

STABLE GROUND STATES AND SELF-SIMILAR BLOW-UP SOLUTIONS FOR THE GRAVITATIONAL VLASOV-MANEV SYSTEM

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ABSTRACT. In this work, we study the orbital stability of steady states and the existence of blow-up self-similar solutions to the so-called Vlasov-Manev (VM) system. This system is a kinetic model which has a similar Vlasov structure as the classical Vlasov-Poisson system, but is coupled to a potential in $-1/r - 1/r^2$ (Manev potential) instead of the usual gravitational potential in $-1/r$, and in particular the potential field does not satisfy a Poisson equation but a fractional-Laplacian equation. We first prove the orbital stability of the ground states type solutions which are constructed as minimizers of the Hamiltonian, following the classical strategy: compactness of the minimizing sequences and the rigidity of the flow. However, in driving this analysis, there are two mathematical obstacles: the first one is related to the possible blow-up of solutions to the VM system, which we overcome by imposing a sub-critical condition on the constraints of the variational problem. The second difficulty (and the most important) is related to the nature of the Euler-Lagrange equations (fractional-Laplacian equations) to which classical results for the Poisson equation do not extend. We overcome this difficulty by proving the uniqueness of the minimizer under equimeasurability constraints, using only the regularity of the potential and not the fractional-Laplacian Euler-Lagrange equations itself. In the second part of this work, we prove the existence of exact self-similar blow-up solutions to the Vlasov-Manev equation, with initial data arbitrarily close to ground states. This construction is based on a suitable variational problem with equimeasurability constraint.

1. Introduction and main results

In this paper, we study the stability of steady states and the existence of blow-up self-similar solutions to the Vlasov-Manev (VM) model for gravitational systems. In this mean field kinetic model, the usual Newtonian interaction potential is replaced by the so-called Manev potential. This potential, which was studied in particular by Manev in the 1920' in order to explain some observed phenomena in planetary systems [19, 20, 21, 22], corrects the Newtonian gravitational potential as follows:

$$U(x) = -\frac{1}{4\pi|x|} - \frac{\kappa}{2\pi^2|x|^2},$$

where κ is a positive constant. We then consider in this paper the case of a potential given by:

$$U(x) = -\frac{\delta}{4\pi|x|} - \frac{\kappa}{2\pi^2|x|^2},$$

where δ is a nonnegative constant. Further physical studies of this potential can be found in [7]. The case $\delta = 1$, $\kappa = 0$ corresponds to the classical *Newtonian potential*. The case $\delta = 0$, $\kappa = 1$ will be referred to as the *pure Manev case*. The case $\delta > 0$,

$\kappa \geq 0$ will be referred to as *the Poisson-Manev case* which includes the Newtonian case.

Taking into account this correction, the standard Vlasov-Poisson system is replaced by the following Vlasov-Manev system:

$$\begin{cases} \partial_t f + v \cdot \nabla_x f - \nabla_x \phi_f \cdot \nabla_v f = 0, & (t, x, v) \in \mathbb{R}_+ \times \mathbb{R}^3 \times \mathbb{R}^3, \\ f(t=0, x, v) = f_0(x, v) \geq 0, \end{cases} \quad (1.1)$$

in which $f = f(t, x, v) \geq 0$ is a distribution function and ϕ_f the associated potential defined as follows. We have

$$\phi_f(t, x) = \delta \phi_f^P + \kappa \phi_f^M, \quad (1.2)$$

where ϕ_f^P and ϕ_f^M are respectively the Poisson potential and the Manev potential of f given by:

$$\phi_f^P(t, x) = - \int_{\mathbb{R}^3} \frac{\rho_f(t, y)}{4\pi|x-y|} dy, \quad \phi_f^M(t, x) = - \int_{\mathbb{R}^3} \frac{\rho_f(t, y)}{2\pi^2|x-y|^2} dy, \quad (1.3)$$

ρ_f being the density associated with the distribution function f :

$$\rho_f(t, x) = \int_{\mathbb{R}^3} f(t, x, v) dv.$$

Note that the two potentials satisfy

$$\Delta \phi_f^P = \rho_f \quad \text{and} \quad (-\Delta)^{1/2} \phi_f^M = -\rho_f,$$

and in particular the system (1.1) reduces to the well-known gravitational Vlasov-Poisson system in the case $\delta = 1$ and $\kappa = 0$.

To our knowledge, the only existing mathematical analysis of the Vlasov-Manev model is due to Bobylev, Dukes, Illner and Victory [5, 6]. In these works, the local existence of regular solutions is proved and some questions of global existence and finite-time blow-up are discussed.

We now give some basic properties of the Vlasov-Manev system (1.1). Sufficiently regular solutions to (1.1) on a time interval $[0, T]$ satisfy the conservation of the so-called Casimir functionals:

$$\forall t \in [0, T], \quad \|j(f(t))\|_{L^1} = \|j(f_0)\|_{L^1} \quad (1.4)$$

and the conservation of the Hamiltonian

$$\forall t \in [0, T], \quad \mathcal{H}(f(t)) = \mathcal{H}(f_0),$$

where j is any smooth real-valued function with $j(0) = 0$, and where

$$\mathcal{H}(f(t)) = \| |v|^2 f(t) \|_{L^1} - E_{pot}(f(t)). \quad (1.5)$$

The potential energy E_{pot} is defined by

$$E_{pot}(f(t)) = - \int_{\mathbb{R}^3} \phi_f(t, x) \rho_f(t, x) dx = \delta E_{pot}^P(f(t)) + \kappa E_{pot}^M(f(t)),$$

where we have denoted

$$E_{pot}^P(f(t)) = - \int_{\mathbb{R}^3} \phi_f^P(t, x) \rho_f(t, x) dx \quad \text{and} \quad E_{pot}^M(f(t)) = - \int_{\mathbb{R}^3} \phi_f^M(t, x) \rho_f(t, x) dx.$$

These potential energies are controlled thanks to standard interpolation inequalities:

$$0 \leq E_{pot}^P(f) \leq C_1 \| |v|^2 f \|_{L^1}^{\frac{1}{2}} \| f \|_{L^1}^{\frac{7p-9}{6(p-1)}} \| f \|_{L^p}^{\frac{p}{3(p-1)}}, \quad (1.6)$$

$$0 \leq E_{pot}^M(f) \leq C_2 \| |v|^2 f \|_{L^1} \| f \|_{L^1}^{\frac{p-3}{3(p-1)}} \| f \|_{L^p}^{\frac{2p}{3(p-1)}}, \quad (1.7)$$

for all $p \geq 3$.

Our aim in this paper is two folds. First we prove the orbital stability of ground states type stationary solutions to the Vlasov-Manev problem. Second we prove the existence of exact self-similar solutions to the pure Manev case and in particular we construct a continuous family of blow-up solutions to this system around each ground state. While the question of non linear stability has not been studied in the past for the VM system, it has attracted considerable attention in the case of the Vlasov-Poisson system ($\kappa = 0$), both in physics (see [1, 2], [3] and the references therein) and mathematics community [29, 8, 9, 10, 11, 26, 14]. Note that nonlinear asymptotic stability has been proved recently in the remarkable work [24, 25] in the case of spatially homogeneous steady states in bounded domains. We emphasize that the structure of the equation in the pure Manev case ($\delta = 0$, $\kappa = 1$) can be compared in some sense with the Vlasov-Poisson system in dimension 4 (see [11]), where blow-up self-similar profiles and pseudo-conformal symmetry are exhibited. In the pure Manev case, we shall construct ground states by minimizing the constant in the interpolation inequality (1.7), following the standard strategy as in the case of nonlinear Schrödinger equation [28].

On the other hand, the case of the general VM system ($\delta > 0$) is somehow similar to the relativistic Vlasov-Poisson system [13], where the stability is proved by minimizing the energy and by using a homogeneity-breaking property (which comes from the presence of two contributions in the expression of the general VM potential with different homogenities). This homogeneity-breaking property makes possible to built a well-posed variational problem provided a sub-critical condition is imposed on the constraints. In driving the classical approach as in [13] and [11], a new important difficulty appears. This difficulty is related to the nature of the Euler-Lagrange equations to which classical results for the Poisson equation do not extend. In the classical VP case, a complete stability result is generally obtained by using both the Euler-Lagrange equation (which is equivalent to a non linear Poisson equation) and the rigidity of the flow. In the present case, the Euler-Lagrange equation is a fractional-Laplacian equation, and this prevents from using ODE techniques. Nevertheless, we prove the uniqueness of the minimizer under equimeasurable constraints by a new argument which completely avoids ODE techniques. This argument is again used, together with the help of suitable rearrangement techniques as introduced in [15, 14], to prove the existence of exact self-similar solutions in the pure Manev case, and to build a continuous family of blow-up solutions around each minimizer.

In order to state our main results, let us make precise our assumptions. Consider a function $j : \mathbb{R}_+ \rightarrow \mathbb{R}_+$ satisfying the following hypotheses.

- (H1) j is a \mathcal{C}^2 function, with $j(0) = j'(0) = 0$ and such that $j''(t) > 0$ for $t > 0$.
(H2) There exist $p, q > 3$ such that

$$p \leq \frac{tj'(t)}{j(t)} \leq q, \quad \forall t > 0. \quad (1.8)$$

We note that (H2) is equivalent to the nondichotomy condition:

$$b^p j(t) \leq j(bt) \leq b^q j(t), \quad \forall b \geq 1, t \geq 0. \quad (1.9)$$

For a function j satisfying (H1) and (H2), we define the corresponding energy space

$$\mathcal{E}_j = \{f \geq 0 \text{ such that } \|f\|_{\mathcal{E}_j} := \|f\|_{L^1} + \|j(f)\|_{L^1} + \||v|^2 f\|_{L^1} < +\infty\} \quad (1.10)$$

and we shall say that a sequence f_n converges to f in \mathcal{E}_j if

$$\|f_n - f\|_{L^1} \rightarrow 0, \quad \|j(f_n - f)\|_{L^1} \rightarrow 0 \quad \text{and} \quad \||v|^2(f_n - f)\|_{L^1} \rightarrow 0.$$

From the interpolation inequality (1.7), the following constant is strictly positive:

$$K_j^M = \inf_{f \in \mathcal{E}_j \setminus \{0\}} K_j^M(f) \quad \text{with} \quad K_j^M(f) = \frac{\||v|^2 f\|_{L^1} \|f\|_{L^1}^{\frac{p-3}{3(p-1)}} \|f + j(f)\|_{L^1}^{\frac{2}{3(p-1)}}}{E_{pot}^M(f)}. \quad (1.11)$$

Indeed, from (1.9) one has $t + j(t) \geq Ct^p$ for all $t \geq 0$.

In our first result, we establish the existence of ground states for the Vlasov-Manev problem.

Theorem 1.1 (Existence of ground states). *Let j be a function satisfying (H1) and (H2).*

(i) Poisson-Manev case ($\delta > 0$). *Let $M_1 > 0$, $M_j > 0$ such that*

$$\kappa M_1^{\frac{p-3}{3(p-1)}} (M_1 + M_j)^{\frac{2}{3(p-1)}} < K_j^M, \quad (1.12)$$

where K_j^M is defined by (1.11), and let

$$\mathcal{F}(M_1, M_j) = \{f \in \mathcal{E}_j, \|f\|_{L^1} = M_1, \|j(f)\|_{L^1} = M_j\}.$$

Then there exists a steady state of (1.1) which minimizes the variational problem

$$I(M_1, M_j) = \inf_{f \in \mathcal{F}(M_1, M_j)} \mathcal{H}(f), \quad (1.13)$$

where \mathcal{H} is the Hamiltonian defined by (1.5).

(ii) Pure Manev case ($\delta = 0$, $\kappa = 1$). *For all $M_1, M_j > 0$, the following variational problem*

$$J(M_1, M_j) = \inf_{f \in \mathcal{F}(M_1, M_j)} K(f), \quad \text{with} \quad K(f) := \frac{\||v|^2 f\|_{L^1}}{E_{pot}^M(f)}. \quad (1.14)$$

admits a minimizer. Furthermore, for any given $M_1 > 0$, there exists a unique $M_j > 0$ such that $J(M_1, M_j) = 1$. Moreover, the minimizers of (1.14) are steady states to (1.1) if, and only if $J(M_1, M_j) = 1$.

(iii) In both cases ($\delta \geq 0$), any steady state Q obtained as a minimizer of (1.13) or (1.14) is continuous, compactly supported and takes the form

$$Q(x, v) = (j')^{-1} \left(\frac{\frac{|v|^2}{2} + \phi_Q(x) - \lambda}{\mu} \right)_+ \quad (1.15)$$

where λ and μ are negative constants. Moreover, $\phi_Q(x)$ is spherically symmetric (up to a translation shift), increasing and belongs to $\mathcal{C}^{1,\alpha}$, for all $\alpha \in (0, 1)$. In (1.15), we used the notation $a_+ = \max(a, 0)$.

