S_G^2(0, T)$  the completion of  $u \in C^\infty(0, T)$  w.r.t. the norm  $\|\cdot\|_{S_G^2}$ .
- 2) For  $u \in C^\infty(0, T)$ , we set

$$\|u\|_{W_G^2}^2 = \mathbb{E}^G \left[ \sup_{s \in [0, T]} |u_s|^2 + \int_0^T (|D_s u_s|^2 + |D_x u_s|^2 + |D_x^2 u_s|^2) ds \right].$$



- The key point for  $G$ -Sobolev spaces: the uniqueness of the decomposition for  $G$ -Itô processes,

- The key point for  $G$ -Sobolev spaces: the uniqueness of the decomposition for  $G$ -Itô processes,
- Actually solved by Song (2012)

- The key point for  $G$ -Sobolev spaces: the uniqueness of the decomposition for  $G$ -Itô processes,
- Actually solved by Song (2012)
- see Peng, Song and Zhang (2012) for the multi-dimensional case.
- We only consider the 1-dim  $G$ -BM and assume  $\bar{\sigma}^2 := \mathbb{E}^G[B_1^2] > \underline{\sigma}^2 := -\mathbb{E}^G[-B_1^2]$

## Lemma

If

$$u(\omega_t) = \int_0^t \zeta(\omega_s) ds + \int_0^t v(\omega_s) dB_s + \frac{1}{2} \int_0^t w(\omega_s) d\langle B \rangle_s = 0$$

with  $\zeta, v, w \in M_G^2(0, T)$ , we have  $\zeta = v = w = 0$ .

## Proof.

By the uniqueness of the decomposition for continuous semimartingales we have  $v = 0$  and  $\int_0^t \zeta(\omega_s) ds + \frac{1}{2} \int_0^t w(\omega_s) d\langle B \rangle_s = 0$ . By Corollary 3.5 in Song (2012) we conclude that  $\zeta = w = 0$ .  $\square$

## Proposition.

The norm  $\|\cdot\|_{W_G^2}$  is closable in the space  $S_G^2(0, T)$ : Let  $u^n \in C^\infty(0, T)$  be a Cauchy sequence w.r.t. the norm  $\|\cdot\|_{W_G^2}$ . If  $\|u^n\|_{S_G^2} \rightarrow 0$ , we have  $\|u^n\|_{W_G^2} \rightarrow 0$ . □

## Proposition.

The norm  $\|\cdot\|_{W_G^2}$  is closable in the space  $S_G^2(0, T)$ : Let  $u^n \in C^\infty(0, T)$  be a Cauchy sequence w.r.t. the norm  $\|\cdot\|_{W_G^2}$ . If  $\|u^n\|_{S_G^2} \rightarrow 0$ , we have  $\|u^n\|_{W_G^2} \rightarrow 0$ . □

## Proof.

The proposition follows directly from the uniqueness of the decomposition for  $G$ -Itô processes. □

Denote by  $W_G^2(0, T)$  the closure of  $C^\infty(0, T)$  w.r.t. the norm  $\|\cdot\|_{W_G^2}$  in  $S_G^2(0, T)$ . Now the differential operators  $D_t$ ,  $D_x$  and  $D_x^2$  defined on  $C^\infty(0, T)$  can be continuously extended to the space  $W_G^2(0, T)$ .

## Proposition.

Assume  $u \in S_G^2(0, T)$ . Then the following two conditions are equivalent:

- (i)  $u \in W_G^2(0, T)$ ;
- (ii)  $u$  is of the form:

$$u(\omega_t) = u(\omega_0) + \int_0^t \zeta(\omega_s) ds + \int_0^t v(\omega_s) dB_s + \frac{1}{2} \int_0^t w(\omega_s) d\langle B \rangle_s,$$

$$\zeta, v, w \in M_G^2(0, T)$$

Moreover, we have

$$D_t u(\omega_t) = \zeta(\omega_t), \quad D_x u(\omega_t) = v(\omega_t), \quad D_x^2 u(\omega_t) = w(\omega_t).$$





## Remark.

Compared to  $W_p^2(0, T)$  case, here the derivatives  $D_t u$ ,  $D_x u$ ,  $D_x^2 u$  can be distinguished clearly. □

: to find a pair of processes  $(Y, Z) \in S_P^2(0, T) \times M_P^2(0, T)$  s. t.

$$Y_t = \zeta + \int_t^T g(s, Y_s, Z_s) ds - \int_t^T Z_s dB_s, \quad (6)$$

$g$ : a given function and  $\zeta$  is a given  $\mathcal{F}_T$ -measurable.

