# Conductance Based Neuron Models

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UPMC - LPMA

Workshop PDMP

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#### Conductance Based Neuron Models: a Biological Description





#### Conductance Based Neuron Models: a Biological Description

#### Conductance Based Neuron Models as PDMPs





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Some limit theorems





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Conductance Based Neuron Models as PDMPs

Some limit theorems

Some Simulations



# This talk is inspired by:

- Reduction of stochastic conductance-based neuron models with time-scales separation, J. of Comp. Neuro. (2011) G. Wainrib, M. Thieullen, K. Pakdaman.
- Averaging and large deviation principles for fully-coupled piecewise deterministic Markov processes, Markov Proc. Rel. Fields (2009) A. Faggionato, D. Gabrielli and M. Ribezzi Crivellari.
- Averaging for a Fully-Coupled Piecewise Deterministic Markov Process in Infinite Dimensions, Adv. in App. Proba. (2012) A.
   G. and M. Thieullen.
- An exact stochastic hybrid model of excitable membranes including spatio-temporal evolution, J. Math. Bio. (2011) E. Buckwar and M. Riedler.
- Limit theorems for infinite-dimensional piecewise deterministic Markov processes. Applications to stochastic excitable membrane models, Elect. J. Prob. (2012), M. Riedler, M. UPP Thieullen and G. Wainrib.



- the soma contains the 'organs' of the cell body;
- the dendrites where the neural cell receives inputs from other neurons or muscles or peripheral organs;
- the axon responsible for transmitting neural information, that is the inputs, to interconnected target neurons;
- the synapses at the interfaces of axon terminals with target cells.

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- K<sup>+</sup>: potassium.
- Na<sup>+</sup>: sodium.
- Cl<sup>-</sup>: chloride.



- Increasing the voltage of the axon membrane produces a large, but transient, flow of positive charge carried by Na<sup>+</sup> ions flowing into the cell: inward current.
- This transient inward current is followed by a sustained flow of positive charge out of the cell, the outward current carried by a sustained flux of K<sup>+</sup> ions moving out of the cell.

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#### The nerve impulse



Action potential in the pointwise Hodgkin-Huxley model.



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## Mathematical model

A membrane with N ionic channels and an axon considered as a segment I.



Generation and propagation of an action potential:



with initial and boundary conditions.

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Some Simulations

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#### Mathematical model

Dynamic of ionic channels (voltage-dependent):

$$\mathbb{P}(r_{t+h}(i) = \zeta | r_t(i) = \xi) = \underbrace{\alpha_{\xi\zeta}(v_t(z_i))}_{\text{rate of jump}} h + o(h)$$



- $r_t(i) \in E$  state of the channel at locus  $z_i$  at time t.
- State space:  $r = (r(i), i = 1, ..., N) \in E^N$ .

## An excitable system



Some Simulations

## A class of switching PDEs

#### An evolution equation:

$$C_m \partial_t v_t = \frac{a}{2R} \partial_{xx} v_t + \frac{1}{N} \sum_{i=1}^N c_{r_t(i)} (v_{r_t(i)} - v_t(z_i)) \delta_{z_i}$$

with coefficient r = (r(i), i = 1, ..., N) updated at voltage dependent rates:

 $q_{r\tilde{r}}(v) = \begin{cases} 0 & \text{if } r \text{ and } \tilde{r} \text{ differ from more than one component,} \\ \frac{\alpha_{r(i)\tilde{r}(i)}(v(z_i))}{\alpha_{r(i)}(v(z(i)))} & \text{if } r(i) \neq \tilde{r}(i) \text{ and all the other components agree.} \end{cases}$ 

A PDMP !

# A class of switching PDEs

Remarks on the evolution equation :

• Smoothed choice:

$$C_m \partial_t \mathbf{v}_t = \frac{a}{2R} \partial_{\mathbf{x}\mathbf{x}} \mathbf{v}_t + \frac{1}{N} \sum_{i=1}^N c_{r_t(i)} (\mathbf{v}_{r_t(i)} - (\mathbf{v}_t, \phi_{z_i})) \phi_{z_i},$$

• Compartment type models:

Infinitesimal generator:

$$\mathcal{A}f(v,r) = \mathcal{C}(r)f(\cdot,r)(v) + \mathcal{J}(v)f(v,\cdot)(r)$$