Notice that in the case $\delta = 1$ and $\kappa = 0$, the condition (1.12) is always satisfied. In this case, the Vlasov-Manev system (1.1) is nothing but the classical Vlasov-Poisson system, for which it is already known that minimizers of the two constraints problem (1.13) always exist and that the minimizing sequences are compact, see [11]. In [13], the orbital stability in the case of the VP system has been proved thanks

to a uniqueness result of these minimizers which was based on a combination of the Poisson equation and the rigidity of the flow.

Our second main result concerns the orbital stability of the above constructed ground states under the action of the Vlasov-Manev flow. As in [13], the proof of these stability results needs in a crucial way the uniqueness of the minimizer under some flow constraints (namely the equimeasurability property). However in [13], the proof of this uniqueness was based on the use of the Poisson equation satisfied by the minimizer. Here, the Euler-Lagrange equation is a fractional Laplacian equation and the proof of [13] cannot be used. In fact, we prove this uniqueness result in a way that completely avoids the use of the Euler-Lagrange equation, and in particular, this generalizes also the uniqueness result obtained in [13]. The only property of the minimizers that we use is their equimeasurability. In particular, our proof avoids the usual ODE techniques, which in fact, are useless here since the Euler-Lagrange equation is a fractional-Laplacian equation.

Lemma 1.2 (Uniqueness of the minimizer under equimeasurability condition). *Let $F \in \mathcal{C}^0(\mathbb{R}, \mathbb{R}_+)$, strictly decreasing on \mathbb{R}_- , such that $F(\mathbb{R}_-) = \mathbb{R}_+$ and $F(\mathbb{R}_+) = \{0\}$. We define*

$$Q_0(x, v) = F\left(\frac{|v|^2}{2} + \psi_0(x)\right), \quad Q_1(x, v) = F\left(\frac{|v|^2}{2} + \psi_1(x)\right)$$

on $\mathbb{R}^3 \times \mathbb{R}^3$, where ψ_0 and ψ_1 are two nondecreasing continuous radially symmetric potentials such that the sets $\{x \in \mathbb{R}^3, \psi_0(x) < 0\}$ and $\{x \in \mathbb{R}^3, \psi_1(x) < 0\}$ are bounded. Then the equimeasurability of Q_0 and Q_1 for the Lebesgue measure in \mathbb{R}^6 , i.e.

$$\forall t > 0, \text{ meas}\{(x, v) \in \mathbb{R}^6, Q_0(x, v) > t\} = \text{ meas}\{(x, v) \in \mathbb{R}^6, Q_1(x, v) > t\}, \quad (1.16)$$

implies that $Q_0 = Q_1$. In particular:

(i) Poisson-Manev case ($\delta \neq 0$): two equimeasurable steady states of (1.1) which minimize (1.13) under the subcritical condition (1.12) are equal up to a translation in space.

(ii) Pure Manev case ($\delta = 0, \kappa = 1$): two equimeasurable steady states of (1.1) which minimize (1.14) and which have the same kinetic energy are equal up to a translation shift in space.

Now, using the compactness of all the minimizing sequences of (1.13) and (1.14) (which will be proved) and the uniqueness result stated in Lemma 1.2 we get the desired stability results.

Theorem 1.3 (Orbital stability of ground states).

(i) Poisson-Manev case ($\delta > 0$). Let $M_1, M_j > 0$ satisfying the subcritical condition (1.12). Then any steady state Q of (1.1) which minimizes (1.13) is orbitally stable under the flow (1.1). More precisely, given $\varepsilon > 0$, there exists $\delta(\varepsilon) > 0$ such that the following holds true. Consider f_0 a smooth function with $\|f_0 - Q\|_{\varepsilon_j} \leq \delta(\varepsilon)$, and let $f(t)$ be a classical solution to (1.1) on a time interval $[0, T)$, $0 < T \leq +\infty$, with initial data f_0 . Then there exists a translation shift $x(t) \in \mathbb{R}^3$ such that, for all $t \in [0, T)$, we have

$$\|f(t, x + x(t), v) - Q\|_{\varepsilon_j} < \varepsilon.$$

(ii) Pure Manev case ($\delta = 0$, $\kappa = 1$). Let Q be a steady state of (1.1) which minimizes (1.14). Then for all $\varepsilon > 0$, there exists a constant $\delta(\varepsilon) > 0$ such that the following property holds true. Let $f(t)$ be a classical solution to (1.1) on a time interval $[0, T)$, $0 < T \leq +\infty$, with initial data f_0 , satisfying:

$$(a) \|f_0 - Q\|_{L^1} \leq \delta(\varepsilon) \text{ and } \|j(f_0)\|_{L^1} \leq \|j(Q)\|_{L^1} + \delta(\varepsilon),$$

$$(b) \forall t \in [0, T), \quad \lambda(t)^2 \mathcal{H}(f(t)) < \delta(\varepsilon) \quad \text{where } \lambda(t) = \left(\frac{\| |v|^2 Q \|_{L^1}}{\| |v|^2 f(t) \|_{L^1}} \right)^{1/2}.$$

Then there exists a translation shift $x(t) \in \mathbb{R}^3$ such that, for all $t \in [0, T)$, we have

$$\left\| f \left(t, \lambda(t)(x + x(t)), \frac{v}{\lambda(t)} \right) - Q \right\|_{\mathcal{E}_j} < \varepsilon.$$

Remark 1.4. The goal here is to prove this stability result assuming the framework of classical solutions to the Vlasov-Manev model, and not to solve the Cauchy problem. For smooth initial data decaying fast enough at the infinity, the local existence and the uniqueness of regular solutions to (1.1) has been proved in [6]. The global existence of classical solutions is an open problem. Our result shows that the solutions remain in the vicinity of the ground state Q (up to a translation shift), but does not a priori exclude a possible blow-up of some derivative of f .

Notice that one may not be aimed at a better stability than the blow-up stability in the pure Manev case. Indeed the classical stability does not hold as shown by the following example (translating the pseudo-conformal symmetry property in this case): let $g = g(x, v)$ be a steady state of (1.1) in the pure Manev case ($\delta = 0$, $\kappa = 1$), then the function f_T defined by

$$f_T(t, x, v) = g \left(\frac{Tx}{T-t}, \frac{T-t}{T}v + \frac{x}{T} \right),$$

is a blow-up solution to the system (1.1) in the pure Manev case ($\delta = 0$, $\kappa = 1$), see [5, 6].

To go further with the pure Manev system our last result gives the existence of exact spherically symmetric self-similar solutions (we recall that a spherically symmetric function, in this context, is a function which only depends of $|x|$, $|v|$ and $x \cdot v$).

Theorem 1.5 (Exact self-similar solutions in the pure Manev case). *Let Q be a steady state of (1.1) in the pure Manev case ($\delta = 0$, $\kappa = 1$), which minimizes (1.14). Then there exists a constant $b^* > 0$ such that for all $b \in [0, b^*]$, there exists a compactly supported spherically symmetric profile $Q_b \in \mathcal{C}^0(\mathbb{R}^6)$ having the form*

$$Q_b(x, v) = F_b \left(\frac{|v|^2}{2} + bx \cdot v + \phi_{Q_b}(x) \right)$$

on its support, and such that, for all $T > 0$, the function

$$f(t, x, v) = Q_b \left(\frac{x}{\lambda(t)}, \lambda(t)v \right) \quad \text{with } \lambda(t) = \sqrt{2b(T-t)} \quad (1.17)$$

is an exact self-similar blow-up solution to the pure Manev system (1.1) in \mathcal{E}_j . Here, the function ϕ_{Q_b} belongs to \mathcal{C}^1 and the function F is a continuous nonnegative function on \mathbb{R} , which is \mathcal{C}^1 on $] -\infty, e_b[$ for some $e_b < 0$ and vanishes on $[e_b, +\infty[$. Moreover, Q_b converges to $Q_0 = Q$ in \mathcal{E}_j as $b \rightarrow 0$.

Remark 1.6. The previous results show that, in the pure Manev case ($\delta = 0$, $\kappa = 1$), around the ground state Q , there are at least three classes of dynamical profiles.

(i) *Subcritical solutions.* When the initial data f_0 is subcritical, i.e. when

$$J(\|f_0\|_{L^1}, \|j(f_0)\|_{L^1}) > 1 = J(\|Q\|_{L^1}, \|j(Q)\|_{L^1}),$$

then the kinetic energy of the solution $f(t)$ is controlled for all time. Indeed, one has

$$\mathcal{H}(f(t)) \geq \| |v|^2 f \|_{L^1} \left(1 - \frac{1}{K(f(t))} \right) \geq \| |v|^2 f \|_{L^1} \left(1 - \frac{1}{J(\|f_0\|_{L^1}, \|j(f_0)\|_{L^1})} \right).$$

Recall that J is defined by (1.14) and is continuous and decreasing with respect to its two arguments.

(ii) *Pseudo-conformal blow-up solutions.* The following family gives an explicit class of finite time blow-up solutions [5, 6]:

$$f(t, x, v) = Q \left(\frac{Tx}{T-t}, \frac{T-t}{T}v + \frac{x}{T} \right), \quad T > 0.$$

Note that the kinetic energy blows up with the rate $(T-t)^{-2}$.

(iii) *Self-similar blow-up solutions.* The family given by (1.17) blows up in finite time and the kinetic energy blows up with the rate $(T-t)^{-1}$.

The outline of the paper is as follows. Section 2 deals with the proof of Theorem 1.1. After preliminary technical results concerning some properties of the infimum $I(M_1, M_j)$ (Subsection 2.1), we prove in Subsection 2.2 the existence of minimizers. Then we characterize the ground states: Euler-Lagrange equation, regularity and spherical symmetry. Section 3 is devoted to the proof of stability of the ground state through the Vlasov-Manev flow as stated in Theorem 1.3. First, in Subsection 3.1, we prove the uniqueness of the ground state in the class of equimeasurable functions, Lemma 1.2. Then we use standard concentration-compactness arguments to prove the compactness of minimizing sequences. Combining the uniqueness and compactness properties, we finally deduce the orbital stability result, Theorem 1.3. Section 4 is devoted to the proof of the Theorem 1.5: in Subsection 4.1 we introduce the rearrangement with respect of a modified microscopic energy and apply it in Subsection 4.2 to build self-similar solutions of (1.1) in the pure Manev case $\delta = 0$, $\kappa = 1$.

2. Existence of ground states

This section is devoted to the proof of Theorem 1.1.

2.1. Properties of the infimum. In this section, we prove two lemmas concerning some monotonicity properties of the infimum defined by (1.13) and by (1.14).

Lemma 2.1 (Monotonicity properties of the infimum $I(M_1, M_j)$). *Let j be a real-valued function satisfying Assumptions (H1) and (H2), let $M_1 > 0$ and $M_j > 0$ such that (1.12) holds, and let $I(M_1, M_j)$ be defined by (1.13) in the case $\delta > 0$. Then we have*

$$-\infty < I(M_1, M_j) < 0. \tag{2.1}$$

Moreover the following nondichotomy condition holds true: for all $0 < \alpha < 1$ and $0 \leq \beta \leq 1$,

$$I(\alpha M_1, \beta M_j) + I((1 - \alpha)M_1, (1 - \beta)M_j) > I(M_1, M_j). \quad (2.2)$$

Proof. Step 1. The infimum is finite and negative.

We first prove (2.1). Let $f \in \mathcal{F}(M_1, M_j)$. Then from (1.6) and (1.11), we have

$$\begin{aligned} \mathcal{H}(f) &\geq \| |v|^2 f \|_{L^1} - \frac{\kappa}{K_j^M} \| |v|^2 f \|_{L^1} M_1^{\frac{p-3}{3(p-1)}} (M_1 + M_j)^{\frac{2}{3(p-1)}} \\ &\quad - C\delta \| |v|^2 f \|_{L^1}^{1/2} M_1^{\frac{7p-9}{6(p-1)}} (M_1 + M_j)^{\frac{1}{3(p-1)}} \\ &\geq \| |v|^2 f \|_{L^1} \left(1 - \frac{\kappa}{K_j^M} M_1^{\frac{p-3}{3(p-1)}} (M_1 + M_j)^{\frac{2}{3(p-1)}} \right) - C_{M_1, M_j} \| |v|^2 f \|_{L^1}^{1/2}. \end{aligned} \quad (2.3)$$

Now the subcritical condition (1.12) implies that

$$1 - \frac{\kappa}{K_j^M} M_1^{\frac{p-3}{3(p-1)}} (M_1 + M_j)^{\frac{2}{3(p-1)}} > 0.$$

Thus $\mathcal{H}(f)$ is bounded from below, which proves that $I(M_1, M_j)$ is finite. To prove that $I(M_1, M_j)$ is negative, we use a rescaling argument. For $\lambda > 0$ and $f \in \mathcal{F}(M_1, M_j)$, we consider the rescaled function $\tilde{f}(x, v) = f(\frac{x}{\lambda}, \lambda v)$. Then \tilde{f} belongs to $\mathcal{F}(M_1, M_j)$ and we have (see Appendix A)

$$\begin{aligned} \mathcal{H}(\tilde{f}) &= \frac{1}{\lambda^2} \| |v|^2 f \|_{L^1} - \frac{\delta}{\lambda} E_{pot}^P(f) - \frac{\kappa}{\lambda^2} E_{pot}^M(f) \\ &\sim -\frac{1}{\lambda} E_{pot}^P(f) \text{ as } \lambda \rightarrow +\infty, \end{aligned}$$

where $E_{pot}^P(f)$ is positive (since f is not zero). The property (2.1) follows.