The backward SDE (6) is equivalent to the path dependent PDE: to find  $u \in W_P^1(0, T)$  such that

$$\mathcal{A}u(\omega_t) + f(t, u(\omega_t), D_x u(\omega_t)) = 0, \quad t \in [0, T), \quad (7)$$

$$u(\omega_T) = \zeta(\omega_T). \quad (8)$$

**Assumption 1.**  $f(t, Y_t, Z_t) \in M_P^2(0, T)$  for any  $(Y, Z) \in S_P^2(0, T) \times M_P^2(0, T)$ .

### Theorem

Let  $(Y, Z)$  be a solution to the backward SDE (6). Then we have  $u(\omega_t) := Y_t(\omega) \in W_P^1(0, T)$  with  $D_x u(\omega_t) = Z_t(\omega)$ .

Moreover, given  $u(\omega_t) \in W_P^1(0, T)$ , the following (i) and (ii) are equivalent:

- (i)  $(u, D_x u)$  is a solution to the backward SDE (6);
- (ii)  $u$  is a solution to the path dependent PDE (7-8).

Proof.

(i)  $\implies$  (ii). Assume that  $(Y, Z)$  is a solution to the backward SDE. We know that  $u(\omega_t) := Y_t(\omega) \in W_P^1(0, T)$  with  $D_x u(\omega_t) = Z_t(\omega)$  and

$$Au(\omega_t) + f(t, u(\omega_t), D_x u(\omega_t)) = 0.$$

(ii)  $\implies$  (i). Assume that  $u(\omega_t) \in W_P^1(0, T)$  is a solution to the path dependent PDE (7-8). By Proposition ?? we have

$$\begin{aligned} u(\omega_t) &= u(\omega_0) + \int_0^t Au(\omega_s) ds + \int_0^t D_x u(\omega_s) dB_s \\ &= u(\omega_0) - \int_0^t f(s, u(\omega_s), D_x u(\omega_s)) ds + \int_0^t D_x u(\omega_s) dB_s \\ &= \zeta(\omega_T) + \int_t^T f(s, u(\omega_s), D_x u(\omega_s)) ds - \int_t^T D_x u(\omega_s) dB_s. \end{aligned}$$



## Remark.

The advantage of our formulation is the path dependent PDE can be a system of PDEs, namely  $u(\omega_t)$  can be  $\mathbb{R}^m$ -valued, or even  $H$ -valued for a Hilbert space  $H$ . □

## Remark.

Let us consider Markovian situations:

$\xi = \varphi(B_T)$ ,  $f(\omega_t, y, z) = h(t, B_t(\omega), y, z)$  for deterministic and continuous functions  $\varphi(x)$  and  $h(t, x, y, z)$  satisfying Lipschitz conditions in  $(y, z)$  and polynomial growth condition in  $x$ . Assume that  $(Y, Z)$  is the solution to the backward SDE (6) with the coefficients  $(\varphi(B_T), h(t, B_t, y, z))$ . By the classical arguments in the BSDE theory, we know that  $Y$  is Markovian, i.e., there exists a deterministic function  $u(t, x)$  such that  $Y_t = u(t, B_t)$ . Assuming  $u(t, x)$  is smooth, we have

$$\mathcal{A}u(\omega_t) = \partial_t u(t, B_t) + \frac{1}{2} \Delta_x u(t, B_t), \quad D_x u(\omega_t) = Du(t, B_t).$$

By Theorem 7, we have

$$\partial_t u(t, B_t) + \frac{1}{2} \Delta_x u(t, B_t) + h(t, B_t, u(t, B_t), Du(t, B_t)) = 0.$$

Let us consider backward SDEs driven by  $G$ -Brownian motion in the following form: to find  $Y \in S_G^2(0, T)$ ,  $Z, \eta \in M_G^2(0, T)$  such that

$$Y_t = \xi + \int_t^T f(s, Y_s, Z_s, \eta_s) ds - \int_t^T Z_s dB_s - (K_T - K_t), \quad (9)$$

where  $K_t = \frac{1}{2} \int_0^t \eta_s d\langle B \rangle_s - \int_0^t G(\eta_s) ds$ ,  $f$  is a given function and  $\xi$  is a given random variable.

