

# Integrability of homogeneous systems; Results and problems

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October 31, 2006

# Outline

- 1 Homogeneous equations
- 2 Theory
- 3 Main results
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# Homogeneous Hamiltonian equations

Integrability of Hamiltonian systems given by

$$H = \frac{1}{2} \sum_{i=1}^n p_i^2 + V(\mathbf{q}), \quad (\mathbf{q}, \mathbf{p}) \in \mathbb{C}^{2n},$$

$$V(\mathbf{q}) \in \mathbb{C}[\mathbf{q}], \quad \deg V = k > 2,$$

$V(\mathbf{q})$  — homogeneous; i.e., integrability of

$$\frac{d}{dt} q_i = \frac{\partial H}{\partial p_i} = p_i, \quad \frac{d}{dt} p_i = -\frac{\partial H}{\partial q_i} = -\frac{\partial V}{\partial q_i}, \quad i = 1, \dots, n$$

$$\frac{d^2}{dt^2} q_i = -F_i(\mathbf{q}), \quad F_i(\mathbf{q}) = \frac{\partial V}{\partial q_i}, \quad i = 1, \dots, n,$$

# Homogeneous Newton's equations

Integrability of the system of autonomous Newton equations

$$\ddot{\mathbf{q}} = -\mathbf{F}(\mathbf{q}), \quad \mathbf{q} = (q_1, \dots, q_n)^T \in \mathbb{C}^n,$$

where  $F_i \in \mathbb{C}[\mathbf{q}]$  are homogeneous, and

$$\deg F_i = l := k - 1, \text{ for } i = 1, \dots, n.$$

$$\frac{d}{dt}q_i = p_i, \quad \frac{d}{dt}p_i = -F_i, \quad i = 1, \dots, n$$

# Integrability in the Liouville sense

$H_i = H_i(\mathbf{q}, \mathbf{p})$ , for  $i = 1, \dots, n$  are first integrals,

$$\{H_i, H_j\} := \sum_{k=1}^n \frac{\partial H_i}{\partial q_k} \frac{\partial H_j}{\partial p_k} - \frac{\partial H_i}{\partial p_k} \frac{\partial H_j}{\partial q_k} = 0$$

## Definition

We say that the Hamiltonian system with  $n$  degrees of freedom is integrable in the Liouville sense if it admits  $n$  functionally independent first integrals that commute.

# Integrability in the Jacobi sense

## Definition

We say that the system of  $n$  first order differential equations is integrable in the Jacobi sense if it admits an invariant  $n$ -form and possesses  $n - 2$  functionally independent first integrals.

$$\mathbf{v}(\mathbf{q}, \mathbf{p}) := \sum_{i=1}^n \left( p_i \frac{\partial}{\partial q_i} - F_i(\mathbf{q}) \frac{\partial}{\partial p_i} \right), \quad \mathbf{p} := \dot{\mathbf{q}},$$

$$\operatorname{div}(\mathbf{v}) := \sum_{i=1}^n \frac{\partial v_i}{\partial x_i} = 0,$$

invariant  $2n$ -form

$$\mu = dq_1 \wedge \cdots \wedge dq_n \wedge dp_1 \wedge \cdots \wedge dp_n$$

## Fact

For integrability in the Jacobi sense of Newton's equations  $2n - 2$  first integrals are necessary.

# Classes of equivalence

- **Equivalent potentials:**

$$V(\mathbf{q}) \sim V_A(\mathbf{q}) = V(A\mathbf{q}), \quad A \in \text{PO}(n, \mathbb{C}),$$

$$\text{PO}(n, \mathbb{C}) := \{A \in \text{GL}(n, \mathbb{C}) \mid AA^T = \alpha E, \quad \alpha \in \mathbb{C}\}.$$

- We say that forces  $\mathbf{F}$  and  $\tilde{\mathbf{F}}$  are **equivalent** if there exists a non-singular matrix  $A \in \text{GL}(n, \mathbb{C})$  such that  $\tilde{\mathbf{F}}(\mathbf{q}) = A^{-1}\mathbf{F}(A\mathbf{q})$ .
- Integrability of one system implies the integrability of all systems belonging to the same equivalence class.



# Problem

## Problem

How to find integrable Hamiltonian and Newton systems?

