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Poisson Structures

Definition [edit]

There are two main points of view to define Poisson structures: it is customary and convenient to switch between them, and we shall do so below.

As bracket [edit]

Let M be a smooth manifold and let $C^\infty(M)$ denote the real algebra of smooth real-valued functions on M, where the multiplication is defined pointwise. A **Poisson bracket** (or **Poisson structure**) on M is an $\mathbb R$ -bilinear map

$$\{\cdot,\cdot\}: C^{\infty}(M) \times C^{\infty}(M) \to C^{\infty}(M)$$

defining a structure of Poisson algebra on $C^{\infty}(M)$, i.e. satisfying the following three conditions:

- Skew symmetry: $\{f, g\} = -\{g, f\}$.
- Jacobi identity: $\{f, \{g, h\}\} + \{g, \{h, f\}\} + \{h, \{f, g\}\} = 0$.
- Leibniz's Rule: $\{fg,h\}=f\{g,h\}+g\{f,h\}$.

The first two conditions ensure that $\{\cdot,\cdot\}$ defines a Lie-algebra structure on $C^\infty(M)$, while the third guarantees that, for each $f\in C^\infty(M)$, the linear map $X_f:=\{f,\cdot\}:C^\infty(M)\to C^\infty(M)$ is a derivation of the algebra $C^\infty(M)$, i.e., it defines a vector field $X_f\in\mathfrak{X}(M)$ called the Hamiltonian vector field associated to f.

Choosing some local coordinates (U,x^i) , any Poisson bracket is given by

$$\{f,g\}_{|U} = \sum_{i,j} \pi_{ij} \frac{\partial f}{\partial x^i} \frac{\partial g}{\partial x^j},$$

for $\pi_{ij} = \{x^i, x^j\}$ the Poisson bracket of the coordinate functions.

Lir algebre structure on G_X + Leibniz

As bivector [edit]

A **Poisson bivector** on a smooth manifold M is a bivector field $\pi \in \mathfrak{X}^2(M) := \Gamma \big(\wedge^2 TM \big)$ satisfying the non-linear partial differential equation $[\pi,\pi]=0$, where

$$[\cdot,\cdot]:\mathfrak{X}^p(M) imes\mathfrak{X}^q(M) o\mathfrak{X}^{p+q-1}(M)$$

denotes the Schouten–Nijenhuis bracket on multivector fields. Choosing some local coordinates (U,x^i) , any Poisson bivector is given by

$$\pi_{|U} = \sum_{i,j} \pi_{ij} rac{\partial igwedge \partial}{\partial x_i} rac{\partial igodown}{\partial x_j},$$

for π_{ij} skew-symmetric smooth functions on U.

$$\frac{3x^{i}}{3} \vee \frac{3x^{j}}{3} = -\frac{3x}{3} \vee \frac{3x^{j}}{3}$$

Examples

· Symplectic manifolds

Poisson monifolds Jonordies Symplectic Manifolds

Two dimensional foliations with $\omega_{\pm} = O_X$ (e.g., degree two foliations on P^3)

Cod 1

· Products

Poisson distribution $\pi \in H^0(X, \Lambda T_X)$, $[\pi, \pi] = 0$ D'X TX Image of this morphism is involvino \Rightarrow Defines a solution hinear algebra \Rightarrow dim $\Xi = 2K$

THE LOCAL STRUCTURE OF POISSON MANIFOLDS

ALAN WEINSTEIN

Theorem 2.1 (Splitting theorem). Let x_0 be any point in a Poisson manifold P. Then there are a neighborhood U of x_0 in P and an isomorphism $\phi = \phi_S \times \phi_N$ from U to a product $S \times N$ such that S is symplectic and the rank of N at $\phi_N(x_0)$ is zero. The factors S and N are unique up to local isomorphism.

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 $T = \begin{pmatrix} \sum_{i=1}^{n} \frac{\partial}{\partial x_i} & \frac{\partial}{\partial y_i} \\ \sum_{i=1}^{n} \frac{\partial}{\partial x_i} & \frac{\partial}{\partial y_i} \end{pmatrix} + T$

A global Weinstein splitting theorem for holomorphic Poisson manifolds

Stéphane Druel* Jorge Vitório Pereira[†] Brent Pym[‡] Frédéric Touzet§

 $\mathbf{W}^{0}(X_{1}X_{1}X_{2}X_{3})$ Theorem 1.1. Let (X,π) be a compact Kähler Poisson manifold, and suppose that $L \subset X$ is a compact symplectic leaf whose fundamental group is finite. Then there exist a compact Kähler Poisson manifold Y, and a finite étale Poisson morphism $\widetilde{L} \times Y \to X$, where \widetilde{L} is the universal cover of L.