The related path dependent PDEs: to find  $u \in W_G^2(0, T)$  such that

$$D_t u + G(D_x^2 u) + f(t, u, D_x u, D_x^2 u) = 0, \quad t \in [0, T), \quad (10)$$

$$u(\omega_T) = \xi(\omega_T). \quad (11)$$

**Assumption 2.**

$f(t, Y_t, Z_t, \eta_t) \in M_G^2(0, T)$  for any  
 $(Y, Z, \eta) \in S_G^2(0, T) \times M_G^2(0, T) \times M_G^2(0, T)$ .

**Theorem**

*Let  $(Y, Z, \eta)$  be a solution to the backward SDE (9). Then we have  $u(\omega_t) := Y_t(\omega) \in W_G^2(0, T)$  with  $D_x u(\omega_t) = Z_t(\omega)$  and  $D_x^2 u(\omega_t) = \eta_t(\omega)$ .*

*Moreover, for  $u(\omega_t) \in W_G^2(0, T)$ , the following conditions are equivalent:*

- (i)  $(u, D_x u, D_x^2 u)$  is a solution to the backward SDE (9);*
- (ii)  $u$  is a solution to the path dependent PDE (10-11).*



$W_G^1(0, T)$  in  $G$ -expectation space

Let us see how to define the  $G$ -Sobolev space  $W_G^1(0, T)$ .

For  $u, v \in C^\infty(0, T)$ , set

$$\tilde{d}_{W_G^1}^2(u, v) = \mathbb{E}^G \left[ \sup_{s \in [0, T]} |u_s - v_s|^2 + \int_0^T (|\mathcal{A}_G u_s - \mathcal{A}_G v_s|^2 + |D_x(u_s - v_s)|^2) ds \right]$$

However, we don't know whether the metric  $\tilde{d}_{W_G^1}$  is closable in the space  $S_G^2(0, T)$ , which is equivalent to the uniqueness of the following decomposition:

$\mathcal{Q}$ : Assume  $\int_0^t \eta_s ds + K_t = L_t$ , where  $\eta \in M_G^2(0, T)$ ,  $K_t, L_t$  are non-increasing  $G$ -martingales with  $K_T, L_T \in L_G^2(\Omega_T)$ . Does it hold that  $\int_0^t \eta_s ds = 0$  and  $K_t = L_t$ ?

Now we modify the metric  $\tilde{d}_{W_G^1}$  slightly. For  $u, v \in C^\infty(0, T)$ , set

$$d_{W_G^1}^2(u, v) = \mathbb{E}^G \left[ \sup_{s \in [0, T]} |u_s - v_s|^2 + \int_0^T |D_x(u_s - v_s)|^2 ds \right] + \int_0^T \mathbb{E}^G [|\mathcal{A}_G u_s - \mathcal{A}_G v_s|^2] ds$$

For a step process  $\eta$ , set  $\|\eta\|_{\tilde{M}_G^2}^2 = \int_0^T \mathbb{E}^G [|\eta_s|^2] ds$ . Denote by  $\tilde{M}_G^2(0, T)$  the completion of the collection of step processes with respect to the norm  $\|\cdot\|_{\tilde{M}_G^2}$ .

In order to define the first-order  $G$ -Sobolev space, we first recall the structure of  $G$ -martingales. S.P., Y.Song & J.Zhang proved that for any  $\xi \in C^\infty(\Omega_T)$ , the  $G$ -martingale  $X_t = \mathbb{E}_t^G[\xi]$  has the following representation:

$$X_t = \mathbb{E}^G[\xi] + \int_0^t Z_s dB_s + \frac{1}{2} \int_0^t \eta_s d\langle B \rangle_s - \int_0^t G(\eta_s) ds \quad (12)$$

for some  $Z, \eta \in M_G^2(0, T)$  and conjectured that for any  $\xi \in L_G^2(\Omega_T)$  the representation (12) holds. Besides, [?] showed that for any  $\eta \in M_G^2(0, T)$ ,

$$K_t := \frac{1}{2} \int_0^t \eta_s d\langle B \rangle_s - \int_0^t G(\eta_s) ds$$

is a non-increasing  $G$ -martingale.

For  $p \geq 1$  and  $\xi \in C^\infty(\Omega_T)$ , set  $\|\xi\|_{\mathbb{L}_G^p}^p = \mathbb{E}^G[\sup_{t \in [0, T]} |\mathbb{E}_t^G[\xi]|^p]$ .