## Known methods

- Kovalevskaya analysis  $\implies$  Painlevé analysis
- Ziglin theory
- **Morales-Ramis theory**

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# Variational equations

## Main Idea

A non-linear system leaves fingerprints of its properties in variational equations.

For a system

$$\dot{\mathbf{x}} = \mathbf{v}(\mathbf{x}), \quad \mathbf{x} = (x_1, \dots, x_n)^T \in \mathbb{C}^n.$$

with a known non-equilibrium particular solution  $\varphi(t)$  the substitution  $\mathbf{x} = \varphi(t) + \xi$  is applied.

Variational equations

$$\frac{d}{dt}\xi = A(t)\xi, \quad A(t) = \frac{\partial \mathbf{v}}{\partial \mathbf{x}}(\varphi(t)).$$

# First integrals of the system and its VEs

## First implication

If the system possesses  $k$  functionally independent meromorphic first integrals  $F_1, \dots, F_k$ , then VEs have  $k$  functionally independent rational first integrals.

## Second implication

If system has  $k$  functionally independent first integrals which are meromorphic in a connected neighbourhood of a non-equilibrium solution  $\varphi(t)$ , then the differential Galois group  $\mathcal{G}$  of the variational equations along  $\varphi(t)$  has  $k$  functionally independent rational invariants.

# Hamiltonian systems – Morales-Ramis theorem

## Theorem

*Assume that a Hamiltonian system is meromorphically integrable in the Liouville sense in a neighbourhood of the analytic phase curve  $\Gamma$ , and that the variational equations along  $\Gamma$  are Fuchsian. Then the identity component of the differential Galois group of the variational equations along  $\Gamma$  is Abelian.*

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# Particular solutions

## Definition

Darboux point  $\mathbf{d} \in \mathbb{C}^n$  is a solution of

$$\mathbf{F}(\mathbf{d}) = \mathbf{d},$$

and all  $\tilde{\mathbf{d}} = \gamma \mathbf{d}$  where  $\gamma \in \mathbb{C}^* = \mathbb{C} \setminus \{0\}$  define the same Darboux point.

Particular solution

$$\mathbf{q}(t) = \varphi(t) \mathbf{d}, \quad \text{provided} \quad \ddot{\varphi} = -\varphi^{k-1}.$$

$$\dot{\varphi}^2 = \frac{2}{k} (\varepsilon - \varphi^k), \quad \varepsilon \in \mathbb{C}^*.$$

# Variational equations

$$\ddot{\mathbf{x}} = -\varphi(t)^{k-2} \mathbf{F}'(\mathbf{d}) \mathbf{x},$$

where  $\mathbf{F}'(\mathbf{d})$  is the Jacobi matrix of  $\mathbf{F}$  calculated at  $\mathbf{d}$ . In the Hamiltonian case  $\mathbf{F}'(\mathbf{d}) = V''(\mathbf{d})$

If  $F'(\mathbf{d})$  is diagonalisable

$$\ddot{\eta}_i = \lambda_i \varphi(t)^{k-2} \eta_i, \quad i = 1, \dots, n,$$

where  $\lambda_i$  for  $i = 1, \dots, n$  are eigenvalues of  $F'(\mathbf{d})$ .

By homogeneity of  $\mathbf{F}$ ,  $\lambda_n = k - 1$ .

Differential Galois group

$$\mathcal{G} = \mathcal{G}(\lambda_1) \times \cdots \times \mathcal{G}(\lambda_n) \subset \mathrm{Sp}(2n, \mathbb{C}), \quad \mathcal{G}(\lambda_i) \subset \mathrm{Sp}(2, \mathbb{C}).$$



# Transformation to hypergeometric equations

$$z := \frac{1}{k} \varphi(t)^k.$$

$$\left. \begin{aligned} z(1-z)\eta'' + [c - (a+b+1)z]\eta' - ab\eta &= 0, \\ a+b = \frac{k-2}{2k}, \quad ab = -\frac{\lambda_j}{2k}, \quad c = 1 - \frac{1}{k}. \end{aligned} \right\}$$

$$G = G(\lambda_1) \times \cdots \times G(\lambda_n) \subset GL(2n, \mathbb{C}), \quad G(\lambda_j) \subset GL(2, \mathbb{C}).$$

Isomorphism of identity components of  $\mathcal{G}(\lambda_j)$  and  $G(\lambda_j)$ .