Step 2. The nondichotomy condition.

We now claim the following monotonicity properties: for all $0 < k \leq 1$,

$$I(M_1, kM_j) \geq k^{\frac{1}{3(q-1)}} I(M_1, M_j) \quad (2.4)$$

and

$$I(kM_1, M_j) \geq k^{\frac{4p-6}{3(p-1)}} I(M_1, M_j). \quad (2.5)$$

Proof of (2.4). Let $k \in (0, 1]$ and $f \in \mathcal{F}(M_1, kM_j)$. From Appendix A, consider the unique rescaled function $\tilde{f}(x, v) = \alpha f(\alpha^{1/3}x, v)$ in $\mathcal{F}(M_1, M_j)$. From (A.2), we deduce in particular that $\alpha \geq 1$ and that

$$\alpha^{p-1} \leq \frac{1}{k} \leq \alpha^{q-1}.$$

Then, we get

$$\mathcal{H}(\tilde{f}) = \| |v|^2 f \|_{L^1} - \alpha^{\frac{1}{3}} \delta E_{pot}^P(f) - \alpha^{\frac{2}{3}} \kappa E_{pot}^M(f) \leq \| |v|^2 f \|_{L^1} - \alpha^{\frac{1}{3}} (\delta E_{pot}^P(f) + \kappa E_{pot}^M(f))$$

and

$$I(M_1, M_j) \leq \mathcal{H}(\tilde{f}) \leq \| |v|^2 f \|_{L^1} - \left(\frac{1}{k} \right)^{\frac{1}{3(q-1)}} (\delta E_{pot}^P(f) + \kappa E_{pot}^M(f)) \leq \left(\frac{1}{k} \right)^{\frac{1}{3(q-1)}} \mathcal{H}(f).$$

This result holds for all $f \in \mathcal{F}(M_1, kM_j)$ and $k \in (0, 1]$, which proves (2.4).

Proof of (2.5). Similarly, we take $f \in \mathcal{F}(kM_1, M_j)$ and set

$$\tilde{f}(x, v) = \alpha f(\alpha^{1/3} k^{1/3} x, v)$$

the unique rescaled function in $\mathcal{F}(M_1, M_j)$, which implies that $\alpha \leq 1$ with

$$\alpha^{q-1} \leq k \leq \alpha^{p-1}.$$

Thus,

$$\begin{aligned} \mathcal{H}(\tilde{f}) &= \frac{1}{k} \| |v|^2 f \|_{L^1} - \alpha^{1/3} k^{-5/3} \delta E_{pot}^P(f) - \alpha^{2/3} k^{-4/3} \kappa E_{pot}^M(f) \\ &\leq \frac{1}{k} \| |v|^2 f \|_{L^1} - \left(\frac{1}{k} \right)^{\frac{5p-6}{3(p-1)}} \delta E_{pot}^P(f) - \left(\frac{1}{k} \right)^{\frac{4p-6}{3(p-1)}} \kappa E_{pot}^M(f). \end{aligned}$$

From $k \leq 1$ and $p > 3$, we conclude that

$$I(M_1, M_j) \leq \mathcal{H}(\tilde{f}) \leq \left(\frac{1}{k} \right)^{\frac{4p-6}{3(p-1)}} \mathcal{H}(f),$$

and (2.5) follows.

We now prove (2.2). Let $0 < \alpha < 1$ and $0 \leq \beta \leq 1$. Then (2.4) and (2.5) imply

$$I(\alpha M_1, \beta M_j) \geq \alpha^{\frac{4p-6}{3(p-1)}} \beta^{\frac{1}{3(q-1)}} I(M_1, M_j),$$

and a similar inequality with $(1 - \alpha)$ and $(1 - \beta)$. As we have $I(M_1, M_j) < 0$, we only have to show that

$$\alpha^{\frac{4p-6}{3(p-1)}} \beta^{\frac{1}{3(q-1)}} + (1 - \alpha)^{\frac{4p-6}{3(p-1)}} (1 - \beta)^{\frac{1}{3(q-1)}} < 1,$$

which holds true since $q > 1$ and $\frac{4p-6}{3(p-1)} > 1$. The proof of Lemma 2.1 is complete. \square

Now we state the second lemma concerning the pure Manev case.

Lemma 2.2 (Monotonicity properties of the infimum $J(M_1, M_j)$). *Let j be a real-valued function satisfying Assumptions (H1) and (H2), let $M_1, M_j > 0$ and let $J(M_1, M_j)$ be defined by (1.14) in the case $\delta = 0$. Then for all $0 < \alpha \leq 1$ we have*

$$\alpha^{\frac{3-p}{3(p-1)}} J(M_1, M_j) \leq J(\alpha M_1, M_j) \leq \alpha^{\frac{3-q}{3(q-1)}} J(M_1, M_j), \quad (2.6)$$

$$\alpha^{-\frac{2}{3(q-1)}} J(M_1, M_j) \leq J(M_1, \alpha M_j) \leq \alpha^{-\frac{2}{3(p-1)}} J(M_1, M_j), \quad (2.7)$$

In particular, the function $(M_1, M_j) \mapsto J(M_1, M_j)$ is continuous.

Proof. Let $M_1, M_j > 0$ and $\alpha \in (0, 1]$. Let $f \in \mathcal{F}(\alpha M_1, M_j)$ and let

$$\tilde{f}(x, v) = \gamma f \left(\frac{\gamma^{1/3}}{\lambda^{1/3}} x, v \right)$$

be the unique rescaled function in $\mathcal{F}(M_1, M_j)$ given by Lemma A.1. Then we deduce from (A.2) that $\lambda = \frac{1}{\alpha}$ and, since $\alpha < 1$, we have also

$$\gamma^{q-1} \leq \alpha \leq \gamma^{p-1}.$$

Moreover, we also deduce from the rescaling identities of Appendix A that

$$K(\tilde{f}) = \alpha^{1/3} \gamma^{-2/3} K(f).$$

This yields (2.6). The inequality (2.7) is obtained similarly. \square

2.2. Proof of Theorem 1.1. We are now ready to prove Theorem 1.1 which concerns the existence of the minimizers and some of their properties.

Step 1. Existence of a minimizer.

The Poisson-Manev case ($\delta > 0$).

Let $M_1, M_j > 0$. From Lemma 2.1, we know that $I(M_1, M_j)$ is finite. Consider a minimizing sequence f_n of (1.13):

$$\|f_n\|_{L^1} = M_1, \quad \|j(f_n)\|_{L^1} = M_j \quad \text{and} \quad \lim_{n \rightarrow +\infty} \mathcal{H}(f_n) = I(M_1, M_j). \quad (2.8)$$

At fixed n , we denote by f_n^{*x} the standard Schwarz rearrangement of f_n with respect to the variable x . From the Riesz inequality, we have $E_{pot}(f_n^{*x}) \geq E_{pot}(f_n)$. Thus we have $\mathcal{H}(f_n^{*x}) \leq \mathcal{H}(f_n)$ and we may assume that the sequence f_n is spherically symmetric in space.

We now observe that the sequence (f_n) is bounded in \mathcal{E}_j . Indeed, from the subcritical condition (1.12), the kinetic energy of f_n is controlled by the inequality (2.3). Thus, from Lemma B.2 of Appendix B, there exists $f \in \mathcal{E}_j$ such that

$$f_n \rightharpoonup f \text{ in } L^p(\mathbb{R}^6) \text{ and } E_{pot}(f_n) \rightarrow E_{pot}(f).$$

By lower semi-continuity, we then have $\mathcal{H}(f) \leq I(M_1, M_j)$ which implies $f \neq 0$ since $I(M_1, M_j) < 0$ (see (2.1)). Therefore there exist $0 < \alpha, \beta \leq 1$ such that $\|f\|_{L^1} = \alpha M_1$ and $\|j(f)\|_{L^1} = \beta M_j$. Combining this with (2.5) and (2.4), we get

$$\alpha^{\frac{4p-6}{3(p-1)}} \beta^{\frac{1}{3(q-1)}} I(M_1, M_j) \leq \mathcal{H}(f) \leq I(M_1, M_j).$$

Hence $\alpha = \beta = 1$ and f is a minimizer of (1.13).

The pure Manev case ($\delta = 0, \kappa = 1$).

Let f_n be a minimizing sequence of (1.14). By a similar argument as above, we may assume that f_n is spherically symmetric in space. Moreover, from the rescaling formulas of Appendix B, the sequence of functions defined by $\hat{f}_n = f_n(\frac{x}{\lambda_n}, \lambda_n v)$ (where $\lambda_n^2 = \| |v|^2 f_n \|_{L^1}$) satisfies

$$\hat{f}_n \in \mathcal{F}(M_1, M_j), \quad K(\hat{f}_n) = K(f_n) \quad \text{and} \quad \| |v|^2 \hat{f}_n \|_{L^1} = 1.$$

In particular, (\hat{f}_n) is bounded in \mathcal{E}_j . From Lemma B.2 of Appendix B, there exists $\hat{f} \in \mathcal{E}_j$ such that

$$\hat{f}_n \rightharpoonup \hat{f} \text{ in } L^p(\mathbb{R}^6) \text{ and } E_{pot}(\hat{f}_n) \rightarrow E_{pot}(\hat{f}).$$

Since (\hat{f}_n) is a minimizing sequence of (1.14), $E_{pot}(\hat{f}_n)$ converges to $J(M_1, M_j)^{-1}$. This implies that

$$E_{pot}(\hat{f}) = J(M_1, M_j)^{-1} > 0$$

and then $\hat{f} \neq 0$.

Moreover, from Fatou's Lemma, we have $K(\hat{f}) \leq \liminf K(\hat{f}_n) = J(M_1, M_j)$ and we have also $\hat{f} \in \mathcal{F}(\alpha M_1, \beta M_j)$ with $0 < \alpha, \beta \leq 1$. A similar rescaling as in the proof of Lemma 2.2 gives

$$K(\hat{f}) \geq \frac{1}{\alpha^{\frac{q-3}{3(q-1)}} \beta^{\frac{2}{3(p-1)}}} J(M_1, M_j),$$

which implies that $\alpha = \beta = 1$. Therefore f is a minimizer of the variational problem (1.14).

Step 2. Euler-Lagrange equation for the minimizer.

The Poisson-Manev case ($\delta > 0$).

Let $M_1, M_2 > 0$ satisfy the subcritical condition (1.12) and let Q be a minimizer of (1.13). Our goal in this step is to derive the Euler-Lagrange equation satisfied by Q . Let $\varepsilon > 0$. We introduce the set

$$S_\varepsilon = \{(x, v) \in \mathbb{R}^6, Q(x, v) \geq \varepsilon\},$$

and pick a compactly supported function $g \in L^\infty(\mathbb{R}^6)$ such that $g > 0$ almost everywhere in $\mathbb{R}^6 \setminus S_\varepsilon$. Then,

$$\text{for all } t \in \left[0, \frac{\varepsilon}{\|g\|_\infty}\right], \quad f_t = Q + tg \in \mathcal{E}_j \setminus \{0\}.$$

Similarly as in Appendix A, there exists a unique pair (γ_t, η_t) positive numbers such that the function \tilde{f}_t defined by

$$\tilde{f}_t(x, v) = \gamma_t f_t \left(x, \left(\frac{\gamma_t}{\eta_t} \right)^{\frac{1}{3}} v \right)$$

belongs to $\mathcal{F}(M_1, M_j)$, which is equivalent to

$$\eta_t = \frac{M_1}{\|f_t\|_{L^1}} \quad \text{and} \quad \frac{1}{\gamma_t} \|j(\gamma_t f_t)\|_{L^1} = \frac{M_j}{M_1} \|f_t\|_{L^1}. \quad (2.9)$$

By differentiating the first equality, we obtain for $t \rightarrow 0$

$$\eta_t = 1 - \frac{\int_{\mathbb{R}^6} g}{M_1} t + o(t). \quad (2.10)$$

For all $t \in [0, \frac{\varepsilon}{\|g\|_\infty}]$ and for all $\gamma \in \mathbb{R}_+^*$, we set

$$G(\gamma, t) = \frac{1}{\gamma} \int_{\mathbb{R}^6} j(\gamma f_t) - \frac{M_j}{M_1} \int_{\mathbb{R}^6} f_t.$$