Macroscopic generator and microscopic generator:

$$\mathcal{C}(r)f(\cdot,r)(v) = \langle f_v(v,r), \frac{a}{2R}\Delta v + \frac{1}{N}\sum_{i=1}^N c_{r(i)}(v_{r(i)} - v(z_i))\delta_{z_i} \rangle$$

$$\mathcal{J}(v)f(v,\cdot)(r) = \sum_{i=1}^{N} \sum_{\zeta \in E} [f(v, r_{r(i) \to \zeta}) - f(v, r)] \alpha_{r(i),\zeta}(v(z_i))$$

#### When N goes to infinity





#### When N goes to infinity

• Deterministic limit:

$$\begin{cases} \partial_t v_t = \partial_{xx} v_t + \sum_{\xi \in E} c_{\xi}(v_{\xi} - v_t), \\ \partial_t p_{\xi,t} = \sum_{\zeta \neq \xi} p_{\zeta,t} \alpha_{\zeta\xi}(v_t) - p_{\xi,t} \alpha_{\xi\zeta}(v_t). \end{cases}$$

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#### When N goes to infinity

• At a fixed N:  $\begin{cases}
\frac{\partial_t v_t = \partial_{xx} v_t + \frac{1}{N} \sum_{i=1}^N c_{r_t(i)} (v_{r_t(i)} - (v_t(z_i)) \delta_{z_i}, \\
\mathbb{P}(r_{t+h}(i) = \xi) = \alpha_{\xi\xi} (v_t(z_i)) h + o(h).
\end{cases}$ 

• Langevin approximmation:

 $\begin{cases} v_t^{(N)} \simeq v_t + \frac{1}{\sqrt{N}} V_t, \\ \frac{1}{N} \sum_{i=1}^N \mathbb{1}_{\xi}(r_t(i)) \delta_{z_i} \simeq p_{\xi,t} + \frac{1}{\sqrt{N}} P_{\xi,t}. \end{cases}$ 

Deterministic limit:

$$\begin{cases} \partial_t v_t = \partial_{xx} v_t + \sum_{\xi \in E} c_{\xi}(v_{\xi} - v_t), \\ \partial_t p_{\xi,t} = \sum_{\zeta \neq \xi} p_{\zeta,t} \alpha_{\zeta\xi}(v_t) - p_{\xi,t} \alpha_{\xi\zeta}(v_t). \end{cases}$$



The model with two time scales:

$$\begin{cases} \partial_t v_t^{\varepsilon} = \partial_{xx} v_t^{\varepsilon} + \frac{1}{N} \sum_{i=1}^N c_{r_t^{\varepsilon}(i)} (v_{r_t^{\varepsilon}(i)} - v_t^{\varepsilon}(z_i)) \delta_{z_i} \\ \mathbb{P}(r_{t+h}^{\varepsilon}(i) = \zeta | r_t^{\varepsilon}(i) = \xi) = \alpha_{\xi\zeta}^{\varepsilon} (v_t^{\varepsilon}(z_i)) h + o(h) \end{cases}$$

with *I* different classes:  $E = E_1 \sqcup \cdots \sqcup E_I$ .



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with *I* different classes:  $E = E_1 \sqcup \cdots \sqcup E_l$ .





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with *I* different classes:  $E = E_1 \sqcup \cdots \sqcup E_I$ . The aggregated process:

$$\overline{r}_t^{\varepsilon}(i) = j \text{ iff } r_t^{\varepsilon}(i) \in E_j$$



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Some Simulations

#### When v is held fixed...



Let v held fixed and i = 1, ..., N,  $\overline{r}^{\varepsilon}(i)$  converges weakly toward the Markov process  $\overline{r}(i)$  with generator:

$$\overline{\mathcal{J}}[v]f(\overline{r}(i)) = \sum_{j=1}^{l} 1_{j}(\overline{r}(i)) \sum_{k=1, k \neq j}^{l} (f(k) - f(j)) \sum_{\xi \in E_{k}} \sum_{\zeta \in E_{j}} \alpha_{\zeta,\xi}(v(z_{i})) \mu_{j}(v(z_{i}))(\zeta)$$

#### When $\varepsilon$ goes to zero

• When  $\varepsilon$  is held fixed:

$$\begin{cases} \partial_t v_t^{\varepsilon} = \partial_{xx} v_t^{\varepsilon} + \frac{1}{N} \sum_{i \in \mathcal{N}} c_{r_t^{\varepsilon}(i)} (v_{r_t^{\varepsilon}(i)} - v_t^{\varepsilon}(z_i)) \delta_{z_i} \\ \mathbb{P}(r_{t+h}^{\varepsilon}(i) = \zeta | r_t^{\varepsilon}(i) = \xi) = \alpha_{\xi\zeta}^{\varepsilon} (v_t^{\varepsilon}(z_i)) h + o(h) \end{cases}$$