## Other Morales-Ramis Theorem

If the Hamiltonian system with homogeneous potential is meromorphically integrable then each  $(k, \lambda_i)$  belong to the following list:

$$\begin{aligned} & \left( k, p + \frac{k}{2} p(p-1) \right), \quad \left( k, \frac{1}{2} \left[ \frac{k-1}{k} + p(p+1)k \right] \right), \\ & \left( 3, -\frac{1}{24} + \frac{3}{32} (1+4p)^2 \right), \quad \left( 3, -\frac{1}{24} + \frac{3}{50} (1+5p)^2 \right), \\ & \left( 3, -\frac{1}{24} + \frac{3}{50} (2+5p)^2 \right), \quad \left( 4, -\frac{1}{8} + \frac{2}{9} (1+3p)^2 \right), \\ & \left( 5, -\frac{9}{40} + \frac{5}{18} (1+3p)^2 \right), \quad \left( 5, -\frac{9}{40} + \frac{1}{10} (2+5p)^2 \right), \end{aligned}$$

where  $p \in \mathbb{Z}$ .

# What for Newton's equations?

## Theorem

*Assume that the Newton system with polynomial homogeneous polynomial right-hand sides of degree  $l = k - 1 > 1$  is integrable in the Jacobi sense. Then if  $\mathbf{d}$  is a Darboux point such that  $\mathbf{F}'(\mathbf{d})$  is semi-simple and  $\lambda_1, \dots, \lambda_n$  are the corresponding eigenvalues, then  $(k, \lambda_i)$  for  $i = 1, \dots, n$  belong to the following list*

case	$k$	$\lambda$	
1.	$k$	$p + \frac{k}{2}p(p-1)$	
2.	$k$	$\frac{1}{2} \left( \frac{k-1}{k} + p(p+1)k \right)$	
3.	3	$-\frac{1}{24} + \frac{1}{6}(1+3p)^2,$ $-\frac{1}{24} + \frac{3}{50}(1+5p)^2,$	$-\frac{1}{24} + \frac{3}{32}(1+4p)^2$ $-\frac{1}{24} + \frac{3}{50}(2+5p)^2$
4.	4	$-\frac{1}{8} + \frac{2}{9}(1+3p)^2$	
5.	5	$-\frac{9}{40} + \frac{5}{18}(1+3p)^2,$	$-\frac{9}{40} + \frac{1}{10}(2+5p)^2,$

where  $p$  is an integer. Moreover, among  $(k, \lambda_i)$  at most two belong to item 1 of the above list.

## Relations between $\lambda_j$

$\Lambda_j = \lambda_j - 1$ , for  $i = 1, \dots, n - 1$ ,

$\Lambda = \Lambda(\mathbf{d}) = (\Lambda_1, \dots, \Lambda_{n-1}) \in \mathbb{C}^{n-1}$ .  $\tau_i$ , for  $i = 0, \dots, n - 1$  – elementary symmetric polynomials in  $(n - 1)$  variables.

### Theorem

Assume that  $\mathbf{F}$  has exactly  $D(n, k) = [(k - 1)^n - 1] / (k - 2)$  Darboux points  $\mathbf{d} \in \mathcal{D}_{\mathbf{F}}$ . Then  $\Lambda(\mathbf{d})$  satisfy the following relations:

$$\sum_{\mathbf{d} \in \mathcal{D}_{\mathbf{F}}} \frac{\tau_1(\Lambda(\mathbf{d}))^r}{\tau_{n-1}(\Lambda(\mathbf{d}))} = (-1)^n (n + k - 2)^r, \quad 0 \leq r \leq n - 1,$$

or, alternatively

$$\sum_{\mathbf{d} \in \mathcal{D}_{\mathbf{F}}} \frac{\tau_r(\Lambda(\mathbf{d}))}{\tau_{n-1}(\Lambda(\mathbf{d}))} = (-1)^{n-r-1} \sum_{i=0}^r \binom{n-r-1}{r-i} (k-1)^i.$$

## $\Lambda_j$ are Kovalevskaya exponents

The auxiliary system related to Newton system with force field  $\mathbf{F}$  or Hamiltonian system with  $\mathbf{F} = V'$

$$\frac{d}{dt}\mathbf{q} = \mathbf{F}(\mathbf{q}), \quad \mathbf{q} \in \mathbb{C}^n.$$

$F_i$  are homogeneous polynomials of degree  $l$ .

