Continuous Time Random Walks and fractional HJB equations

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- HJB and fHJB
- Basics of fractional calculus
- Mittag-Leffler function
- Example of a fDE
- Payoff equation
- Existence and uniqueness
- Open problems



HJB and fHJB

General HJB:

$$\frac{\partial S}{\partial t} + LS + \sup_{u} [f(x, u) \frac{\partial S}{\partial x} + g(x, u)] = 0.$$
(1)

Game theory: HJB Isaacs equation

$$\frac{\partial S}{\partial t} + LS + \sup_{u} \inf_{v} [f(x, u, v) \frac{\partial S}{\partial x} + g(x, u, v)] = 0.$$
(2)

fHJB

$$\frac{\partial^{\beta}S}{\partial t^{\beta}} + LS + \sup_{u} [f(x, u)\frac{\partial S}{\partial x} + g(x, u)] = 0$$
(3)

We're particularly interested in the case when $L = a(x)D_{0,x}^{*\alpha}, \alpha \in (0, 2].$



Fractional calculus

CTRW and optimal payoff equation

A random variable γ in DOA (β -stable law) if as $n
ightarrow \infty$

$$\frac{\sum_{i=1}^{n} \gamma_i - a_n}{b_n} \to Z,\tag{4}$$

in distribution, for some a_n , b_n , where Z is stable. In other notation, as $n \to \infty$ if $\nu(dr)$ is the law for γ_i waiting times

$$\int_{|r|>n} \nu(dr) \sim \frac{1}{\Gamma[1-\beta]n^{\beta}}$$
(5)

for $\beta \in (0, 1)$.

- Waiting times $\gamma_i \in \text{DOA}(\beta$ -stable law), $\beta \in (0, 1)$.
- Denote $X(n) = \sum_{i=1}^{n} \gamma_i$ and $Z_X(t) = \inf_n \{n : X(n) > t\}$
- Jumps $\xi_i \in \text{DOA}(\alpha \text{-stable law}), \ \alpha \in (0, 2], \ \xi_i \in \mathbb{R}^d$.
- The process $Y_{Z_X}(t) = \sum_{i=1}^{Z_X(t)} \xi_i$ is the CTRW.
- Control set U at every jump: $\xi_i(u_i)$, $i \in \mathbb{N}$.
- Set of all possible controls for all jump times:

$$\tilde{U} = \{\tilde{u} = (u_1, u_2, \ldots)\}, u_i \in U.$$

Fractional integral defined via iterations for f ∈ S, Schwartz space: Let If(x) = ∫^x_{-∞} f(y)dy for f ∈ S.

$$I^{k}f(x) = \frac{1}{(k-1)!} \int_{-\infty}^{x} (x-y)^{k-1} f(y) dy, \text{ for } k \in \mathbb{N}.$$
 (7)

Now replace integer k by fractional β :

$$I^{\beta}f(x) = \frac{1}{\Gamma[\beta]} \int_{-\infty}^{x} (x-y)^{\beta-1} f(y) dy, \text{ for } \beta > 0.$$
 (8)

• Related fractional derivative for $\beta \in (0, 1)$:

$$\frac{d^{\beta}f(x)}{dx^{\beta}} = \frac{d}{dx}I^{1-\beta}f(x).$$
(9)



• The left-sided Caputo derivative for $\beta \in (0,1)$ is defined for $f \in S$ by

$$D_{0,x}^{*\beta}f(x) = \frac{1}{\Gamma[1-\beta]} \int_0^x \frac{df(y)}{dy} (x-y)^{-\beta} dy.$$
(10)

• Fractional Laplacian operator $(-\nabla)^{lpha}$:

$$-\frac{1}{\Gamma(1-\alpha)}\int_{-\infty}^{\infty}\frac{(f(x)-f(y))}{|x-y|^{1+\alpha}}dy.$$
 (11)

- The operators $-D_{0,y}^{*\beta}$ and $(-\nabla)^{\beta/2}$ are generators of stable Levy motions.
- A general β-stable Levy motion L_t can be described by the following log-characteristic function:

$$log\mathbb{E}[e^{i\theta L_t}] = -t\kappa^{\beta}|\theta|^{\beta}(1-i\beta sign(\theta)tan(\beta\pi/2)) + itm\theta$$
(12)

for $\beta \neq 1$, β stability index.