Then G is clearly a \mathcal{C}^1 function of t and γ . Moreover, from Appendix A, we get

$$\frac{\partial G}{\partial \gamma}(\gamma, t) > 0.$$

This implies that $t \mapsto \gamma_t$ is a \mathcal{C}^1 function and, by differentiating (2.9) with respect to t , we obtain

$$\gamma_t = 1 + \left(\frac{M_j}{M_1 C_Q} \int_{\mathbb{R}^6} g - \frac{1}{C_Q} \int_{\mathbb{R}^6} j'(Q)g \right) t + o(t), \quad \text{as } t \rightarrow 0, \quad (2.11)$$

where, from the hypothesis (1.8), $C_Q = \|j'(Q)Q\|_{L^1} - M_j$ is a positive constant. Since Q is a minimizer of (1.13) and since \tilde{f}_t belongs to $\mathcal{F}(M_1, M_j)$, we have

$$\lim_{t \rightarrow 0} \frac{\mathcal{H}(\tilde{f}_t) - \mathcal{H}(Q)}{t} \geq 0.$$

From the computation in Appendix A, we also have

$$\begin{cases} \left\| |v|^2 \tilde{f}_t \right\|_{L^1} - \left\| |v|^2 Q \right\|_{L^1} = \frac{\eta_t^{5/3}}{\gamma_t^{2/3}} \left(\left\| |v|^2 Q \right\|_{L^1} + t \int_{\mathbb{R}^6} |v|^2 g \right) - \left\| |v|^2 Q \right\|_{L^1}, \\ E_{pot}(\tilde{f}_t) - E_{pot}(Q) = \eta_t^2 \left(E_{pot}(Q) - 2t \int_{\mathbb{R}^6} \phi_Q g + t^2 E_{pot}(g) \right) - E_{pot}(Q). \end{cases}$$

Inserting the expansions (2.10) and (2.11) in these expressions, we get

$$\int_{\mathbb{R}^6} \left(\frac{|v|^2}{2} + \phi_Q - \lambda - \mu j'(Q) \right) g \geq 0, \quad (2.12)$$

with

$$\mu = -\frac{\left\| |v|^2 Q \right\|_{L^1}}{3C_Q} \quad \text{and} \quad \lambda = -\frac{1}{M_1} \left(E_{pot}(Q) - \frac{\left\| |v|^2 Q \right\|_{L^1}}{6} \left(5 + \frac{2M_j}{C_Q} \right) \right).$$

We now observe that μ and λ are negative. Indeed, the equality $I(M_1, M_j) = \left\| |v|^2 Q \right\|_{L^1} - E_{pot}(Q)$ gives

$$\lambda = \frac{1}{M_1} \left(I(M_1, M_j) - \frac{\left\| |v|^2 Q \right\|_{L^1}}{6C_Q} \int_{\mathbb{R}^6} (j'(Q)Q - 3j(Q)) \right),$$

where $I(M_1, M_j) < 0$ and, from (1.8), $j'(Q)Q - 3j(Q) \geq 0$. Since equality (2.12) holds for all $g \in L^\infty(\mathbb{R}^6)$ which is compactly supported on S_ε , we have

$$\frac{|v|^2}{2} + \phi_Q - \lambda - \mu j'(Q) = 0 \quad \text{on } S_\varepsilon.$$

This means that this equality holds on $\text{Supp}(Q)$. Similarly, out of the support of Q , as $g \geq 0$, we have

$$\frac{|v|^2}{2} + \phi_Q - \lambda \geq 0.$$

We finally get, for all $(x, v) \in (\mathbb{R}^3)^2$,

$$Q(x, v) = (j')^{-1} \left(\frac{\frac{|v|^2}{2} + \phi_Q(x) - \lambda}{\mu} \right)_+.$$

We will show later (Step 3) that ϕ_Q is a \mathcal{C}^1 function, which is sufficient to ensure that Q is a steady state. Indeed, from (H1), we deduce that the function $(j')^{-1}$ is \mathcal{C}^1 on \mathbb{R}_+^* with $(j')^{-1}(0) = 0$. Hence, Q being a function of the microscopic energy is a steady state of (1.1), at least in the weak sense. Note that Q is \mathcal{C}^1 in the interior of its support and is continuous but may have an infinite derivative at the boundary of its support.

The pure Manev case ($\delta = 0$, $\kappa = 1$).

Let Q be a minimizer of (1.14). To get the Euler-Lagrange equation, we simply differentiate $f \mapsto K(f)$ following the same procedure as above and find after computations

$$Q = (j')^{-1} \left(\frac{\frac{|v|^2}{2} + \gamma \phi_Q(x) - \lambda}{\mu} \right)_+$$

with

$$\gamma = \frac{\| |v|^2 Q \|_{L^1}}{E_{pot}(Q)} = J(M_1, M_j), \quad \lambda = -\frac{(C_Q - 2M_j) \| |v|^2 Q \|_{L^1}}{6M_1 C_Q}, \quad \mu = -\frac{\| |v|^2 Q \|_{L^1}}{3C_Q}.$$

By inserting these expressions in (1.1), we observe that f is a steady state of (1.1) if and only if $\gamma = 1$, which means $J(M_1, M_j) = 1$. Let $M_1 > 0$ be fixed. From the control of the infimum (2.7), we deduce that the function $M_j \mapsto J(M_1, M_j)$ is continuous, strictly decreasing and satisfies

$$\lim_{M_j \rightarrow 0} J(M_1, M_j) = +\infty, \quad \lim_{M_j \rightarrow +\infty} J(M_1, M_j) = 0.$$

Therefore, it is clear that there exists a unique M_j such that $J(M_1, M_j) = 1$.

Step 3. Regularity of the potential ϕ_Q and compact support of Q

Let us prove that ϕ_Q belongs to $\mathcal{C}^{1,\alpha}$, for all $\alpha \in (0, 1)$. Using the expression of Q , we get

$$\rho_Q(x) = \int_{\mathbb{R}^3} (j')^{-1} \left(\frac{\frac{|v|^2}{2} + \phi_Q(x) - \lambda}{\mu} \right)_+ dv. \quad (2.13)$$

Passing to the spherical velocity coordinate $u = |v|$ and performing the change of variable $w = \frac{u^2}{2|\mu|}$, we get

$$\rho_Q(x) = 4\pi\sqrt{2}|\mu|^{\frac{3}{2}} \int_0^{+\infty} (j')^{-1} (k(x) - w)_+ \sqrt{w} dw, \quad (2.14)$$

where $k(x) = \frac{\phi_Q(x) - \lambda}{\mu}$. We remark that the support of ρ_Q is contained in $\{x \in \mathbb{R}^3, k(x) \geq 0\}$ and that $k(x)_+ \leq \phi_Q(x)/\mu$. Moreover, from (H2), for all $s \geq 0$ we have

$$(j')^{-1}(s) \leq C \left(s^{\frac{1}{p-1}} + s^{\frac{1}{q-1}} \right).$$

Therefore

$$\begin{aligned} \rho_Q(x) &\leq C \int_0^{k(x)_+} \left((k(x) - w)^{\frac{1}{p-1}} + (k(x) - w)^{\frac{1}{q-1}} \right) \sqrt{w} dw \\ &\leq C \left((k(x)_+)^{\frac{3}{2} + \frac{1}{p-1}} + ((k(x)_+)^{\frac{3}{2} + \frac{1}{q-1}}) \right) \\ &\leq C \left(|\phi_Q(x)|^{\frac{3}{2} + \frac{1}{p-1}} + |\phi_Q(x)|^{\frac{3}{2} + \frac{1}{q-1}} \right). \end{aligned} \quad (2.15)$$

Since Q belongs $L^1 \cap L^p$, $p > 3$, and since $|v|^2 Q$ belongs to L^1 , we deduce from interpolation inequalities that $\rho_Q \in L^1 \cap L^{p_0}$ with $p_0 = \frac{5p-3}{3p-1} \in (\frac{3}{2}, \frac{5}{3}]$.

Assume now that $\rho_Q \in L^1 \cap L^k$ for some $\frac{3}{2} < k < 3$. Then from the Hardy-Littlewood-Sobolev inequality, we deduce that ϕ_Q^P belongs to all L^s with $3 < s \leq \infty$ and that ϕ_Q^M belongs to all L^s with $\frac{3}{2} < s \leq \frac{3k}{3-k}$. Hence, from (2.15), since $q \geq p$, we deduce that the function ρ_Q belongs to L^ℓ with

$$\ell \left(\frac{3}{2} + \frac{1}{p-1} \right) = \frac{3k}{3-k}. \quad (2.16)$$

Using (2.16) and $p > 3$ (Assumption (H2)), a simple bootstrap argument enables to prove that there exists $r > 3$ such that $\rho_Q \in L^r$.

Consequently, from Sobolev embeddings and from $(-\Delta)^{1/2}\phi_Q^M = -\rho_Q$, we deduce that the Manev potential ϕ_Q^M belongs to $\mathcal{C}^{0,\alpha}$ for all $\alpha \in (0, 1 - \frac{3}{r})$. Since this function converges to 0 at the infinity, we have $\phi_Q^M \in L^\infty$, and then $\phi_Q \in L^\infty$. Thus (2.15) gives $\rho_Q \in L^\infty$. Finally, using again Sobolev embeddings, ϕ_Q^M and ϕ_Q^P belong to $\mathcal{C}^{0,\alpha}$ for all $\alpha \in (0, 1)$.

From the regularity of ϕ_Q , the fact that this function goes to 0 as $|x| \rightarrow +\infty$ and that $\lambda < 0$, one deduces that

$$\text{Supp}(Q) = \left\{ (x, v) \in \mathbb{R}^6, \quad \frac{|v|^2}{2} + \phi_Q(x) - \lambda \leq 0 \right\}$$

is a compact subset of \mathbb{R}^6 .

Let us now prove that ρ_Q belongs to $\mathcal{C}^{0,\alpha}$ for all $\alpha \in (0, 1)$. Passing to the spherical coordinate in velocity in the expression (2.13) of ρ_Q and performing the change of variable $s = \frac{\frac{|v|^2}{2} + \phi_Q(x) - \lambda}{\mu}$ yields

$$\rho_Q(x) = |\mu|^{\frac{3}{2}} \sqrt{2} \int_{\mathbb{R}_+} (j')^{-1}(s) \left(\frac{\phi_Q(x) - \lambda}{\mu} - s \right)_+^{1/2} ds.$$

For all $k \in \mathbb{R}$, denote $f(k) = \int_{\mathbb{R}_+} (j')^{-1}(s) (k - s)_+^{1/2} ds$. We claim that, for all $k_0 > 0$, we have

$$\forall k_1, k_2 \in (-\infty, k_0], \quad |f(k_1) - f(k_2)| \leq (j')^{-1}(k_0) k_0^{1/2} |k_1 - k_2|. \quad (2.17)$$

By taking $k_0 = \frac{-\|\phi_Q\|_\infty - \lambda}{\mu}$, we deduce from this claim that

$$\forall (x, y) \in \mathbb{R}^6, \quad |\rho_Q(x) - \rho_Q(y)| \leq C |\phi_Q(x) - \phi_Q(y)|.$$

This shows that $\rho_Q \in \mathcal{C}^{0,\alpha}$ for all $\alpha \in (0, 1)$. Next, since we have

$$\phi_Q = \Delta^{-1}(\rho_Q) - (-\Delta)^{-1/2}(\rho_Q),$$

we can conclude from standard regularity argument that $\phi_Q \in \mathcal{C}^{1,\alpha}$ for all $\alpha \in (0, 1)$. This is the regularity of the potential stated in Theorem 1.1. Let us now prove the claim (2.17). For all $k_1 \leq k_2 \leq k_0$, we have

$$\begin{aligned} f(k_2) - f(k_1) &= \int_{\mathbb{R}_+} (j')^{-1}(s) \left((k_2 - s)_+^{1/2} - (k_1 - s)_+^{1/2} \right) ds \\ &\leq (j')^{-1}(k_0) \int_{\mathbb{R}_+} \left((k_2 - s)_+^{1/2} - (k_1 - s)_+^{1/2} \right) ds \\ &= \frac{2}{3} (j')^{-1}(k_0) \left((k_2)_+^{3/2} - (k_1)_+^{3/2} \right) \leq (j')^{-1}(k_0) k_0^{1/2} (k_2 - k_1). \end{aligned}$$

Since f is an increasing function, this yields (2.17). This concludes the proof of the regularity of the potential stated in Theorem 1.1.

Step 4. The functions ρ_Q and ϕ_Q are spherically symmetric and monotone.