The Kovalevskaya matrix  $\mathbf{K}(\mathbf{d})$  at a Darboux point  $\mathbf{d} \in \mathcal{D}_{\mathbf{F}}$

$$\mathbf{K}(\mathbf{d}) := \mathbf{F}'(\mathbf{d}) - \mathbf{E},$$

Eigenvalues  $\Lambda_i = \Lambda_i(\mathbf{d})$ ,  $i = 1, \dots, n$ , of the Kovalevskaya matrix  $\mathbf{K}(\mathbf{d})$  are called the Kovalevskaya exponents.

By homogeneity one of them, let us say  $\Lambda_n$ , is trivial and it is  $\Lambda_n = l - 1$ .

$\Lambda(\mathbf{d}) = (\Lambda_1(\mathbf{d}), \dots, \Lambda_{n-1}(\mathbf{d}))$  – nontrivial Kovalevskaya exponents.

## Guillot theorem (2004)

### Theorem

*Assume that the above system with homogeneous polynomial right hand sides of degree  $l$  has the maximal number of Darboux points and let  $S$  be a symmetric homogeneous polynomial in  $n - 1$  variables of degree less than  $n$ . Then, the number*

$$R := \sum_{\mathbf{d} \in \mathcal{D}_F} \frac{S(\Lambda(\mathbf{d}))}{\tau_{n-1}(\Lambda(\mathbf{d}))},$$

*depends only on the choice of  $S$ , dimension  $n$  and homogeneity degree  $l$ .*

$n$ -dimensional generalisation of the Jouanolou system:

$$\dot{x}_i = x_{i+1}^l, \quad 1 \leq i \leq n, \quad x_{n+1} \equiv x_j.$$

## Finiteness of choices of $\Lambda_j$

$$\sum_{\mathbf{d} \in \mathcal{D}_V} \sum_{i=1}^{n-1} \frac{1}{\Lambda_i(\mathbf{d})} = -\frac{(k-1)^n - n(k-2) - 1}{(k-2)^2}.$$

### Theorem

*Let us assume that homogeneous system possesses the maximal number of Darboux points. Then for homogeneous Hamiltonian as well as Newton equations there exist only finite number of sets  $(\Lambda_1, \dots, \Lambda_n)$  at each Darboux point belonging to the appropriate sets of rational numbers (depending on  $k$ ) satisfying the above relation.*



## Examples of admissible $\Lambda_i$ for $n = 2$ and $k = 3, 4$

$$\begin{array}{c} \overline{\overline{\{\Lambda_1, \Lambda_2, \Lambda_3\}}} \\ \overline{\overline{\{-1, -1, 1\}}} \\ \overline{\overline{\{-2/3, 4, 4\}}} \\ \overline{\overline{\{-7/8, 14, 14\}}} \\ \overline{\overline{\{-2/3, 7/3, 14\}}}. \end{array}$$

$$\begin{array}{c} \overline{\overline{\overline{\{\Lambda_1, \Lambda_2, \Lambda_3, \Lambda_4\}}}} \\ \overline{\overline{\overline{\{-1, -1, 2, 2\}}}} \\ \overline{\overline{\overline{\{-5/8, 5, 5, 5\}}}} \\ \overline{\overline{\overline{\{-5/8, 2, 20, 20\}}}} \\ \overline{\overline{\overline{\{-5/8, 27/8, 27/8, 135\}}}} \\ \overline{\overline{\overline{\{-5/8, 2, 14, 35\}}}}. \end{array}$$

## Two types of integrability obstructions

- 1 all  $\Lambda_j = \lambda_j - 1$  must belong to appropriate sets of rational numbers (tables in Morales-Ramis theorem for Hamiltonian systems and our theorem for Newton systems). This is a local analysis.
- 2 between  $\Lambda_j$  calculated at all Darboux points some universal relations exist. This is a global analysis.