Mittag-Leffler function: power series definition

A Mittag-Leffler function $E_{\beta,\alpha}(z)$ is defined as:

$$E_{\beta,\alpha}(z) := \sum_{k=0}^{\infty} \frac{z^k}{\Gamma[\beta k + \alpha]} = \frac{1}{2\pi i} \int_{\mathsf{Ha}} e^{\lambda} \frac{\lambda^{\beta - \alpha}}{\lambda^{\beta} - z} d\lambda, \qquad (13)$$

for $\alpha, \beta > 0, z \in C$, and where Ha denotes a Hankel path, which is a contour starting and finishing at $-\infty$ and encircling the disc $|\lambda| \leq |z|^{1/\beta}$ counter clockwise.



Fractional calculus

Examples of Caputo derivatives of functions

- $D_{0,t}^{*\beta}(e^{\lambda t}) = t^{-\beta} E_{1,1-\beta}(\lambda t) \frac{t^{-\beta}}{\Gamma[1-\beta]},$
- $D_{0,t}^{*\beta}(\cosh(\sqrt{\lambda}t)) = t^{-\beta}E_{2,1-\beta}(\lambda t^2) \frac{t^{-\beta}}{\Gamma[1-\beta]}$,
- $D_{0,t}^{*\beta}(H(t)) = 0$, where H(t) is the unit Heaviside function.



Fractional calculus

Mittag-Leffler function: examples

For example.		
	$E_{1,1}(z)=e^z$	(14)
and		
	$E_{1,2}(z)=\frac{e^z-1}{z}$	(15)
and		
	$E_{2,2}(z^2) = \frac{\sinh(z)}{z}.$	(16)



Simple fDE

For $eta \in (0,1], \lambda \in \mathbb{R}$,

$$D_{0,t}^{*\beta}y(t) = \lambda y(t), \qquad (17)$$

with initial condition

$$y(0) = y_0.$$
 (18)

Solution is given by

$$y(t) = y_0 E_{\beta,1}(\lambda t^{\beta}). \tag{19}$$

When $\beta = 1$, $y(t) = y_0 \sum_{n=0}^{\infty} \frac{(\lambda t)^n}{\Gamma(n+1)} = y_0 e^{\lambda t}$, a standard result.



Fractional calculus

CTRW and optimal payoff equation

- Waiting times $\gamma_i \in \mathsf{DOA}(\beta$ -stable law), $\beta \in (0, 1)$.
- Denote $X(n) = \sum_{i=1}^{n} \gamma_i$
- Denote $Z_X(t) = \inf_n \{n : X(n) > t\}$
- Jumps $\xi_i \in \text{DOA}(\alpha \text{-stable law}), \ \alpha \in (0, 2], \ \xi_i \in \mathbb{R}^d$.
- The process $Y_{Z_X}(t) = \sum_{i=1}^{Z_X(t)} \xi_i$ is the CTRW. Y considered at jump times only is a Markov process.
- Controlling jump sizes to optimise payoff:
- Control set U at every jump time
- Set of all possible controls for all jump times:

$$\tilde{U} = \{ \tilde{u} = (u_1, u_2, \ldots) \}, u_i \in U.$$
 (20)



• The optimal payoff function S(t, y) is defined as follows:

$$S(t,y) = \sup_{\tilde{u}\in \tilde{U}} \mathbb{E}S_0(y+Y(t,\tilde{u})), \quad t \ge 0.$$
(21)

• Scaling jump sizes by $\tau^{1/\alpha}$ and waiting times by $\tau^{1/\beta}$, then $Y^{\tau}(u,t) = \sum_{i=1}^{Z_{X_n^{\tau}}(t)} \tau^{1/\alpha} \xi_i(u_i)$ and

$$S^{\tau}(t,y) = \sup_{\tilde{u}\in\tilde{U}} \mathbb{E}S_0^{\tau}(y+Y^{\tau}(t,\tilde{u})).$$
(22)

$$S^{\tau}(t,y) = \sup_{u \in U} \left[S_0^{\tau}(y) \int_t^{\infty} \nu(dr/\tau^{1/\beta}) + \int_0^t \int_{\mathbb{R}^d} S^{\tau}(t-r,y+\xi) \mu_u(d\xi/\tau^{1/\alpha}) \nu(dr/\tau^{1/\beta}) \right].$$
(23)

As $\tau \to 0$, assume $\forall t \ge 0$, $y \in \mathbb{R}^d$, $S^{\tau}(t, y) \to \tilde{S}(t, y)$, where \tilde{S} belongs to domains of the stable generator L and $A_{0,t}^{*\beta}$.