Denote by  $\mathbb{L}_G^p(\Omega_T)$  the closure of  $C^\infty(\Omega_T)$  with respect to the norm  $\|\cdot\|_{\mathbb{L}_G^p}$  in  $L_G^p(\Omega_T)$ . [?] showed that for any  $\xi \in \mathbb{L}_G^2(\Omega_T)$  the  $G$ -martingale  $X_t := \mathbb{E}_t^G[\xi]$  has the following decomposition:

$$X_t = \mathbb{E}^G[\xi] + \int_0^t Z_s dB_s + K_t, \quad (13)$$

where  $K_t$  is a non-increasing  $G$ -martingale.

Song [?] showed that  $\mathbb{L}_G^p(\Omega_T) \supset L_G^q(\Omega_T)$  for any  $1 \leq p < q$ . Moreover, [?] proved that the decomposition (13) holds for any  $\xi \in L_G^p(\Omega_T)$  with  $p > 1$ . Independently, [?] showed that  $\mathbb{L}_G^2(\Omega_T) \supset L_G^q(\Omega_T)$  for any  $q > 2$ .

Below we present a property of non-increasing  $G$ -martingales.

### Lemma

Assume  $\int_0^t \eta_s ds + K_t = L_t$ , where  $\eta \in \tilde{M}_G^2(0, T)$ ,  $K_t, L_t$  are non-increasing  $G$ -martingales with  $K_T, L_T \in L_G^2(\Omega_T)$ . Then we have  $\int_0^t \eta_s ds = 0$  and  $K_t = L_t$ .

## Proof.

Let  $\zeta \in \tilde{M}_G^2(0, T)$ . We claim that  $A = 0$  if  $A_t := \int_0^t \zeta_s ds$  is a  $G$ -martingale. In fact  $A_t$  must be a non-increasing  $G$ -martingale by  $G$ -martingale decomposition theorem. For  $n \in \mathbb{N}$ , set  $h = T/n$  and

$$\hat{\zeta}_t^n = \sum_{k=0}^{n-1} \mathbf{1}_{(kh, (k+1)h]}(t) \frac{1}{h} \int_{kh}^{(k+1)h} \zeta_s ds,$$

$$\check{\zeta}_t^n = \sum_{k=1}^{n-1} \mathbf{1}_{(kh, (k+1)h]}(t) \frac{1}{h} \int_{(k-1)h}^{kh} \zeta_s ds.$$

For  $t \in (kh, (k+1)h]$ , we have  $\mathbb{E}^G[\hat{\zeta}_t^n - \check{\zeta}_t^n] = \frac{1}{h} \mathbb{E}^G[-(A_{kh} - A_{(k-1)h})]$ .

$$\begin{aligned} 0 \leftarrow \left\{ T \int_0^T \mathbb{E}^G[|\hat{\zeta}_t^n - \check{\zeta}_t^n|^2] dt \right\}^{1/2} &\geq \int_0^T \mathbb{E}^G[\hat{\zeta}_t^n - \check{\zeta}_t^n] dt \\ &= \sum_{k=0}^{n-1} \mathbb{E}^G[-(A_{kh} - A_{(k-1)h})] \end{aligned}$$

By the uniqueness of the decomposition we obtain the following result.

### Proposition.

The metric  $d_{W_G^1}$  is closable in the space  $S_G^2(0, T)$ : Let  $u^n, v^n \in C^\infty(0, T)$  be two Cauchy sequences w.r.t. the metric  $d_{W_G^1}$ . If  $\|u^n - v^n\|_{S_G^2} \rightarrow 0$ , we have  $d_{W_G^1}(u^n, v^n) \rightarrow 0$ .  $\square$



$W_G^1(0, T) :=$  the closure of  $\mathcal{C}^\infty(0, T)$  w.r.t. the metric  $d_{W_G^1}$  in  $S_G^2(0, T)$ .  
 $\mathcal{A}_G, D_x$  is continuously extended to  $W_G^1(0, T)$ .

## Proposition.

Assume  $u \in S_G^2(0, T)$ . Then the following two conditions are equivalent:

(i)  $u \in W_G^1(0, T)$ ;

(ii)  $u(\omega_t) = u(\omega_0) + \int_0^t \eta(\omega_s) ds + \int_0^t v(\omega_s) dB_s + K_t$  with  
 $\eta \in \tilde{M}_G^2(0, T), v \in M_G^2(0, T), K_T \in L_G^2(\Omega_T)$  and  $K_t$  a non-increasing  
 $G$ -martingale.

