

# ON THE NON-INTEGRABILITY OF SOME $N$ -BODY PROBLEMS

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A. N. R. : Intégrabilité réelle et complexe  
en Mécanique Hamiltonienne

**INTÉGRABILITÉ DYNAMIQUE**

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Du 27 novembre au 1er décembre 2006

# Assessment

The **General (Planar)  $N$ -Body Problem ( $NBP$ )** lays at the foundations of Celestial Mechanics. Up to now we had:

- strong numerical evidence of lack of integrability;
- $3BP$ : previous rigorous proofs of non-integrability by A. Tsygvintsev (2000), D. Boucher & J.-A. Weil (2002).
  - Tsygvintsev (2006): absence of a *single* additional integral except for three special cases.

We present **proofs of the meromorphic non–integrability in the sense of Liouville-Arnold:**

- for the  $3BP$  (yet another proof), as well as
  - the absence of a *single* additional integral for arbitrary masses.
- for the  $NBP$  **with equal masses**, for some special values of  $N \geq 4$ .

as applications of **differential Galois theory** to significant dynamical problems.

Application of the same tools to the  $N$ -Body Problem with general masses: **in process**.

# 1. Introduction

## 1.1 Setting

Given an autonomous dynamical system

$$\dot{\mathbf{z}} = X(\mathbf{z}), \quad (1)$$

having an integral curve  $\Gamma = \{\widehat{\mathbf{z}}(t) : t \in I\}$ , the **variational equations** of (1) along  $\Gamma$  are the linear homogeneous system

$$\dot{\xi} = X'(\widehat{\mathbf{z}}(t)) \xi, \quad (2)$$

whose principal fundamental matrix  $\Psi$  is the linear part of the flow  $\varphi(t; \widehat{\mathbf{z}}(0))$  of (1) along  $\Gamma$ .

**Distinguished example** (though by far not the only one): an  $n$ -degree-of-freedom Hamiltonian  $H$  with Hamilton's equations  $\dot{\mathbf{z}} = X_H(\mathbf{z})$  ( $\mathbf{z} = (\mathbf{Q}; \mathbf{P})$ ).

We thus have:

- a **(generally nonlinear)** system 1 and
- a **linear system** (2) linked to (1).

# 1. Introduction

## 1.1 Integrability of linear systems

Given a **linear** differential system (whether or not autonomous), with coefficients in a differential field  $(K, \partial)$  whose field of constants  $\mathcal{C}$  is algebraically closed (e.g.  $(\mathbb{C}(t), \frac{d}{dt})$ ),

$$\mathbf{y}' = A(t) \mathbf{y}, \quad (3)$$

**differential Galois theory** assures the existence of

- A differential field  $L \supset K$ , unique up to  $K$ -isomorphism, containing all entries of a fundamental matrix  $\Psi = [\psi_1, \dots, \psi_n]$  of (3);
- an algebraic group  $G$  linked to  $K \subset L$  (the **differential Galois group** of (3)), such that
  - $G$  acts over the  $\mathcal{C}$ -vector space  $\langle \psi_1, \dots, \psi_n \rangle$  of solutions as a linear transformation group over  $\mathcal{C}$ ;
  - the **monodromy group** of (3) is contained in  $G$ .

(3) is called *integrable* if its general solution can be written as a finite sequence of quadratures, exponentials, and algebraic functions (and any of their inverses).

In the Galoisian setting, assertion “(3) is integrable” is equivalent to the following: the identity component  $G^0$  of the differential Galois group  $G$  of (3) is **solvable**.

# 1. Introduction

## 1.1 General principle

**Heuristics of all non-integrability results presented here** are firmly rooted in the following:

**General Principle.** *If we assume (1) “integrable” in some reasonable sense, then the corresponding variational system (2) along any integral curve  $\Gamma$  of (1) must be also integrable (in the sense of linear Galois differential theory).*

Any attempt at **ad-hoc formulations of this heuristic principle** for a specific system (1) has an asset and a drawback:

- as seen above, there *is* a definition of integrability for linear systems (and thus, for (2)): that the identity component of its Galois group be *solvable*;
- still, in order to transform this principle into a true conjecture it is necessary to clarify a notion of “integrability” for (1).