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• Averaged model:

$$\begin{cases} \partial_t v_t = \\ \partial_{xx} v_t + \frac{1}{N} \sum_{i=1}^N \sum_{j=1}^l \mathbf{1}_{E_j}(\bar{r}_t(i)) \sum_{\xi \in E_j} \mu_j(v_t(z_i))(\xi) c_\xi(v_\xi - v_t(z_i)) \delta_{z_i} \\ \mathbb{P}(\bar{r}_t(i) = l_2 | \bar{r}_t(i) = l_1) = \overline{\alpha}_{l_1 l_2}(v_t(z_i)) h + o(h) \end{cases}$$

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• Langevin approximation:

$$\begin{cases} dv_t^{\varepsilon} = [\partial_{xx}v_t^{\varepsilon} + F_{\overline{r}_t}(v_t^{\varepsilon})]dt + \sqrt{\varepsilon}B_{\overline{r}_t}(v_t^{\varepsilon})dW_t \\ \mathbb{P}(\overline{r}_t(i) = l_2|\overline{r}_t(i) = l_1) = \overline{\alpha}_{l_1 l_2}(v_t(z_i))h + o(h) \end{cases}$$

• Averaged model:

$$\begin{cases} \partial_t \mathbf{v}_t = \\ \partial_{xx} \mathbf{v}_t + \frac{1}{N} \sum_{i=1}^N \sum_{j=1}^l \mathbf{1}_{E_j}(\overline{r}_t(i)) \sum_{\xi \in E_j} \mu_j(\mathbf{v}_t(z_i))(\xi) c_\xi(\mathbf{v}_\xi - \mathbf{v}_t(z_i)) \delta_{z_i} \\ \mathbb{P}(\overline{r}_t(i) = l_2 | \overline{r}_t(i) = l_1) = \overline{\alpha}_{l_1 l_2}(\mathbf{v}_t(z_i)) h + \mathrm{o}(h) \end{cases}$$

## Another multiscale model

#### What happens if the potential is also fast?

$$\begin{cases} \partial_t v_t = \frac{1}{\varepsilon} \left[ \partial_{xx} v_t + \frac{1}{N} \sum_{i=1}^N \sum_{k=1}^2 c_{r_t^k(i)} (v_{r_t^k(i)} - (v_t, \phi_{z_i})) \phi_{z_i} \right] \\ \mathbb{P}(r_{t+h}^{(1)}(i) = \zeta | r_t^{(1)}(i) = \xi) = \frac{1}{\varepsilon} \alpha_{\xi\zeta}^{(1)}((v_t, \phi_{z_i})) h + o(h) \\ \mathbb{P}(r_{t+h}^{(2)}(i) = \zeta | r_t^{(2)}(i) = \xi) = \alpha_{\xi\zeta}^{(2)}((v_t, \phi_{z_i})) h + o(h) \end{cases}$$

In this case, the fast part of the process is a still a PDMP...



## Another multiscale model

Fix  $r^{(2)}$  and consider the PDMP:

$$\begin{cases} \partial_t v_t = \partial_{xx} v_t + \frac{1}{N} \sum_{i=1}^N \sum_{k=1}^2 c_{r_t^k(i)} (v_{r_t^k(i)} - (v_t, \phi_{z_i})) \phi_{z_i} \\ \mathbb{P}(r_{t+h}^{(1)}(i) = \zeta | r_t^{(1)}(i) = \xi) = \alpha_{\xi\zeta}^{(1)}((v_t, \phi_{z_i}))h + o(h) \end{cases}$$

There exists a unique invariant measure  $\mu_{r^{(2)}}$ .

Remark: one can show that the speed of convergence towards the invariant measure is exponential in Wasserstein distance.