Consider a minimizer Q of (1.13), continuous and compactly supported thanks to the previous step, and denote by Q^{*x} its symmetric rearrangement with respect to the x variable only. We have clearly $Q^{*x} \in \mathcal{F}(M_1, M_j)$ and $\int |v|^2 Q dx dv = \int |v|^2 Q^{*x} dx dv$. Moreover, by the Riesz inequality (see [16]), we have

$$\int_{\mathbb{R}^6} Q(x, v) Q(y, w) g(|x - y|) dx dy \leq \int_{\mathbb{R}^6} Q^{*x}(x, v) Q^{*x}(y, w) g(|x - y|) dx dy \quad (2.18)$$

for all $(v, w) \in \mathbb{R}^3 \times \mathbb{R}^3$, where $g(r) = \frac{\delta}{r} + \frac{\kappa}{r^2}$ (recall that $\delta \geq 0$ and $\kappa \geq 0$). Therefore, by integrating this inequality with respect to v and w , one gets

$$E_{pot}(Q) \leq E_{pot}(Q^{*x}),$$

which means that $\mathcal{H}(Q^{*x}) \leq \mathcal{H}(Q)$: Q^{*x} is also a minimizer of (1.13). Hence, we must have equality in the above inequalities: $E_{pot}(Q) = E_{pot}(Q^{*x})$ and, even more, we have an equality in (2.18) for all v, w . We are then in a situation of equality in the Riesz inequality: since the function g is strictly decreasing, we deduce that (see [16]), for all v, w , there exists a translation shift $x_0(v, w)$ such that

$$Q(x, v) = Q^{*x}(x + x_0(v, w), v) \quad \text{and} \quad Q(x, w) = Q^{*x}(x + x_0(v, w), w). \quad (2.19)$$

Let v be such that $Q(\cdot, v) \not\equiv 0$. Q being compactly supported, we integrate the first equality in (2.19) against x and obtain

$$\begin{aligned} \int_{\mathbb{R}^3} xQ(x, v)dx &= \int_{\mathbb{R}^3} xQ^{*x}(x + x_0(v, w), v)dx \\ &= \int_{\mathbb{R}^3} xQ^{*x}(x, v)dx - x_0(v, w) \int_{\mathbb{R}^3} Q^{*x}(x, v)dx. \end{aligned}$$

Hence, we have the expression

$$x_0(v, w) = \frac{\int_{\mathbb{R}^3} x(Q(x, v) - Q^{*x}(x, v))dx}{\int_{\mathbb{R}^3} Q^{*x}(x, v)dx}$$

and then $x_0(v, w)$ is independent of w . Similarly, using the second equality in (2.19), one obtain that x_0 is independent of v . We have proved finally that there exists $x_0 \in \mathbb{R}^3$ such that

$$Q(x, v) = Q^{*x}(x + x_0, v) = Q^{*x}(|x + x_0|, v), \quad \forall v \in \mathbb{R}^3.$$

Consequently, up to a translation shift, ρ_Q is a nonincreasing function of $|x|$.

Let us now prove that ϕ_Q is a nondecreasing function of $r = |x|$. Since the function j is convex and $\mu < 0$, the expression (2.13) shows that $\phi_Q(r)$ is nondecreasing on the compact support of the nonincreasing function $\rho_Q(r)$. Let $[0, R_Q]$ be this compact support.

For $|x| = r > R_Q$, we have

$$\phi_Q^P(x) = - \int_{\mathbb{R}^3} \frac{\rho_Q(y)}{4\pi|x-y|} dy \quad \text{and} \quad \phi_Q^M(x) = - \int_{\mathbb{R}^3} \frac{\rho_Q(y)}{2\pi^2|x-y|^2} dy.$$

Passing to the spherical coordinate (see the proof of Proposition B.1 in Appendix B), we have

$$\phi_Q^P(x) = -\frac{M_1}{4\pi r} \quad \text{and} \quad \phi_Q^M(x) = -\frac{1}{\pi} \int_0^{R_Q} \frac{s\rho_Q(s)}{r} \ln\left(\frac{r+s}{r-s}\right) ds.$$

Since the function $r \mapsto \frac{1}{r} \ln\left(1 + \frac{2s}{r-s}\right)$ is positive and decreasing, ϕ_Q is nondecreasing on $[R_Q, +\infty)$. The proof of Theorem 1.1 is complete. \square

3. Orbital stability of the ground states

To prove the orbital stability result stated in Theorem 1.3, we first need to prove the uniqueness of the minimizer under equimeasurability and symmetric constraints which are inherited from the invariance properties of the Vlasov-Manev flow. This uniqueness result is at the heart of our stability analysis and is quite robust in the sense that its proof does not use the Euler-Lagrange equation. Technically, the uniqueness proof only uses the fact that a minimizer is a function of a certain microscopic energy, which is not necessarily that of the minimizer. Therefore our proof does not use the equation satisfied by the potential itself (a non linear fractional-Laplacian equation in the present case).

3.1. Uniqueness of the minimizer under equimeasurability condition. This subsection is devoted to the proof of Lemma 1.2.

Let

$$Q_0(x, v) = F\left(\frac{|v|^2}{2} + \psi_0(x)\right), \quad Q_1(x, v) = F\left(\frac{|v|^2}{2} + \psi_1(x)\right)$$

be the functions defined in Theorem 1.2. Note that ψ_0 and ψ_1 are not supposed to coincide with ϕ_{Q_0} and ϕ_{Q_1} respectively, which means that they are not supposed to satisfy the fractional-Laplacian equation. For $i \in \{0, 1\}$ and for all $\tau < 0$, we define

$$a_{\psi_i}(\tau) = \text{meas} \left\{ (x, v) \in \mathbb{R}^6, \quad \frac{|v|^2}{2} + \psi_i(x) < \tau \right\}.$$

From the equimeasurability of Q_0 and Q_1 and the properties of the function F , we have

$$\forall \tau < 0, \quad a_{\psi_0}(\tau) = a_{\psi_1}(\tau). \quad (3.1)$$

For $i \in \{0, 1\}$, we define

$$\mu_{\psi_i}(\lambda) = \text{meas} \{x \in \mathbb{R}^3, \quad \psi_i(x) < \lambda\}$$

for all $\lambda < 0$ and we have then for all $\tau < 0$,

$$a_{\psi_i}(\tau) = \int_{\mathbb{R}^3} \mu_{\psi_i} \left(\tau - \frac{|v|^2}{2} \right) dv.$$

Passing to the spherical velocity coordinate $u = |v|$ and performing the change of variable $w = \tau - u^2/2$, we obtain

$$a_{\psi_i}(\tau) = 4\pi\sqrt{2} \int_{-\infty}^{\tau} \mu_{\psi_i}(w) \sqrt{\tau - w} dw. \quad (3.2)$$

We claim that the expression (3.2) and the equality (3.1) imply that,

$$\text{for almost all } \lambda < 0, \quad \mu_{\psi_0}(\lambda) = \mu_{\psi_1}(\lambda). \quad (3.3)$$

Hence, as ψ_0 and ψ_1 are continuous and nondecreasing, we have $\psi_0 = \psi_1$ on the set

$$\{x \in \mathbb{R}^3, \psi_0(x) < 0\} = \{x \in \mathbb{R}^3, \psi_1(x) < 0\},$$

which immediatly gives $Q_0 = Q_1$.

Proof of (3.3) from (3.1) and (3.2). By differentiating with respect to τ the function a_{ψ_i} defined by (3.2), one gets

$$\forall \tau < 0, \quad a'_{\psi_i}(\tau) = 2\pi\sqrt{2} \int_{-\infty}^{\tau} \frac{\mu_{\psi_i}(w)}{\sqrt{\tau - w}} dw. \quad (3.4)$$

Now, remarking that, for $w < \lambda$, the following integral is constant:

$$I(\lambda, w) = \int_w^\lambda \frac{d\tau}{\sqrt{(\lambda - \tau)(\tau - w)}} = \pi,$$

one deduces from the Fubini theorem that

$$\int_{-\infty}^\lambda \frac{a'_{\psi_i}(\tau)}{\sqrt{\lambda - \tau}} d\tau = 2\pi\sqrt{2} \int_{-\infty}^\lambda \mu_{\psi_i}(w) I(\lambda, w) dw = 2\pi^2\sqrt{2} \int_{-\infty}^\lambda \mu_{\psi_i}(w) dw.$$

Thus, from $a_{\psi_0} = a_{\psi_1}$, we deduce that $\mu_{\psi_0}(\lambda) = \mu_{\psi_1}(\lambda)$ for almost all $\lambda < 0$, and the proof of (3.3) is complete.

End of the proof of Lemma 1.2. Let Q_0, Q_1 be two equimeasurable and spherically symmetric steady states to (1.1) which minimize the variational problem (1.13) in the Poisson-Manev case ($\delta > 0$) or the variational problem (1.14) in the pure Manev case ($\delta = 0, \kappa = 1$). From Theorem 1.1, there exist $\lambda_0, \mu_0, \lambda_1, \mu_1 < 0$ such that, for $i \in \{0, 1\}$,

$$Q_i(x, v) = (j')^{-1} \left(\frac{\frac{|v|^2}{2} + \phi_{Q_i}(x) - \lambda_i}{\mu_i} \right)_+. \quad (3.5)$$

We now define, for $i \in \{0, 1\}$,

$$\tilde{Q}_i(x, v) = Q_i \left(\frac{x}{|\mu_i|^{1/2}}, |\mu_i|^{1/2} v \right).$$

The function \tilde{Q}_0 and \tilde{Q}_1 are still equimeasurable and satisfy

$$\tilde{Q}_i(x, v) = (j')^{-1} \left(-\frac{|v|^2}{2} - \psi_i(x) \right)_+ \quad \text{with} \quad \psi_i(x) = \frac{\phi_{Q_i} \left(\frac{x}{|\mu_i|^{1/2}} \right) - \lambda_i}{|\mu_i|}.$$

Since ϕ_{Q_i} is continuous nondecreasing and converges to 0 as $r \rightarrow +\infty$, the function ψ_i is continuous, nondecreasing and the set $\{x \in \mathbb{R}^3, \psi_0(x) < 0\}$ is bounded. From the previous step, we then conclude that

$$\tilde{Q}_0 = \tilde{Q}_1,$$

which means that

$$Q_1(x, v) = Q_0 \left(\frac{x}{\alpha}, \alpha v \right) \quad \text{with} \quad \alpha = \sqrt{\frac{\mu_1}{\mu_0}}. \quad (3.6)$$

We shall now prove that $\alpha = 1$.

The pure Manev case. In this case, the equality of the kinetic energies (which is assumed in this lemma) directly gives $\alpha = 1$.

The Poisson-Manev case. Let us derive a virial identity satisfied by the minimizers Q of (1.13), using a rescaling argument. For $\lambda > 0$, we set $f_\lambda(x, v) = Q(\lambda x, \frac{v}{\lambda})$, which implies $f_\lambda \in \mathcal{F}(M_1, M_j)$ and

$$\mathcal{H}(f_\lambda) = \lambda^2 \| |v|^2 Q \|_{L^1} - \lambda \delta E_{pot}^P(Q) - \lambda^2 \kappa E_{pot}^M(Q).$$

This function of λ has a strict global minimizer in $\lambda = 1$, which yields the following virial identity:

$$\| |v|^2 Q \|_{L^1} - \frac{\delta}{2} E_{pot}^P(Q) - \kappa E_{pot}^M(Q) = 0. \quad (3.7)$$

Moreover we recall that Q satisfies

$$\| |v|^2 Q \|_{L^1} - \delta E_{pot}^P(Q) - \kappa E_{pot}^M(Q) = I(M_1, M_j).$$

Combining this two equalities, we get

$$\frac{\delta}{2} E_{pot}^P(Q) = -I(M_1, M_j). \quad (3.8)$$

Let us now use this identity for the two minimizers Q_0 and Q_1 . From (3.8) and (2.1), one deduces that

$$E_{pot}^P(Q_0) = E_{pot}^P(Q_1) > 0.$$

Moreover, from (3.6) and Appendix A, one gets

$$E_{pot}^P(Q_1) = \frac{1}{\alpha} E_{pot}^P(Q_0).$$

This yields $\alpha = 1$, which ends the proof of Lemma 1.2. \square

3.2. Orbital stability of the minimizers, proof of Theorem 1.3. In this subsection, we prove Theorem 1.3.

The Poisson-Manev case.

Let Q be a minimizer of (1.13) and assume that Theorem 1.3 is false. Then there exist $\varepsilon > 0$ and sequences $f_0^n \in \mathcal{E}_j$, $t_n > 0$, such that

$$\lim_{n \rightarrow +\infty} \|f_0^n - Q\|_{\mathcal{E}_j} = 0, \quad (3.9)$$

and

$$\forall n \geq 0, \forall x_0 \in \mathbb{R}^3, \|f^n(t_n, x, v) - Q(x + x_0, v)\|_{\mathcal{E}_j} \geq \varepsilon, \quad (3.10)$$

where $f^n(t, x, v)$ is a solution to (1.1) with initial data f_0^n .

From (3.9), we have

$$\lim_{n \rightarrow +\infty} \mathcal{H}(f_0^n) = I(M_1, M_j), \quad \lim_{n \rightarrow +\infty} \|f_0^n\|_{L^1} = M_1, \quad \lim_{n \rightarrow +\infty} \|j(f_0^n - Q)\|_{L^1} = 0. \quad (3.11)$$

In particular, f_0^n converges to Q in the strong L^p topology and hence almost everywhere, up to a subsequence. Using the assumptions (H1), (H2) and the convexity of j , we deduce from a classical argument (see Theorem 2 in [4]) that $\|j(f_0^n)\|_{L^1} \rightarrow \|j(Q)\|_{L^1}$.