Extensions and other versions

- Motion during waiting times can be deterministic, e.g. in case d = 1, with a generator of the form f(x) d/dx. I.e. the process Y is piecewise deterministic.
- This only slightly changes the equation for the optimal payoff, adding an extra term with the generator of the motion during waiting time intervals.
- running costs- for waiting and for jumping, apart from arriving: represented by functions f and g.
- Time and position dependence:

$$X_{n}^{\tau} = X_{n-1}^{\tau} + \gamma_{n}(X_{n-1}), \qquad (24)$$

and

$$Y_n^{\tau} = Y_{n-1}^{\tau} + \xi_n(Y_{n-1}), \qquad (25)$$

and the process we study is $Y_{Z_X(t)}$.



Construction of the jump process

For an arbitrary Feller process \tilde{Y} with a generator L^u , it is always possible to construct a family of measures $\mu_{u,\tau}(y, d\xi)$, such that

$$Y_n^{\tau} = Y_{n-1}^{\tau} + \xi_n(Y_{n-1}^{\tau}), \qquad (26)$$

where $\xi_n, n \in \mathbb{N}$ are r.v.'s with distributions given by $\mu_{u,\tau}$, and such that

$$\int_{\mathbb{R}^d} \frac{f(t, y+\xi) - f(t, y)}{\tau} \mu_{u,\tau}(y, d\xi) \to L^u f(t, y).$$
(27)

Then

$$Y^{\tau}_{[t/\tau]} \to_d \tilde{Y}.$$
 (28)

Essentially, in such a case we obtain the same form of payoff equation.



Let au
ightarrow 0, obtain the limiting equation of the form:

$$D_{0,t}^{*\beta}S(t,y) = -LS(t,y) + H(u,t,y,D_yS).$$
⁽²⁹⁾

First, we study

$$D_{0,t}^{*\beta}S(t,y) = -LS(t,y) + f(t,y),$$
(30)

We study the case when $L: D(L) \to C_{\infty}(\mathbb{R}^d)$, with the resolvent set $\rho(L)$ including the right half plane. More precisely this theory applies to $L = -|\nabla|^{\alpha}$, $\alpha \in (0, 2]$ and to $L = \sum_{i,j=1}^{d} a_{i,j} \frac{\partial^2}{\partial x_i \partial x_j} + \sum_{i=1}^{d} b_i \frac{d}{dx_i}$, where $a_{i,j}, b_i$ are constants.

Applying Laplace transform and re-arranging:

$$\hat{S}(\lambda) = \lambda^{\beta - 1} (\lambda^{\beta} \mathbb{I} + L)^{-1} S_0(y) + (\lambda^{\beta} \mathbb{I} + L)^{-1} \hat{f}(\lambda).$$
(31)

Mittag-Leffler function

Other representation of the Mittag-Leffler function:

$$E_{\beta,\alpha}(-t^{\beta}L) = \frac{1}{2\pi i} \int_{Ha(\epsilon)} \frac{e^{stL^{1/\beta}}s^{\beta-\alpha}}{s^{\beta}+1} ds = \int_{0}^{\infty} e^{-rtL^{1/\beta}} K_{\beta,\alpha}(r) dr,$$
(32)

where

$$\mathcal{K}_{\beta,\alpha}(r) = \frac{1}{\pi} \frac{r^{2\beta-\alpha}\sin(\alpha\pi) - r^{\beta-\alpha}\sin((\beta-\alpha)\pi)}{r^{2\beta} + 2r^{\beta}\cos(\beta\pi) + 1}.$$
 (33)

We will need

$$\mathcal{K}_{\beta,\beta}(r) = \frac{1}{\pi} \frac{r^{\beta} \sin(\beta \pi)}{r^{2\beta} + 2r^{\beta} \cos(\beta \pi) + 1}.$$
 (34)

Here $e^{-rtL^{1/\beta}}$ is a bounded operator.