Averaged model: a CTMC  $\bar{r}^{(2)}$  with rates:

$$\bar{q}_{r\tilde{r}}^{(2)} = \int_{L^2(I) \times E^1} q_{r\tilde{r}}^{(2)}((v, \phi_{z_i})) \mu_r(dv, dr^1)$$



#### Example: $\varepsilon$ goes to zero



$$\partial_t \mathbf{v}_t^{\varepsilon} = \nu \partial_{xx} \mathbf{v}_t^{\varepsilon} + \frac{1}{N} \sum \mathbf{1}_{m_3 h_1} (\mathbf{r}_t^{\varepsilon}(i)) \mathbf{c}_{Na} (\mathbf{v}_{Na} - \mathbf{v}_t^{\varepsilon}(z_i)) \delta_{\frac{i}{N}}$$



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 $\partial_t v_t = \nu \partial_{xx} v_t + \frac{1}{N} \sum \mathbb{1}_1(\bar{r}_t(i)) \mu_1(v_t(z_i))(m_3h_1) c_{Na}(v_{Na} - v_t(z_i)) \mathcal{V}_1(v_t(z_i)) (m_3h_1) c_{Na}(v_{Na} - v_t(z_i)) \mathcal{V}_2(z_i) \mathcal{V}_2($ 

#### Example



Figure: Simulation of the averaged model with N = 250



#### Example: N goes to infinity, $\varepsilon$ held fixed



$$\partial_t v_t^{\varepsilon} = \partial_{xx} v_t^{\varepsilon} + \frac{1}{N} \sum \mathbb{1}_{m_3 h_1} (r_t^{\varepsilon}(i)) c_{Na} (v_{Na} - v_t^{\varepsilon}(z_i)) \delta_{\frac{i}{N}}$$



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Converges to:

$$\begin{cases} \partial_t v_t^{\varepsilon} = \partial_{xx} v_t^{\varepsilon} + \frac{p_{\mathsf{m}_{\mathsf{3}}h_{1,t}} c_{\mathsf{Na}}(v_{\mathsf{Na}} - v_t^{\varepsilon}) \\ \partial_t p_{\xi,t} = \sum_{\zeta \neq \xi} \alpha_{\zeta\xi}^{\varepsilon}(v_t^{\varepsilon}) p_{\zeta,t} - \alpha_{\xi\zeta}(v_t^{\varepsilon}) p_{\xi,t} \end{cases}$$

for  $\xi \in E = \{m_0h_0, m_1h_0, m_2h_0, m_3h_0, m_0h_1, m_1h_1, m_2h_1, m_3h_1\}$ 

Example: deterministic averaging,  $N = \infty$ ,  $\varepsilon \rightarrow 0$ 



$$\begin{cases} \partial_t \mathbf{v}_t^{\varepsilon} = \partial_{\mathsf{X}\mathsf{X}} \mathbf{v}_t^{\varepsilon} + \mathbf{p}_{\mathsf{m}\mathsf{3}\mathbf{h}\mathsf{1},t} \mathbf{c}_{\mathsf{N}\mathsf{a}} (\mathbf{v}_{\mathsf{N}\mathsf{a}} - \mathbf{v}_t^{\varepsilon}) \\ \partial_t \mathbf{p}_{\xi,t} = \sum_{\zeta \neq \xi} \alpha_{\zeta\xi} (\mathbf{v}_t^{\varepsilon}) \mathbf{p}_{\zeta,t} - \alpha_{\xi\zeta} (\mathbf{v}_t^{\varepsilon}) \mathbf{p}_{\xi,t} \end{cases}$$

for  $\xi \in E = \{m_0h_0, m_1h_0, m_2h_0, m_3h_0, m_0h_1, m_1h_1, m_2h_1, m_3h_1\}$ . The model converges to

$$\begin{cases} \partial_t v_t = \partial_{xx} v_t + \left(\frac{a_m(v_t)}{a_m(t) + b_m(v_t)}\right)^3 h_t c_{Na}(v_{Na} - v_t) \\ \partial_t h_t = (1 - h_t) a_h(v_t) - b_h(v_t) h_t. \end{cases}$$



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#### Example



Figure: Simulation of the averaged deterministic model ( $N = \infty$ )



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Some Simulations

#### Simulations for various N.



Remarks: The speed of the deterministic front wave is always greater than the mean speed of the stochastic wave. The difference for large N is of order  $\frac{1}{\sqrt{N}}$ .

# Concluding remarks

- The joint convergence  $(arepsilon, N) o (0,\infty)$  need to be clarify.
- Dependence of the model w.r.t. the initial conditions of ionic channels.
- Why, in the presented example, the stochastic celerity is smaller (in mean) than the deterministic one?
- In the model where both the potential and some ionic channels are fast, may we say more about the invariant measure of the fast system?



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Some Simulations

# Concluding remarks

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Thank you for your attention !