## Algorithm for integrability analysis

- 1 Fix  $k$  and postulate the general form of polynomial potential  $V$  or force field  $\mathbf{F}$  with undetermined coefficients.
- 2 Determine sets for that belong all  $\Lambda_j$ .
- 3 Using finiteness relation find all sets  $(\Lambda_1, \dots, \Lambda_n)$  at each Darboux point.
- 4 using  $\Lambda_j$  reconstruct  $V$  or  $\mathbf{F}$ , i.e. find all undetermined coefficients.
- 5 If after reconstruction some polynomial coefficients become free parameters apply stronger integrability obstruction due to variational equations of higher orders or repeat analysis with different particular solution.
- 6 analyse nongeneric cases (with smaller number of Darboux points, multiple Darboux points and without Darboux points).

## Case $n = 2$ . Hamilton systems

### Theorem

Assume that there exist  $1 \leq l \leq k$  **simple** Darboux points and in  $V$  factor  $(q_2 \pm iq_1)$  can appear at most with multiplicity 1, then  $\Lambda_j$  satisfy

$$\sum_{i=1}^l \frac{1}{\Lambda_i} = -1.$$

### Theorem

Assume that there exist  $1 \leq l \leq k$  **simple** Darboux points and that  $r_{\pm} \neq l/2$  are multiplicities of  $(q_2 \pm iq_1)$  in  $V$ , then

$$\sum_{i=1}^l \frac{1}{\Lambda_i} = -1 - \theta_{r_+,2} \frac{r_+}{k - 2r_+} - \theta_{r_-,2} \frac{r_-}{k - 2r_-},$$

$$\theta_{x,y} := \begin{cases} 0 & \text{for } x < y, \\ 1 & \text{for } x \geq y. \end{cases}$$

## Case $n = 2$ . Newton systems

### Theorem

Assume that forces  $\mathbf{F} = (F_1, F_2)$  satisfy the following conditions

**A.1**  $\mathbf{F}$  admits  $1 \leq l \leq k$  simple Darboux points;

**A.2** if  $F_1(\mathbf{q})$  and  $G(\mathbf{q}) := q_2 F_1(\mathbf{q}) - q_1 F_2(\mathbf{q})$  have a common linear factor  $P = \alpha q_1 + \beta q_2$ ,  $|\alpha| + |\beta| \neq 0$ , then the multiplicity of  $P$  in  $G$  is not greater than the multiplicity of  $P$  in  $F_1$ .

Let us  $\Lambda_i$  is the non-trivial Kovalevskaya exponent of  $\mathbf{F}$  at  $i$ -th Darboux point for  $i = 1, \dots, l$ . Then

$$\sum_{i=1}^l \frac{1}{\Lambda_i} = -1.$$

# Non-maximal number of Darboux points – Hamiltonian case

The number of Darboux points is not maximal if and only if  $V$  has a multiple factor.

A generic cases:  $V$  has a factor different that  $(q_2 \pm i q_1)$  with multiplicity 2. Such potential are equivalent to

$$W(q_1, q_2) = q_1^2 \tilde{V}(q_1, q_2), \quad \deg \tilde{V} = k - 2.$$

## Theorem

*Hamiltonian system with potential  $W$  does not admit an additional rational first integral.*

# Non-maximal number of Darboux points – Newton case

If a force  $\mathbf{F} = (F_1, F_2)$  does not have the maximal number of Darboux points, then polynomials  $F_1$  and  $F_2$  have a common factor  $P \in \mathbb{C}[\mathbf{q}] \setminus \mathbb{C}$ , i.e.,  $F_i = P\tilde{F}_i$ , where  $\tilde{F}_i \in \mathbb{C}[\mathbf{q}]$  for  $i = 1, 2$ .

## Theorem

Assume that  $\tilde{F}_1, \tilde{F}_2 \in \mathbb{C}[\mathbf{q}]$  are homogeneous polynomials of degree  $k - 2$ . If  $\deg_{q_1} \tilde{F}_2 = k - 2$ , then system

$$\dot{q}_1 = p_1, \quad \dot{p}_1 = -q_2 \tilde{F}_1(q_1, q_2), \quad \dot{q}_2 = p_2, \quad \dot{p}_2 = -q_2 \tilde{F}_2(q_1, q_2),$$

does not admit two functionally independent polynomial first integrals.

## Infinitely many Darboux points

In the Hamiltonian case – radial potentials i.e.  $V = V(r)$ ,  
 $r^2 = q_1^2 + q_2^2$ .