A Laplace transform and an unbounded operator L

Theorem

Let $L: D(L) \to C_{\infty}(\mathbb{R}^d)$, such as $L = (-\nabla)^{\alpha}, \alpha \in (1, 2]$, and $\beta \in (0, 1)$. Then the following holds:

$$\int_{0}^{\infty} e^{-\lambda t} t^{\alpha - 1} E_{\beta, \alpha}(-t^{\beta} L) dt = \frac{\lambda^{\beta - \alpha}}{(\lambda^{\beta} \mathbb{I} + L)}.$$
 (35)

Consider $L: D(L) \to L^2(\mathbb{R}^d)$ first. The power series representation of $E_{\beta,\alpha}(-t^{\beta}L)f$ holds for any vector f of L, satisfying

$$\sum_{n=1}^{\infty} \frac{\|L^n f\|_{L^2(\mathbb{R}^d)}}{n!} t^n < \infty$$
(36)

for any t > 0. This set of vectors is dense in $L^2(\mathbb{R}^d)$. $C_c(\mathbb{R}^d)$ dense in $L^2(\mathbb{R}^d)$. Approximate functions in $C_{\infty}(\mathbb{R}^d)$ by functions in $C_c(\mathbb{R}^d) \subset L^2(\mathbb{R}^d)$.

Apply the inverse Laplace transform to obtain the mild form.



Mild form of the equation

$$D_{0,t}^*S(t,y) = -LS(t,y) + f(t,y)$$
(37)

turns to

$$S(t,y) = E_{\beta,1}(-t^{\beta}L)S_{0}(y) + \int_{0}^{t} (t-s)^{\beta-1}E_{\beta,\beta}(-(t-s)^{\beta}L)f(t,y)ds.$$
(38)



Application to the limiting payoff equation

Theorem

Let
$$\beta \in (0,1)$$
, $L = (-\nabla)^{\alpha}$, $\alpha \in (1,2]$ or $L = \sum_{i,j=1}^{d} a_{ij} \frac{d^2}{dx_i dx_j}$, where a_{ij} are constants. The fDE

$$D_{0,t}^{*\beta}S(t,y) = -LS(t,y) + H(t,y,u,D_yS(t,y))$$
(39)

has the mild form

$$S(t,y) = E_{\beta,1}(-t^{\beta}L)S_{0}(y) + \int_{0}^{t} (t-s)^{\beta-1}E_{\beta,\beta}(-(t-s)^{\beta}L)H(t,y,u,D_{y}S(t,y)) \, ds.$$
(40)



Theorem 3

Assumptions:

- The domain of *L* is $D = C^2_{\infty}(\mathbb{R}^d)$, unbounded as an operator in $C_{\infty}(\mathbb{R}^d)$, e.g. $L = (-\nabla)^{\alpha}, \alpha \in (1, 2]$.
- $\|e^{-tL^{1/\beta}}f\|_{C^1(\mathbb{R}^d)} \leq t^{\epsilon(\beta)}\|f\|_{C^0(\mathbb{R}^d)}.$
- H(u, t, y, p) is Lipschitz in p uniformly in y, i.e., with a Lipschitz constant κ independent of y, and

$$|H(u,y,0)| \le h \tag{41}$$

for a constant h and all y.

• A restriction on stability parameters α, β :

$$\beta - \frac{\beta}{\alpha} + 1 > 0. \tag{42}$$

Under the above assumptions on H and L, for any $S_0 \in C^1_{\infty}(\mathbb{R}^d)$ there exists a unique $C^1_{\infty}(\mathbb{R}^d)$ solution S(t, y) of the mild equation, for all $t \ge 0$.



The space $C([0, T], C^1_{\infty}(\mathbb{R}^d))$ has the norm

$$\|\phi(\cdot)\| = \sup_{t \in [0,T]} \|\phi\|_{C^1(\mathbb{R}^d)}$$
(43)

Denote by $B_{S_0}^T$ the space of continuous functions from the closed convex subset of $C([0, T], C_{\infty}^1(\mathbb{R}^d))$ with $\phi_0 = S_0$.



Sketch of the proof

Denote the RHS operator by $\Psi(\cdot)$. By triangle inequality:

$$\sup_{t \in [0,T]} \|\Psi(\phi)\|_{C^{1}(\mathbb{R}^{d})} \leq \sup_{t \in [0,T]} \|\int_{0}^{t} (t-s)^{\beta-1} E_{\beta,\beta}(-(t-s)^{\beta}L) \\ H\left(u,s,y,\frac{d\phi(s,y)}{dy}\right) ds\|_{C^{1}(\mathbb{R}^{d})} \\ + \sup_{t \in [0,T]} \|E_{\beta,1}(-t^{\beta}L)S(0)\|_{C^{1}(\mathbb{R}^{d})}.$$
(44)



Let $\phi_1 \neq \phi_2 \in B_{S_0}^T$.