Let now $g_n(x, v) = f_n(t_n, x, v)$. By the conservation properties of the Vlasov-Manev system (1.1), we have

$$\lim_{n \rightarrow +\infty} \mathcal{H}(g_n) = I(M_1, M_j), \quad \lim_{n \rightarrow +\infty} \|g_n\|_{L^1} = M_1, \quad \lim_{n \rightarrow +\infty} \|j(g_n)\|_{L^1} = M_j, \quad (3.12)$$

and, for all $t \geq 0$,

$$\text{meas}\{(x, v) \in \mathbb{R}^6, g_n(x, v) > t\} = \text{meas}\{(x, v) \in \mathbb{R}^6, f_0^n(x, v) > t\}. \quad (3.13)$$

From Appendix A, let us define

$$\bar{g}_n(x, v) = \gamma_n g_n \left(\frac{\gamma_n^{1/3}}{\lambda_n^{1/3}} x, v \right)$$

such that $\|\bar{g}_n\|_{L^1} = M_1$ and $\|j(\bar{g}_n)\|_{L^1} = M_j$. Then, from (3.12),

$$\gamma_n \rightarrow 1, \quad \lambda_n \rightarrow 1, \quad (3.14)$$

and

$$\lim_{n \rightarrow +\infty} \mathcal{H}(\bar{g}_n) = \lim_{n \rightarrow +\infty} \mathcal{H}(g_n) = I(M_1, M_j).$$

Hence \bar{g}_n is a minimizing sequence of (1.13). Now, from classical arguments based on concentration-compactness techniques ([17], [18]) and the non-dichotomy inequality (2.2) (see [11] and [13] for more details), \bar{g}_n is relatively strongly compact in \mathcal{E}_j and converges to a ground state Q_1 , up to a subsequence and up to a translation shift in space. Hence, by (3.14), we have

$$g_n \rightarrow Q_1 \text{ in } \mathcal{E}_j \quad (3.15)$$

up to a subsequence and up to a translation shift.

Let us now prove that the equimeasurability (3.13) and the L^1 convergences of g_n and f_0^n imply the equimeasurability of Q and Q_1 . Indeed, we remark that, for $t > 0$ and $0 < \varepsilon < t$,

$$\begin{cases} \{g_n > t\} \subset (\{|g_n - Q_1| < \varepsilon\} \cap \{Q_1 > t - \varepsilon\}) \cup \{|g_n - Q_1| \geq \varepsilon\}, \\ \{g_n > t\} \supset \{|g_n - Q_1| < \varepsilon\} \cap \{Q_1 > t + \varepsilon\}. \end{cases}$$

By passing to the limit as $n \rightarrow +\infty$, one gets

$$\begin{cases} \limsup_{n \rightarrow +\infty} \text{meas}\{g_n > t\} \leq \text{meas}\{Q_1 > t - \varepsilon\}, \\ \liminf_{n \rightarrow +\infty} \text{meas}\{g_n > t\} \geq \text{meas}\{Q_1 > t + \varepsilon\}. \end{cases}$$

Finally, passing to the limit as $\varepsilon \rightarrow 0$, we have $\text{meas}\{g_n > t\} \rightarrow \text{meas}\{Q_1 > t\}$ for almost all $t > 0$ and similarly $\text{meas}\{f_n^0 > t\} \rightarrow \text{meas}\{Q > t\}$ for almost all $t > 0$. Observing that the functions $t \mapsto \text{meas}\{Q > t\}$ and $t \mapsto \text{meas}\{Q_1 > t\}$ are right-continuous, we obtain the equimeasurability of Q and Q_1 .

We now use the characterization of ground states stated in Theorem 1.1 and the uniqueness result given by Lemma 1.2, to conclude that, $Q = Q_1$, up to a space translation shift. Finally, (3.15) contradicts (3.10) and the proof of Theorem 1.3 is complete. \square

The pure Manev case.

To prove Theorem 1.3 for the pure Manev case, it is clearly sufficient to prove the following proposition.

Proposition 3.1. *Let Q be a steady state of (1.1) which minimizes (1.14) and let $(f_n)_{n \geq 1} \in \mathcal{E}_j$ such that*

$$\forall s > 0, \quad \lim_{n \rightarrow +\infty} \text{meas}\{(x, v) \in \mathbb{R}^6, f_n(x, v) > s\} = \text{meas}\{(x, v) \in \mathbb{R}^6, Q(x, v) > s\} \quad (3.16)$$

and

$$\|f_n\|_{L^1} \rightarrow \|Q\|_{L^1}, \quad \limsup_{n \rightarrow +\infty} \|j(f_n)\|_{L^1} \leq \|j(Q)\|_{L^1} \text{ and } \limsup \frac{\mathcal{H}(f_n)}{\| |v|^2 f_n \|_{L^1}} \leq 0. \quad (3.17)$$

Then there exists $(y_n)_{n \geq 1}$ sequence on \mathbb{R}^3 such that up to a subsequence

$$f_n \left(\lambda_n(x + y_n), \frac{v}{\lambda_n} \right) \rightarrow Q \text{ in } \mathcal{E}_j, \quad \text{where } \lambda_n = \left(\frac{\| |v|^2 Q \|_{L^1}}{\| |v|^2 f_n \|_{L^1}} \right)^{1/2}.$$

Proof. From the assumption (ii), the sequence of rescaled functions defined by $\hat{f}_n(x, v) = f_n(\lambda_n x, \frac{v}{\lambda_n})$ satisfies

$$\forall s > 0, \quad \lim_{n \rightarrow +\infty} \text{meas}\{(x, v) \in \mathbb{R}^6, \hat{f}_n(x, v) > s\} = \text{meas}\{(x, v) \in \mathbb{R}^6, Q(x, v) > s\}, \quad (3.18)$$

$$\limsup \mathcal{H}(\hat{f}_n) \leq 0 \text{ and then } \liminf E_{pot}(\hat{f}_n) \geq \| |v|^2 Q \|_{L^1} = E_{pot}(Q) > 0. \quad (3.19)$$

From concentration-compactness argument [17, 18] and using Lemma 3.2 in [11], one can deduce that the sequence \hat{f}_n satisfies one of the three following alternatives: compactness, vanishing or dichotomy, see e.g. Lemma 3.2 in [11] for the definitions of these standard notions. In fact, we shall prove that only compactness may occur.

Indeed, vanishing cannot occur, since (3.19) prevents $E_{pot}(\hat{f}_n)$ from going to 0 as $n \rightarrow +\infty$. Next, if dichotomy occurs (see [11]), then there exist $0 < \alpha < 1$ such that, for all $\varepsilon > 0$, there exists a decomposition $\hat{f}_n = f_n^1 + f_n^2 + w_n$, with disjoint supports, such that we have

$$\| \|f_n^1\|_{L^1} - \alpha \|Q\|_{L^1} \| + \| \|f_n^2\|_{L^1} - (1 - \alpha) \|Q\|_{L^1} \| < \varepsilon, \quad (3.20)$$

and

$$\left| E_{pot}(\hat{f}_n) - E_{pot}(f_n^1) - E_{pot}(f_n^2) \right| < \varepsilon. \quad (3.21)$$

The control of the mass (3.20) and the monotonicity of the infimum from Lemma 2.2 imply that

$$K(f_n^1) \geq J(\alpha \|Q\|_{L^1} + \varepsilon, \|j(f_n^1)\|_{L^1}) \geq J(\alpha \|Q\|_{L^1} + \varepsilon, \|j(Q)\|_{L^1}).$$

By choosing $\varepsilon < \frac{1-\alpha}{2} \|Q\|_{L^1}$, we ensure that

$$J(\alpha \|Q\|_{L^1} + \varepsilon, \|j(Q)\|_{L^1}) \geq J\left(\frac{1+\alpha}{2} \|Q\|_{L^1}, \|j(Q)\|_{L^1}\right) > 1$$

and then

$$\mathcal{H}(f_n^1) = \| |v|^2 f_n^1 \|_{L^1} \left(1 - \frac{1}{K(f_n^1)}\right) \geq C_1 \| |v|^2 f_n^1 \|_{L^1}, \quad (3.22)$$

where $C_1 > 0$ does not depend of ε and n , which gives

$$\liminf_{n \rightarrow +\infty} \mathcal{H}(f_n^1) \geq 0, \quad \text{and similarly} \quad \liminf_{n \rightarrow +\infty} \mathcal{H}(f_n^2) \geq 0. \quad (3.23)$$

Moreover, we have

$$\begin{aligned} \mathcal{H}(\hat{f}_n) &= \| |v|^2 f_n^1 \|_{L^1} + \| |v|^2 f_n^2 \|_{L^1} + \| |v|^2 w_n \|_{L^1} - E_{pot}(f_n) \\ &\geq \mathcal{H}(f_n^1) + \mathcal{H}(f_n^2) - \varepsilon, \end{aligned}$$

where we used (3.21). Passing to the limit in this inequality as $n \rightarrow +\infty$, we obtain

$$\limsup_{n \rightarrow +\infty} (\mathcal{H}(f_n^1) + \mathcal{H}(f_n^2)) \leq \varepsilon.$$

From (3.22), we deduce that

$$\limsup_{n \rightarrow +\infty} (\| |v|^2 f_n^1 \|_{L^1} + \| |v|^2 f_n^2 \|_{L^1}) \leq C\varepsilon,$$

where $C > 0$ is independent of ε . Then, using

$$E_{pot}(f_n^1) + E_{pot}(f_n^2) = \| |v|^2 f_n^1 \|_{L^1} + \| |v|^2 f_n^2 \|_{L^1} - \mathcal{H}(f_n^1) - \mathcal{H}(f_n^2)$$

together with (3.23), we get

$$\limsup_{n \rightarrow +\infty} (E_{pot}(f_n^1) + E_{pot}(f_n^2)) \leq C\varepsilon.$$

For ε small enough, this contradicts (3.19) and (3.21). This proves that dichotomy cannot occur and then compactness follows. In particular, there exists a sequence of translation shifts y_n such that, up to a subsequence,

$$\hat{f}_n(\cdot + y_n) \rightharpoonup \hat{f} \text{ in } L^1(\mathbb{R}^6) \quad \text{and} \quad E_{pot}(\hat{f}_n) \rightarrow E_{pot}(\hat{f}).$$

Moreover, by lower semicontinuity and by (3.19), we have

$$\|j(\hat{f})\|_{L^1} \leq \|j(Q)\|_{L^1} \quad \text{and} \quad K(\hat{f}) \leq \limsup_{n \rightarrow +\infty} K(\hat{f}_n) \leq 1.$$

Therefore, by (2.7), we have

$$1 = J(\|Q\|_{L^1}, \|j(Q)\|_{L^1}) \leq J(\|Q\|_{L^1}, \|j(\hat{f})\|_{L^1}) \leq K(\hat{f}) \leq 1.$$

The strict monotonicity of the function $M_j \mapsto J(M_1, M_j)$ yields

$$\|j(\hat{f})\|_{L^1} = \|j(Q)\|_{L^1} \quad \text{and} \quad K(\hat{f}) = 1.$$

From this, it is now standard to conclude the strong convergence $\hat{f}_n(\cdot + y_n) \rightarrow \hat{f}$ in \mathcal{E}_j . Note that \hat{f} is a minimizer of (1.14) satisfying $\| |v|^2 \hat{f} \|_{L^1} = \| |v|^2 Q \|_{L^1}$.

Furthermore, from the strong L^1 convergence of $\hat{f}_n(\cdot + y_n)$ to \hat{f} and from their equimeasurability deduced from (3.16), one can prove that \hat{f} is equimeasurable to Q (this proof can be done following the same lines as in the above proof of orbital stability for the Poisson-Manev case). Therefore, from Lemma 1.2, one deduces finally that \hat{f} is equal to Q , up to a translation shift. This concludes the proof of Proposition 3.1 and the proof of Theorem 1.3 is complete. \square

4. Self-similar solutions in the pure Manev case

From now on, we only consider the pure Manev case ($\delta = 0$, $\kappa = 1$). This section is devoted to the proof of Theorem 1.5. Let Q be a steady state solution to (1.1) which minimizes (1.14).