In the Newton case a system possesses infinitely many Darboux points iff

$$F_1 = \sum_{i=0}^{k-2} f_i q_1^{k-1-i} q_2^i \quad \text{and} \quad F_2 = \sum_{i=0}^{k-2} f_i q_1^{k-2-i} q_2^{i+1}.$$

$$I_1 = q_1 p_2 - p_1 q_2.$$

For  $k = 3$  and  $k = 4$  the Newton equations with the above form of forces are integrable

$$I_2 = 3(f_0 p_1 + f_1 p_2)^2 + 2(f_0 q_1 + f_1 q_2)^3,$$

$$I_2 = 2(f_0 p_1^2 + f_1 p_1 p_2 + f_2 p_2^2) + (f_0 q_1^2 + f_1 q_1 q_2 + f_2 q_2^2)^2,$$



# Hamiltonian systems without Darboux points

## Lemma

*If potential  $V$  of degree  $k > 2$  does not have Darboux points, then all its linear factors are multiple. Moreover,  $V = V_{k,l}$*

$$V_{k,l} = \alpha (q_2 - iq_1)^l (q_2 + iq_1)^{k-l}, \quad l = 0, \dots, k, \quad \alpha \in \mathbb{C}^*$$

*for some  $l$ , except for the case when  $k = 2l$  and  $V$  has a factor  $(q_2 \pm iq_1)$  with multiplicity  $l$ .*

$$V = (q_2 - iq_1)^l (q_2 + iq_1)^p q_2^{l-p}, \quad p > 0, \quad l > 1, \quad l > p + 1,$$

$$V = (q_2 - iq_1)^l (q_2 + iq_1)^{l-r-s} q_2^r \left( q_2 - i \frac{r+s}{r-s} q_1 \right)^s,$$

$$l > 1, \quad r > 0, \quad s > 0, \quad l - r - s \in \mathbb{N}_0 \setminus \{1\},$$

# Hamiltonian systems without Darboux points

$$\begin{aligned}
 V &= (q_2 - iq_1)^l (q_2 + iq_1)^{l-p-r-s} q_2^r \\
 &\times \left( q_2 - \frac{i(r-s)(p+r+s) - 2\sqrt{prs(p+r+s)}}{(r-s)^2 + p(r+s)} q_1 \right)^s \\
 &\times \left( q_2 - \frac{i(r-p)(p+r+s) + 2\sqrt{prs(p+r+s)}}{(p-r)^2 + s(p+r)} q_1 \right)^p,
 \end{aligned}$$

$$l > 2, \quad s \in \mathbb{N} \setminus \{1\}, \quad p \in \mathbb{N} \setminus \{1\}, \quad r > 0,$$

$$l - p - r - s = 0 \quad \text{or} \quad l - p - r - s > 1,$$

$$V = q_1 q_2 (q_2 - iq_1)^l (q_2 + iq_1)^{l-2}, \quad l \in \mathbb{N} \setminus \{1, 3\},$$

$$V = q_1 (q_2 - iq_1)^l (q_2 + iq_1)^{l-r-1} \left( q_2 + i \frac{r-1}{r+1} q_1 \right)^r, \quad r = 0, 2, \dots, l-$$

# Newton systems without Darboux points

## Theorem

Assume that a force  $\mathbf{F} = (F_1, F_2)$ ,  $\deg F_i = k - 1$ , does not have any Darboux point. Then

$$F_1 = \prod_{i=1}^{k-1} (q_2 - z_i q_1), \quad F_2 = q_2 F_1 - \prod_{i=1}^p (q_2 - z_i q_1)^{n_i},$$

where  $1 \leq p \leq k - 1$ ,  $z_i \in \mathbb{C}$ , and  $z_1, \dots, z_p$  are pairwise different;  $n_i \in \mathbb{N}$  and  $n_1 + \dots + n_p = k$ . Moreover, if there exist  $1 \leq j \leq p$  such that  $n_j = 1$ , then the Newton equations with force  $\mathbf{F}$  do not admit two functionally independent polynomial first integrals.

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## Summary

- It is possible to express the necessary integrability conditions in the language of eigenvalues  $\Lambda_j$  of Jacobi matrix of the right-hand sides.
- There exist universal relations between these eigenvalues.
- Using these relations one can prove that only finite number of admissible  $\Lambda_j$  satisfying the necessary integrability conditions is possible.
- One can find forms of the potential for Hamiltonian systems and force fields for Newton systems.

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