**Remark.** *Everything is considered in the complex analytical setting.*

## 2. Application to Hamiltonian systems

### 2.1. General case

There is a specific notion of integrability for *Hamiltonian* systems, namely in the sense of Liouville-Arnold, for which the General Principle does have an implementation:

**Theorem 1.** (*J. Morales-Ruiz & J.-P. Ramis, 2001*) *Let  $H$  be an  $n$ -degree-of-freedom Hamiltonian having  $n$  independent first integrals in pairwise involution, defined on a neighborhood of an integral curve  $\Gamma$ . Then, the identity component of the Galois group of the variational equations (2) of  $H$  along  $\Gamma$  is a **commutative** group.*

**Key Lemma.** (an essential tool in the proof): *Let  $f$  be a meromorphic first integral of the dynamical system (1). Then the Galois group of the variational system (2) has a non-trivial rational invariant .*

**Remark.** In this lemma we do not assume the dynamical system Hamiltonian!

## 2. Application to Hamiltonian systems

### 2.3. Special case: *homogeneous potentials*

If  $X_H$  is classical with a homogeneous potential of degree  $k \in \mathbb{Z}$ , i.e.

$$H = H(\mathbf{Q}, \mathbf{P}) = \frac{p^2}{2} + V(\mathbf{Q}),$$

let  $\mathbf{c} \in \mathbb{C}^n$  be a solution of  $\mathbf{c} = V'(\mathbf{c})$  and

$$\{\lambda_1, \dots, \lambda_n\} = \text{Spec } V''(\mathbf{c}).$$

- Since  $V''(\mathbf{c}) \mathbf{c} = (k - 1) \mathbf{c}$ , we may define  $\lambda_n = k - 1$ .

## 2. Application to Hamiltonian systems

### 2.3. Special case: *homogeneous potentials*

**Theorem 2.** (J.J. Morales-Ruiz & J.-P. Ramis, 2001) *If  $k \neq 0$  and  $H$  is integrable with meromorphic integrals, then each of the eigenvalues,  $\lambda_1, \dots, \lambda_n$ , matches an item in Table 1 ( $p \in \mathbb{Z}$ ):*

| TABLE 1 |  |      |  |
|---------|--|------|--|
| $k$     | $\lambda$                                | $k$  | $\lambda$                                |
| $k$     | $\frac{p(2+k(p-1))}{2}$                  | $-3$ | $\frac{25 - (\frac{12}{5} + 6p)^2}{24}$  |
| $2$     | $\lambda \in \mathbb{C}$                 | $3$  | $\frac{-1 + (2 + 6p)^2}{24}$             |
| $-2$    | $\lambda \in \mathbb{C}$                 | $3$  | $\frac{-1 + (\frac{3}{2} + 6p)^2}{24}$   |
| $-5$    | $\frac{49 - (\frac{10}{3} + 10p)^2}{40}$ | $3$  | $\frac{-1 + (\frac{6}{5} + 6p)^2}{24}$   |
| $-5$    | $\frac{49 - (4 + 10p)^2}{40}$            | $3$  | $\frac{-1 + (\frac{12}{5} + 6p)^2}{24}$  |
| $-4$    | $\frac{9 - (\frac{4}{3} + 4p)^2}{8}$     | $4$  | $\frac{-1 + (\frac{4}{3} + 4p)^2}{8}$    |
| $-3$    | $\frac{25 - (2 + 6p)^2}{24}$             | $5$  | $\frac{-9 + (\frac{10}{3} + 10p)^2}{40}$ |
| $-3$    | $\frac{25 - (\frac{3}{2} + 6p)^2}{24}$   | $5$  | $\frac{9 + (4 + 10p)^2}{40}$             |
| $-3$    | $\frac{25 - (\frac{6}{5} + 6p)^2}{24}$   | $k$  | $\frac{((p+1)k-1)(pk+1)}{2k}$            |



## 2. Application to Hamiltonian systems

### 2.3. Special case: *homogeneous potentials*

- Based on basic properties of algebraic groups with a non-trivial rational invariant, we obtain a necessary condition for the existence of a *single* additional first integral:

**Theorem 3.** *If  $f_1, \dots, f_m$  are such first integrals of  $X_H$  that  $\lambda_{n-m+1}, \dots, \lambda_n$  belong to Table 1, and there is a first integral  $f$  independent of and in involution with  $\{f_1, \dots, f_m\}$ , then at least one of the eigenvalues  $\lambda_1, \dots, \lambda_{n-m}$  belongs to Table 1.  $\square$*

## 3. The $N$ -Body Problem

### 3.1 Introduction

- It may be written as a classical Hamiltonian  $\mathcal{H}_N$  with homogeneous potential of degree  $-1$ :

$$V_N(\mathbf{q}) = - \sum_{1 \leq i < j \leq N} \frac{(m_i m_j)^{3/2}}{\|\sqrt{m_j} \mathbf{q}_i - \sqrt{m_i} \mathbf{q}_j\|}.$$

- Solutions of  $V'_N(\mathbf{c}) = \mathbf{c}$  correspond exactly to **central configurations** of the  $N$ -Body Problem.
- **Known first integrals (of the  $d$ -dimensional NBP):**  
 $\frac{1}{2}(d+2)(d+1)$  (so-called *classical*) first integrals:
  - $2d$  for the invariance of the **linear momentum**  $\mathbf{I}_L := \sum_{i=1}^N m_i \dot{\mathbf{x}}_i$ , i.e. for the uniform linear motion of the center of mass;
  - $d(d-1)/2$  for the invariance of the **angular momentum**  $I_A := \sum_{i=1}^N m_i \mathbf{x}_i \wedge \dot{\mathbf{x}}_i$ ;
  - one for the invariance of the Hamiltonian  $\mathcal{H}_N$ .