We seek, for b small enough, a compactly supported and spherically symmetric stationary profile $Q_b \in \mathcal{C}^0(\mathbb{R}^6)$, with $\phi_{Q_b} \in \mathcal{C}^1(\mathbb{R}^3)$, such that

$$Q_b \left(\frac{x}{\lambda(t)}, \lambda(t)v \right) \quad \text{with} \quad \lambda(t) = \sqrt{2b(T-t)} \quad (4.1)$$

is a solution to (1.1) in the pure Manev case. Inserting (4.1) in (1.1) yields, at least in the weak sense, the Vlasov-Manev system in self-similar variables

$$v \cdot \nabla_x Q_b - \nabla_x \phi_{Q_b} \cdot \nabla_v Q_b + b(x \cdot \nabla_x Q_b - v \cdot \nabla_v Q_b) = 0. \quad (4.2)$$

We first observe that a function of the form

$$g(x, v) = F \left(\frac{|v|^2}{2} + bx \cdot v + \phi_g(x) \right)$$

satisfies this equation. However, for non trivial profiles F and for $b \neq 0$, it can be seen that such a function does not belong to \mathcal{E}_j (it has always infinite mass and energy). To solve this problem we proceed as in [23, 12] and introduce a radial cut-off function χ from \mathbb{R}^3 to $[0, 1]$ such that

$$\chi(x) = 1 \text{ for } |x| < r_\chi \quad \text{and} \quad \chi(x) = 0 \text{ for } |x| > R_\chi = 2r_\chi,$$

where $r_\chi > 0$ will be defined later on (see (4.46)). We shall prove the existence of a function having the form

$$Q_b(x, v) = F \left(\frac{|v|^2}{2} + b\chi(x)x \cdot v + \phi_{Q_b}(x) \right), \quad (4.3)$$

which is compactly supported in $\{|x| < r_\chi\}$. Here, the function ϕ_{Q_b} belongs to \mathcal{C}^1 and the function F is a continuous nonnegative function on \mathbb{R} , which is \mathcal{C}^1 on $] -\infty, e_0[$ for some $e_0 < 0$ and vanishes on $[e_0, +\infty[$. Hence, we have

$$Q_b(x, v) = F \left(\frac{|v|^2}{2} + bx \cdot v + \phi_{Q_b}(x) \right), \quad \forall (x, v) \in \mathbb{R}^6 \text{ such that } |x| < r_\chi,$$

which is sufficient to deduce that Q_b is a solution to (4.2).

To construct such self-similar profile Q_b , it is natural to use a minimization problem with constraints. However, if the number of constraints is finite, which is the case for instance if we prescribe the mass and a Casimir functional as in Section 2, then the uniqueness of the minimizer is not guaranteed. This uniqueness property will be crucial to ensure that Q_b is in the vicinity of Q . Therefore, we will choose a variational problem with an infinite number of constraints which, using Lemma 1.2, will lead to a unique minimizer. More precisely, we define the following set of constraints:

$$\text{Eq}(Q) = \{f \in \mathcal{E}_j : f \text{ is equimeasurable with } Q\}. \quad (4.4)$$

Then we consider the associated variational problem

$$T_b := \inf \{T_b(f) : f \in \text{Eq}(Q), \text{ spherically symmetric with } E_{\text{pot}}(f) = E_{\text{pot}}(Q)\}, \quad (4.5)$$

where

$$T_b(f) = \int_{\mathbb{R}^6} \left(\frac{|v|^2}{2} + b\chi(x)x \cdot v \right) f(x, v) dx dv \quad (4.6)$$

and we claim the following Proposition.

Proposition 4.1. *Let Q be a steady state of (1.1) in the pure Manev case which minimizes (1.14). Then there exists $b^* > 0$ such that the following holds. For all $b \in [0, b^*]$, the variational problem (4.5) has at least one minimizer. Moreover, there exists a family of minimizers Q_b of (4.5), taking the form*

$$Q_b(x, v) = F_{Q_b} \left(\frac{|v|^2}{2} + b\chi(x)x \cdot v + \nu_b \phi_{Q_b}(x) \right),$$

where ν_b is a positive constant and $\chi(x)$ has been defined above, and such that, as $b \rightarrow 0$, we have the convergences $\nu_b \rightarrow 1$ and $Q_b \rightarrow Q_0 = Q$ in \mathcal{E}_j . Here, the function Q_b has its support in $\{(x, v) \in \mathbb{R}^6, |x| < r_\chi\}$, the function ϕ_{Q_b} belongs to \mathcal{C}^1 and the function F_{Q_b} is a continuous nonnegative function on \mathbb{R} , which is \mathcal{C}^1 on $] -\infty, e_b[$ for some $e_b < 0$ and vanishes on $[e_b, +\infty[$.

This result will be proved in the sections below. Now, using this Proposition 4.1, we end the proof of Theorem 1.5. To obtain the desired form (4.3) we first rescale the function Q_b given by this proposition as follows:

$$\bar{Q}_b(x, v) = Q_b \left(x, \frac{v}{\nu_b} \right)$$

and set $\tilde{b} = \nu_b b$. This ensures that \bar{Q}_b is a function of

$$\frac{|v|^2}{2} + \tilde{b}\chi(x)x \cdot v + \phi_{\bar{Q}_b}(x).$$

Denoting back \bar{Q}_b and \tilde{b} by Q_b and b respectively, we can conclude that we have constructed a function Q_b of the desired form. To prove that this function is a solution to (4.2), we need the continuity of Q_b on \mathbb{R}^6 and its \mathcal{C}^1 regularity in the interior of its support. This regularity can be deduced in a similar way as for Q , see Section 2.2, Step 3. The proof of Theorem 1.5 is complete. It remains to prove Proposition 4.1. For his purpose, we need some tools which we introduce in the following subsection.

4.1. Reduction to a functional of a modified microscopic energy. Let us first define

$$\Phi_{rad} = \{\phi_f, f \in \mathcal{E}_{j,rad}\}, \text{ with } \mathcal{E}_{j,rad} = \{f \in \mathcal{E}_j, f \text{ spherically symmetric}\}. \quad (4.7)$$

From Lemma B.1, we deduce that there exists a constant $C > 0$ such that, for all $\phi_f \in \Phi_{rad}$, we have

$$\phi_f(r) \geq -\frac{C}{r^{3/2}} \|f\|_{\mathcal{E}_j}. \quad (4.8)$$

Moreover, by interpolation and using (H2), we have

$$\|\rho_f\|_{L^1} + \|\rho_f\|_{L^\alpha} \leq C \|f\|_{\mathcal{E}_j}, \quad \alpha = \frac{5p-3}{3p-1}.$$

Therefore, from Hardy-Littlewood-Sobolev, one deduces that $\phi_f \in L^k$, for all $\frac{3}{2} < k \leq \frac{3(5p-3)}{4p}$, and in particular, since $p > 3$, one has

$$\|\phi_f\|_{L^3} \leq C \|f\|_{\mathcal{E}_j}. \quad (4.9)$$

As we said, we shall construct Q_b as a minimizer of the functional T_b defined by (4.6) under equimeasurability constraint. Similarly as in [14, 15], the key tool to study this variational problem is the symmetrization with respect to the microscopic energy $\frac{|v|^2}{2} + b\chi(x)x \cdot v + \phi(x)$. Before defining this symmetrization, we need to introduce and study the Jacobian associated with this change of variable.

Lemma 4.2 (Definition and properties of the Jacobian $a_{b,\phi}$). *Let $\phi \in \Phi_{rad} \setminus \{0\}$ and $b \in \mathbb{R}_+$. Defining the Jacobian function $a_{b,\phi} : \mathbb{R}_-^* \rightarrow \mathbb{R}^+$ as*

$$a_{b,\phi}(e) = \text{meas} \left\{ (x, v) \in \mathbb{R}^6, \frac{|v|^2}{2} + b\chi(x)x \cdot v + \phi(x) < e \right\}, \quad \forall e < 0,$$

we have the following properties.

(i) *The Jacobian $a_{b,\phi}$ is given by the explicit formula*

$$\forall e < 0, \quad a_{b,\phi}(e) = \frac{32\pi^2\sqrt{2}}{3} \int_0^{+\infty} \left(e - \phi(r) + \frac{(b\chi(r)r)^2}{2} \right)_+^{3/2} r^2 dr. \quad (4.10)$$

(ii) *Let $e_{b,\phi} = \inf \text{ess} \left[\phi(r) - \frac{(b\chi(r)r)^2}{2} \right] \in \mathbb{R}_-^* \cup \{-\infty\}$. Then $a_{b,\phi}(e) = 0$ for all $e \leq e_{b,\phi}$ and $a_{b,\phi}$ is a strictly increasing \mathcal{C}^1 diffeomorphisms from $(e_{b,\phi}, 0)$ onto \mathbb{R}_+^* . We will denote by $a_{b,\phi}^{-1}$ the inverse function of $a_{b,\phi}$.*

(iii) *Let (f_n) be a bounded sequence in $\mathcal{E}_{j,rad} \setminus \{0\}$ and let (e_n, b_n) be a sequence in*

$\mathbb{R}_-^* \times \mathbb{R}^+$ and assume that there exist $f \in \mathcal{E}_{j,rad} \setminus \{0\}$, $e \in \mathbb{R}^- \cup \{-\infty\}$ and $b \in \mathbb{R}^+$ such that

$$f_n \rightharpoonup f \text{ in } L^p(\mathbb{R}^6), \quad e_n \rightarrow e \text{ and } b_n \rightarrow b.$$

Then, by denoting $a_{b,\phi_f}(-\infty) = 0$ and $a_{b,\phi_f}(0) = +\infty$, we have

$$a_{b_n,\phi_{f_n}}(e_n) \rightarrow a_{b,\phi_f}(e) \quad \text{and} \quad \forall s > 0, \quad a_{b_n,\phi_{f_n}}^{-1}(s) \rightarrow a_{b,\phi_f}^{-1}(s).$$

Proof. Proof of (i). We remark that

$$\frac{|v|^2}{2} + b\chi(x)x \cdot v = \frac{1}{2}|v + b\chi(x)x|^2 - \frac{(b\chi(x)|x|)^2}{2}.$$

Hence, by performing the change of variable $w = v + b\chi(x)x$ with respect of the variable v , and passing by the spherical coordinate we find

$$a_{b,\phi}(e) = (4\pi)^2 \int r^2 dr \int \mathbb{1}_{\{\frac{u^2}{2} + \phi(r) - \frac{(b\chi(r)r)^2}{2} < e\}} u^2 du.$$

Formula (4.10) follows. Since $\phi \in \Phi_{rad} \setminus \{0\}$, we have both the control (4.8) and the fact that the set $\{x \in \mathbb{R}^3, \phi(x) < e\}$ is bounded. These two properties ensure that the integral in (4.10) is finite.

Proof of (ii). By dominated convergence, we deduce that $e \mapsto a_{b,\phi}(e)$ is \mathcal{C}^1 on \mathbb{R}_-^* with

$$a'_{b,\phi}(e) = 16\pi^2 \sqrt{2} \int_0^{+\infty} \left(e - \phi(r) + \frac{(b\chi(r)r)^2}{2} \right)_+^{1/2} r^2 dr \geq 0.$$

For $e_{b,\phi} < e < 0$, we have clearly $a'_{b,\phi}(e) > 0$. Let us prove that $a_{b,\phi}(e)$ converges to $+\infty$ as $e \rightarrow 0$. We observe that, for $f \in \mathcal{E}_{j,rad} \setminus \{0\}$ there exists $R > 0$ such that $\|f_R\|_{L^1} = \frac{1}{2}\|f\|_{L^1}$, where $f_R = f\mathbb{1}_{|x| < R}$. Thus one can prove that

$$|\phi_f(r)| \geq |\phi_{f_R}(r)| \sim \frac{\|f_R\|_{L^1}}{2\pi^2 r^2} \quad \text{as } r \rightarrow +\infty, \quad (4.11)$$

which gives

$$a_{b,\phi}(e) \geq C \int_0^{+\infty} \left(e + \frac{C}{1+r^2} \right)^{3/2} r^2 dr.$$

Hence, $a_{b,\phi}(e) \rightarrow +\infty$ as $e \rightarrow 0$. Since, we have clearly $a_{b,\phi}(e_{b,\phi}) = 0$, item (ii) is proved.