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To restricts to a Symplectic Structure on L

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THE SINGULARITIES OF INTEGRABLE STRUCTURALLY STABLE PFAFFIAN FORMS*

By Ivan Kupka

INSTITUTO DE MATEMÁTICA PURA E APLICADA, RIO DE JANEIRO, BRAZIL

Communicated by S. Lefschetz, September 30, 1964

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Foliation of (C,0)codim F = qIf there exists $W \in V N_F$ Such that $JW(0) \neq 0$ then F is a product MATHEMATICS: I. KUPKA Proc. N. A. S.

Definition 5: A C^{∞} function g on an open set $\Omega \subset M$ is called a *unit* on Ω if $g(x) \neq 0$ for $x \in \Omega$.

PROPOSITION 2. If $w \in I(M)$ and g is a C^{∞} function on an open set Ω , then $gw \in I(\Omega)$ and any integral manifold of w is integral manifold of gw. If g is a unit on Ω , then w and gw have the same integral manifolds in Ω .

Proof: Trivial.

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Definition 6: A form $w \in I(M)$ is called structurally stable if for every $\epsilon > 0$ there exists a neighborhood \mathbb{U}_{ϵ} of w in I(M) with the C^1 -topology such that: for any $w' \in \mathbb{U}_{\epsilon}$ there exists a homeomorphism $h: M \to M$ with the following properties: (1) $\operatorname{dist}(x,h(x)) \leq \epsilon$ for all $x \in M$; (2) if D is an integral manifold of w, then h(D) is an integral manifold of w'.

We can now announce our main result.

Main Theorem. If $w \in I(M)$ is structurally stable, the set of all singular points of w is the union of the following two sets: (1) A finite set $\Sigma_n(w)$ such that if $x_0 \in \mathbb{R}$ $\Sigma_n(w)$, then x_0 is isolated in the set of all singular points of w and there exists a neighborhood N_0 of x_0 in M and two C^{∞} functions $f,g:N_0 \to R$ such that: (i) g is a unit in N_0 and f admits in No a unique singular point xo which is generic (in Morse's sense p. 172 of ref. 5) in N_0 ; (ii) w = gdf. The index of x_0 for f (in Morse's sense p. 143 of ref. 5) is called index of w. It determines the structure of the foliation defined by w in the neighborhood of x_0 . (2) A finite union $\Sigma_2(w)$ of C^{∞} compact manifolds of codimension 2, W1, . . . , W , such that if D is a C = 2-dimensional cell transversal to W, at a point xo, the restriction of w to D (i.e., the intersection of the foliation defined by w with D) has at x_0 a generic singular point. More precisely, there exists for each $x_0 \in W$, a neighborhood N_0 of x_0 in M, a C^2 unit $g_0: N_0 \rightarrow R$, and a C^2 mapping $\varphi_0: N_0 \rightarrow R^2$ everywhere of rank 2 such that if (ξ,η) denotes the canonical system of coordinates in R^2 , α_0 is the form $\eta d\xi - \lambda \xi d\eta$ ($\lambda \neq 0,1$ scalar), and α_1 is the form $\xi d\xi + \eta d\eta + \mu (\eta d\xi \xi d\eta$) ($\mu \neq 0$ scalar), then either $w|N_0 = g_0 \varphi_0^* \alpha_0$ or $w|N_0 = g_0 \varphi_0^* \alpha_1$; λ or μ depend only on the manifold W_i , not on the point $x_0 \in W$. Except when λ is rational, φ_0 can be taken of class C... The proofs rely heavily on De Rham's lemma (p. 346 of ref. 6).

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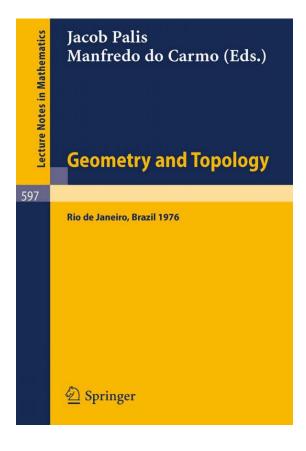
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F foliation of $(C^{n},0)$ codim F = 9If there exists $W \in \Lambda N_{F}^{*}$ Such that $JW(0) \neq \infty$ then F is a product Structural Stability of Integrable Differential Forms

by

Airton S. de Medeiros*

* This paper is essentially the author's doctoral dissertation prepared under the supervision of Professor C. Camacho at IMPA, Rio de Janeiro. This work was supported by CNPq and UFRN.



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