$$\begin{split} \sup_{t\in[0,T]} \|\Psi(\phi_t^1-\phi_t^2)\|_{C^1(\mathbb{R}^d)} \leq \\ \sup_{t\in[0,T]} \left\|\int_0^t (t-s)^{\beta-1} E_{\beta,\beta}(-(t-s)^{\beta}L) \right\| \\ \times \left(H(u,s,y,\frac{d\phi_s^1}{dy}) - H(u,s,y,\frac{d\phi_s^2}{dy})\right) ds \right\|_{C^1(\mathbb{R}^d)} \\ \leq \omega(t) \left(\kappa \sup_{s\leq t} \|\phi_s^1-\phi_s^2\|_{C^1(\mathbb{R}^d)}\right). \end{split}$$

(45)



The RHS operator Ψ is a contraction in the closed convex subset of $C([0, T], C^1_{\infty}(\mathbb{R}^d))$ for small enough T.

As a consequence, it has a unique fixed point, i.e., there is a unique continuous solution S(t, y) for the mild form of the fHJB,

which is approximated by the iterations of Ψ on $S_0(y)$ by Banach fixed point theorem.



The assumptions of the previous theorem remain and we add a new one:

• $|H(u, t, y_1, p) - H(u, t, y_2, p)| \le \tilde{\kappa}|y_1 - y_2|(1 + |p|)$ with a certain constant $\tilde{\kappa} \ge 0$.

If $S_0(y) \in C^2_{\infty}(\mathbb{R}^d)$, the unique solution constructed previously belongs to $C^2_{\infty}(\mathbb{R}^d)$ and represents a classical solution to the original fDE.



Sketch of the proof

Denote by $B_{S_0}^{T,R,2}$ the space of functions which are twice continuously differentiable in y from the closed convex subset $B_{S_0}^T$ of $C([0, T], C_{\infty}^1(\mathbb{R}^d))$, have $\phi_0 = S_0$ and

$$\sup_{t \le T} \|\phi_t\|_{C^2(\mathbb{R}^d)} \le R \tag{46}$$

for some constant R > 0. Then

$$\sup_{t \leq T} \|\Psi(\phi_t)\|_{C^2(\mathbb{R}^d)} \leq \sup_{t \leq T} \|E_{\beta,1}(-t^\beta L)S(0)\|_{C^2(\mathbb{R}^d)} + \int_0^t \omega(s)R(\kappa + \tilde{\kappa})ds.$$
(47)



Want $\sup_{t \leq T} \|\Psi(\phi_t)\|_{C^2(\mathbb{R}^d)} \leq R$, so that Ψ maps $B_{S_0}^{T,R,2}$ to itself. Re-arrange to obtain an expression for R:

$$R \geq \sup_{t \leq T} \|E_{\beta,1}(-t^{\beta}L)S(0)\|_{C^{2}(\mathbb{R}^{d})}$$
$$\times \left(1 - \int_{0}^{T} \omega(s)ds(\kappa + \tilde{\kappa})\right)^{-1}.$$
 (48)

If necessary, reduce T to ηT for some $\eta \in (0, 1)$, so that the denominator is positive.

If (48) is satisfied then Ψ maps $B_{S_0}^{R,T,2}$ into itself and consequently the limit of iterations of Ψ on S_0 is also of class $C^2(\mathbb{R}^d)$.

By the previous theorem we know that the solution to the fHJB is unique in $C^1(\mathbb{R}^d)$, hence, the solution $\lim_{k\to\infty} \Psi^k(S_0)$ is a unique solution of class $C^2(\mathbb{R}^d)$. So, by the principle of dynamic programming, there exists a unique classical solution for the simpleMAS fHJB on any interval [0, T].

Reading

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Further research

- Still remains to prove $S^{ au}
 ightarrow S$.
- What if the restriction on α and β is not satisfied?
- If $L = \sup_{u \in U} a(y)g(u)D_y^{*\alpha}$, how to analyse the fHJB?
- SDE approach to the limiting process, links to fractional Fokker-Planck equation.
- Applications to insurance, for example considering a difference of two sums of jumps with waiting times dependent on related stability parameters β_1 and β_2 and introducing re-insurance as an additional running cost.
- CTRW with regenerations in limit order book theory
- Many-particle systems behaving as a similar CTRW, mean-field interaction of such systems in games
- CTRW approach to queueing theory

Thank You for listening. Merci de votre attention.