Moreover, we have  $\mathcal{A}_G u = \eta$  and  $D_x u = v$ . □

Let's consider a special case of backward SDEs driven by  $G$ -Brownian motion studied in [HJPS2012] (see the Appendix): to find  $(Y, Z, K)$  with  $Y \in S_G^2(0, T)$ ,  $Z \in M_G^2(0, T)$ ,  $K_T \in L_G^2(\Omega_T)$  and  $K_t$  a non-increasing  $G$ -martingale satisfying

$$Y_t = \xi + \int_t^T f(s, Y_s, Z_s) ds - \int_t^T Z_s dB_s - (K_T - K_t). \quad (14)$$

The related path dependent PDEs: to find  $u \in W_G^1(0, T)$ ,  
s.t.

$$\begin{aligned} \mathcal{A}_G u(\omega_t) + f(t, u(\omega_t), D_x u(\omega_t)) &= 0, \quad t \in [0, T), & \text{(PPDE)} \\ u(\omega_T) &= \xi(\omega_T). & \text{(TC)} \end{aligned}$$

**Assumption 3.**  $f(t, Y_t, Z_t) \in \tilde{M}_G^2(0, T)$  for any  
 $(Y, Z) \in S_G^2(0, T) \times M_G^2(0, T)$ .

## Theorem

Let  $(Y, Z)$  be a solution to the backward SDE (14). Then we have  $u(\omega_t) := Y_t(\omega) \in W_G^1(0, T)$  with  $D_x u(\omega_t) = Z_t(\omega)$ .

Moreover, for  $u(\omega_t) \in W_G^1(0, T)$ , the following (i) and (ii) are equivalent:

- (i)  $(u, D_x u)$  is a solution to the backward SDE;
- (ii)  $u$  is a solution to the path dependent PDE.

## Corollary

$u \in S_G^2(0, T)$  is a  $G$ -martingale if and only if  $u \in W_G^1(0, T)$  and  $\mathcal{A}_G u(\omega_t) = 0$ .

## Proof.

By the  $G$ -martingale decomposition theorem,  $u \in S_G^2(0, T)$  is a  $G$ -martingale if and only if  $u$  is a solution of backward SDE (14) with  $f = 0$ . □

In [HJPS2012] the authors studied the backward stochastic differential equations driven by a  $G$ -Brownian motion  $(B_t)_{t \geq 0}$  in the following form:

$$Y_t = \xi + \int_t^T f(s, Y_s, Z_s) ds - \int_t^T Z_s dB_s - (K_T - K_t). \quad (15)$$

where  $K$  is a non-increasing  $G$ -martingale.

# Main result: existence and uniqueness:

Solution  $(Y, Z, K)$  for equation (15) in the  $G$ -framework under the following assumption: there exists some  $\beta > 1$  such that

(H1) for any  $y, z$ ,  $f(\cdot, \cdot, y, z) \in M_G^\beta(0, T)$ ;

(H2)  $|f(\omega_t, y, z) - f(\omega_t, y', z')| \leq L(|y - y'| + |z - z'|)$  for some  $L > 0$ .

Denote by  $\mathfrak{S}_G^\alpha(0, T)$  the collection of processes  $(Y, Z, K)$  such that  $Y \in S_G^\alpha(0, T)$ ,  $Z \in H_G^\alpha(0, T)$ ,  $K$  is a decreasing  $G$ -martingale with  $K_0 = 0$  and  $K_T \in L_G^\alpha(\Omega_T)$ .

### Definition

Let  $\xi \in L_G^\beta(\Omega_T)$  and  $f$  satisfy (H1) and (H2) for some  $\beta > 1$ . A triplet of processes  $(Y, Z, K)$  is called a solution of equation (15) if for some  $1 < \alpha \leq \beta$  the following properties hold:

- (a)  $(Y, Z, K) \in \mathfrak{S}_G^\alpha(0, T)$ ;
- (b)  $Y_t = \xi + \int_t^T f(s, Y_s, Z_s) ds - \int_t^T Z_s dB_s - (K_T - K_t)$ .



The main result in [HJPS2012] is the following theorem:

## Theorem

*Assume that  $\xi \in L_G^\beta(\Omega_T)$  and  $f$  satisfies (H1) and (H2) for some  $\beta > 1$ . Then equation (15) has a unique solution  $(Y, Z, K)$ . Moreover, for any  $1 < \alpha < \beta$  we have  $Y \in S_G^\alpha(0, T)$ ,  $Z \in H_G^\alpha(0, T)$  and  $K_T \in L_G^\alpha(\Omega_T)$ .*

# Merci