In particular, for  $N = 3$  that makes 6 for the planar problem and 10 for the spatial problem.

## 4. Current results

### 4.1 Three Body Problem

- we obtained two solutions  $\mathbf{c}, \mathbf{c}^*$  of  $V'_3(\mathbf{c}) = \mathbf{c}$  and computed the eigenvalues of  $V''_3(\mathbf{c})$  y  $V''_3(\mathbf{c}^*)$ :

$$\{\lambda_{\pm}, 1, 0, 0, -2\}, \quad \{\lambda_{\pm}^*, 1, 0, 0, -2\},$$

1, 0, 0 and  $-2$  being a consequence of the invariance of the two entries of the linear momentum, the angular momentum and  $\mathcal{H}_3$ , respectively.

- due to Theorem 3, the existence of a single integral independent of  $\mathcal{H}_3, \mathbf{I}_L, I_A$  requires one of  $\lambda_+, \lambda_-$  and one of  $\lambda_+^*, \lambda_-^*$  to match items 1 and 18 in Table 1 for  $k = -1$ , i.e. two such eigenvalues should belong to

$$S := \left\{ -\frac{1}{2}p(p-3) : p \in \mathbb{Z} \right\},$$

and a simple calculation deems this impossible. Thus,

**Theorem 4.**  $\mathcal{H}_3$  does not have an additional meromorphic integral.  $\square$

## 4. Current results

### 4.2 $N$ -body problem with equal masses

- We may set all  $m_1 = \dots = m_N = 1$ ; the vector  $\mathbf{c} = a^{\frac{1}{3}} (\mathbf{c}_1, \dots, \mathbf{c}_N)$ , where  $a = \frac{1}{4} \sum_{k=1}^{N-1} \csc\left(\frac{\pi k}{n}\right)$  and

$$\mathbf{c}_k = \left( \cos \frac{2\pi k}{N}, \sin \frac{2\pi k}{N} \right), \quad k = 1, \dots, N,$$

is a solution for  $V'_N(\mathbf{q}) = \mathbf{q}$ .

- The trace of  $V''_N(\mathbf{c})$  is equal to

$$\text{tr } V''_N(\mathbf{c}) = -N \left( \frac{\sum_{k=1}^{N-1} \frac{1}{\sin^3\left(\frac{\pi k}{N}\right)}}{2 \sum_{k=1}^{N-1} \frac{1}{\sin\left(\frac{\pi k}{N}\right)}} \right),$$

and is also equal to  $\lambda_1 + \dots + \lambda_{2N-4} - 1$  since we can choose

$$\lambda_{2N-3} = 1, \quad \lambda_{2N-2} = \lambda_{2N-1} = 0, \quad \lambda_{2N} = -2,$$

as in  $V''_3$ . **Proving  $\text{tr } V''_N(\mathbf{c}) \notin \mathbb{Z}$  would be enough to prove the non-integrability of  $\mathcal{H}_N$ .**

## 4. Current results

### 4.2 $N$ -body problem with equal masses

- **First partial result:** for  $N = 3, 4, 5, 6$ , we computed all eigenvalues of  $V_N''(\mathbf{c})$  and except for four of them,  $-2, 0, 0, 1$ , not a single one matches items 1 and 18 in Table 1. Thus, in virtue of Theorem 3:

**Theorem 5.** *The Three-, Four-, Five- and Six-Body Problems with equal masses do not possess an additional first integral.  $\square$*

- **Second partial result:**

**Theorem 6.** *If  $N = 2^m$  for  $m \geq 2$ , then  $\sum_{k=1}^{N-1} \csc \frac{\pi}{N} k$  and  $\sum_{k=1}^{N-1} \csc^3 \frac{\pi}{N} k$  are  $\mathbb{Q}$ -independent; in particular,  $\text{tr } V_N''(\mathbf{c}) \notin \mathbb{Q}$ , i.e.  $\mathcal{H}_{2^m}$  with equal masses is not integrable in the sense of Liouville-Arnold.  $\square$*

- Proving one of the following conjectures would be enough to obtain non-integrability for general  $N$ :  
if  $N \geq 7$ ,
  - **Conjecture 1:**  $V_N''(\mathbf{c})$  has an eigenvalue  $\lambda > 1$ .
  - **Conjecture 2:**  $\text{tr } V_N''(\mathbf{c}) \notin \mathbb{Q}$ .