Proof of (iii). The sequence (f_n) is bounded in $\mathcal{E}_{j,rad}$. Then, from Lemma B.2 in Appendix B, up to extraction of a subsequence, we have in particular

$$\phi_{f_n} \rightarrow \phi_f \text{ almost everywhere.}$$

From (4.8) and the boundedness of (f_n) in $\mathcal{E}_{j,rad}$, we have

$$\phi_{f_n}(r) \geq -\frac{C}{r^{3/2}}.$$

Thus

$$e_n - \phi_{f_n}(r) + \frac{(b_n\chi(r)r)^2}{2} \leq e_n + \frac{C}{r^{3/2}} + \frac{(b_n\chi(r)r)^2}{2} \rightarrow e_n$$

when r converges to the infinity. Since $e_n \rightarrow e$ as $n \rightarrow +\infty$, this implies that, for $e \in [-\infty, 0)$, the function

$$r \mapsto \left(e_n - \phi_{f_n}(r) + \frac{(b_n\chi(r)r)^2}{2} \right)_+$$

is uniformly compactly supported. Therefore, by dominated convergence, we deduce that

$$a_{b_n, \phi_{f_n}}(e_n) \rightarrow a_{b, \phi_f}(e).$$

Let us now treat the case $e = 0$. Remark first that for all $n \in \mathbb{N}$, we have

$$a_{b_n, \phi_n}(e_n) \geq a_{0, \phi_n}(e_n),$$

and thus it is sufficient to prove that $a_{0, \phi_n}(e_n)$ converges to $a_{b, \phi}(0) = +\infty$ as $n \rightarrow +\infty$. Let $M > 0$ be an arbitrary constant. We know that

$$\forall x \in \mathbb{R}^3, \quad |\phi_f(x)| \geq \frac{C_f}{1 + |x|^2}. \quad (4.12)$$

Denote $\Omega_n = \left\{ x \in \mathbb{R}^3, |\phi_{f_n}(x)| < \frac{C_f}{2(1+|x|^2)} \right\}$ and let $e_0 < 0$ be such that

$$\int_{\mathbb{R}^3} \left(e_0 + \frac{C_f}{2(1+|x|^2)} \right)_+^{3/2} dx > \frac{3M}{4\pi\sqrt{2}}.$$

For n large enough, we have $e_n > e_0$ and thus

$$\begin{aligned} a_{0, \phi_n}(e_n) &\geq \frac{8\pi\sqrt{2}}{3} \int_{\mathbb{R}^3 \setminus \Omega_n} \left(e_0 + \frac{C_f}{2(1+|x|^2)} \right)_+^{3/2} dx \\ &\geq 2M - \frac{8\pi\sqrt{2}}{3} \int_{\Omega_n} \left(e_0 + \frac{C_f}{2(1+|x|^2)} \right)_+^{3/2} dx. \end{aligned} \quad (4.13)$$

To prove that the second term converges to 0 as $n \rightarrow +\infty$, we remark that the set of integration of this term has the form $\Omega_n \cap B(0, R)$ with $R > 0$ independent of n . Now, from (4.12) and from the definition of Ω_n ,

$$\|\phi_{f_n}(x) - \phi_f(x)\|_{L^3(\mathbb{R}^3)}^3 \geq \int_{\Omega_n} \left(\frac{C_f}{2(1+|x|^2)} \right)^3 dx \geq \int_{\Omega_n \cap B(0, R)} \left(\frac{C_f}{2(1+|x|^2)} \right)^3 dx.$$

Since ϕ_{f_n} converges to ϕ_f in $L^3(\mathbb{R}^3)$ by Lemma B.2, we deduce that the measure of the set $\Omega_n \cap B(0, R)$ converges to 0, which implies that the integral

$$\int_{\Omega_n \cap B(0, R)} \left(e_0 + \frac{C_f}{2(1+|x|^2)} \right)_+^{3/2} dx$$

converges to 0 as $n \rightarrow +\infty$. Thus, for n large enough, $a_{b_n, \phi_n}(e_n) \geq a_{0, \phi_n}(e_n) \geq M$, which concludes the proof of the convergence of $a_{b_n, \phi_n}(e_n)$.

Now, we shall prove that for all $s \in \mathbb{R}_+^*$, we have $a_{b_n, \phi_{f_n}}^{-1}(s) \rightarrow a_{b, \phi_f}^{-1}(s)$. Let $e_n := a_{b_n, \phi_{f_n}}^{-1}(s)$. We know from the above result that, if e_n converges to $e \in [-\infty, 0]$, then

$$s = a_{b_n, \phi_{f_n}}(e_n) \rightarrow a_{b, \phi_f}(e).$$

Hence, the sequence (e_n) converges to $e = a_{b, \phi_f}^{-1}(s)$. The proof of Lemma 4.2 is complete. \square

Now, we are ready to construct our symmetrization of f with respect to a given microscopic energy $\frac{|v|^2}{2} + b\chi(x)x \cdot v + \phi(x)$. To that purpose, we first recall that the Schwarz symmetrization Q^* of the function Q is the unique nonincreasing function on \mathbb{R}^+ such that

$$\forall \lambda > 0, \quad \mu_{Q^*}(\lambda) = \mu_Q(\lambda),$$

where

$$\mu_{Q^*}(\lambda) = \text{meas}\{s \in \mathbb{R}^+ : Q^*(s) > \lambda\}, \quad \mu_Q(\lambda) = \{(x, v) \in \mathbb{R}^6 : Q(x, v) > \lambda\}.$$

Note that Q^* is compactly supported and continuous (since Q is compactly supported and continuous). We shall denote

$$r_* = \min\{r \in \mathbb{R}^+ : Q^*(r) = 0\}. \quad (4.14)$$

Lemma 4.3 (Rearrangement with respect to the microscopic energy). *Let $\phi \in \Phi_{\text{rad}} \setminus \{0\}$ and $b \geq 0$. We denote by $Q^{*b, \phi}$ the nonincreasing continuous function of the microscopic energy defined by*

$$Q^{*b, \phi}(x, v) = \begin{cases} Q^* \circ a_{b, \phi} \left(\frac{|v|^2}{2} + b\chi(x)x \cdot v + \phi(x) \right) & \text{if } \frac{|v|^2}{2} + b\chi(x)x \cdot v + \phi(x) < 0, \\ 0 & \text{if } \frac{|v|^2}{2} + b\chi(x)x \cdot v + \phi(x) \geq 0. \end{cases}$$

Then the following holds.

(i) The function $Q^{*b, \phi}$ is compactly supported and

$$\text{Supp}(Q^{*b, \phi}) = \left\{ \frac{|v|^2}{2} + b\chi(x)x \cdot v + \phi(x) < a_{b, \phi}^{-1}(r_*) \right\},$$

where r_* is defined by (4.14).

(ii) We have $Q^{*b, \phi} \in \text{Eq}(Q)$ and

$$\int_{\mathbb{R}^6} |v|^2 Q^{*b, \phi}(x, v) dx dv \leq C(\|\phi\|_{L^3}^2 + b^2). \quad (4.15)$$

(iii) Let (f_n) be a bounded sequence of $\mathcal{E}_{j, \text{rad}} \setminus \{0\}$ and let (b_n) be a sequence of \mathbb{R}^+ such that $f_n \rightharpoonup f \neq 0$ in $L^p(\mathbb{R}^6)$ and $b_n \rightarrow b$. Then,

$$Q^{*b_n, \phi_{f_n}} \rightarrow Q^{*b, \phi_f} \quad \text{in } L^1(\mathbb{R}^6) \cap L^p(\mathbb{R}^6).$$

(iv) For all $f \in \text{Eq}(Q)$, spherically symmetric, and for all $\nu > 0$, we have

$$\int \left(\frac{|v|^2}{2} + b\chi(x)x \cdot v + \nu\phi_f(x) \right) \left(Q^{*b, \nu\phi_f}(x, v) - f(x, v) \right) dx dv \leq 0 \quad (4.16)$$

with equality if, and only if, $f = Q^{*b, \nu\phi_f}$.

Proof. We first remark that property (i) is a direct consequence of the definition of $Q^{*b, \phi}$.

Proof of (ii). Recall that, for all $\lambda > 0$,

$$\mu_{Q^{*b, \phi}} = \text{meas} \left\{ (x, v) \in \mathbb{R}^6, \quad Q^{*b, \phi}(x, v) > \lambda \right\}. \quad (4.17)$$

If $\lambda \geq Q^*(0) = \|Q\|_{L^\infty}$, we clearly have $\mu_{Q^{*b, \phi}}(\lambda) = 0 = \mu_Q(\lambda)$. If $\lambda < Q^*(0)$, then we have

$$\begin{aligned} \mu_{Q^{*b, \phi}}(\lambda) &= \text{meas} \left\{ (x, v) \in \mathbb{R}^6, a_{b, \phi} \left(\frac{|v|^2}{2} + b\chi(x)x \cdot v + \phi(x) \right) < \sup\{r, Q^*(r) > \lambda\} \right\} \\ &= \sup\{r, Q^*(r) > \lambda\} = \mu_Q(\lambda). \end{aligned}$$

Thus the functions $Q^{*b, \phi}$ and Q are equimeasurable. To estimate its kinetic energy, we remark that

$$T_b(Q^{*b, \phi}) \geq \int \left(\frac{|v|^2}{2} - bR_\chi|v| \right) Q^{*b, \phi} \geq \frac{1}{4} \int |v|^2 Q^{*b, \phi} - b^2 R_\chi^2 \|Q\|_{L^1}. \quad (4.18)$$

Moreover, from the definition of $Q^{*b,\phi}$, one deduces that

$$\begin{aligned} T_b(Q^{*b,\phi}) &= \int \left(\frac{|v|^2}{2} + b\chi(x)x \cdot v + \phi(x) \right) Q^{*b,\phi}(x, v) dx dv - \int \phi(x) Q^{*b,\phi}(x, v) dx dv \\ &\leq - \int \phi(x) Q^{*b,\phi}(x, v) dx dv \leq \|\phi\|_{L^3} \|\rho_{Q^{*b,\phi}}\|_{L^{3/2}} \\ &\leq C \|\phi\|_{L^3} \|Q^{*b,\phi}\|_{L^3}^{1/2} \| |v|^2 Q^{*b,\phi} \|_{L^1}^{1/2} \leq C \|\phi\|_{L^3} \| |v|^2 Q^{*b,\phi} \|_{L^1}^{1/2}, \end{aligned}$$

where we used an interpolation inequality and $\|Q^{*b,\phi}\|_{L^3} = \|Q\|_{L^3}$. Combining this with (4.18) gives the control of the kinetic energy (4.15).

Proof of (iii). From the continuity of Q^* and from Lemma 4.2 (ii) and (iii), we clearly have, for any sequence $e_n \rightarrow e$,

$$Q^* \circ a_{b_n, \phi_{f_n}}(e_n) \rightarrow Q^* \circ a_{b, \phi_f}(e).$$

Moreover, by Lemma B.2, up to a subsequence, $\phi_{f_n} \rightarrow \phi_f$ almost everywhere in \mathbb{R}^6 . Denoting

$$e_n(x, v) = \frac{|v|^2}{2} + b_n \chi(x) x \cdot v + \phi_{f_n}(x), \quad e(x, v) = \frac{|v|^2}{2} + b \chi(x) x \cdot v + \phi_f(x),$$

we deduce that

$$\text{for a.e. } (x, v) \in \mathbb{R}^6, \quad e_n(x, v) \rightarrow e(x, v).$$

Thus Q^{*b_n, ϕ_n} converges to $Q^{*b, \phi}$ almost everywhere in \mathbb{R}^6 and the equimeasurability of Q^{*b_n, ϕ_n} and $Q^{*b, \phi}$ gives the convergence in $L^1 \cap L^p$.

Proof of (iv). Let $f \in \text{Eq}(Q)$ be spherically symmetric and let $\nu > 0$. We have $\phi := \nu \phi_f = \phi_{\nu f} \in \Phi_{rad} \setminus \{0\}$. We denote $\bar{f} = Q^{*b, \phi}$ and we use the layer cake representation

$$f(x, v) = \int_{t=0}^{\|f\|_\infty} \mathbf{1}_{t < f(x, v)} dt.$$

Then from Fubini's theorem,

$$\begin{aligned} &\int_{\mathbb{R}^6} \left(\frac{|v|^2}{2} + b\chi(x)x \cdot v + \phi(x) \right) (f(x, v) - \bar{f}(x, v)) dx dv \\ &= \int_{t=0}^{\|f\|_\infty} dt \int_{\mathbb{R}^6} \left(\mathbf{1}_{t < f(x, v)} - \mathbf{1}_{t < \bar{f}(x, v)} \right) \left(\frac{|v|^2}{2} + b\chi(x)x \cdot v + \phi \right) dx dv \\ &= \int_{t=0}^{\|f\|_\infty} dt \int_{\mathbb{R}^6} \left(\mathbf{1}_{\bar{f}(x, v) \leq t < f(x, v)} - \mathbf{1}_{f(x, v) \leq t < \bar{f}(x, v)} \right) \left(\frac{|v|^2}{2} + b\chi(x)x \cdot v + \phi \right) dx dv \\ &= \int_{t=0}^{\|f\|_\infty} dt \left(\int_{S_1(t)} \left(\frac{|v|^2}{2} + b\chi(x)x \cdot v + \phi \right) dx dv - \int_{S_2(t)} \left(\frac{|v|^2}{2} + b\chi(x)x \cdot v + \phi \right) dx dv \right), \end{aligned}$$

with

$$S_1(t) = \{\bar{f}(x, v) \leq t < f(x, v)\}, \quad S_2(t) = \{f(x, v) \leq t < \bar{f}(x, v)\}.$$

Now, from the equimeasurability of f and \bar{f} , we have

$$\forall t > 0, \quad \text{meas}(S_1(t)) = \text{meas}(S_2(t))$$

and, since \bar{f} is a nonincreasing function of $\frac{|v|^2}{2} + b\chi(x)x \cdot v + \phi(x)$,

$$\begin{aligned} a_2(t) &= \sup_{(x,v) \in S_2(t)} \left\{ \frac{|v|^2}{2} + b\chi(x)x \cdot v + \phi(x) \right\} \\ &\leq \inf_{(x,v) \in S_1(t)} \left\{ \frac{|v|^2}{2} + b\chi(x)x \cdot v + \phi(x) \right\} = a_1(t). \end{aligned}$$

Thus

$$\begin{aligned} \int_{S_2(t)} \left(\frac{|v|^2}{2} + b\chi(x)x \cdot v + \phi(x) \right) dx dv &\leq \text{meas}(S_2(t))a_2(t) \leq \text{meas}(S_1(t))a_1(t) \\ &\leq \int_{S_1(t)} \left(\frac{|v|^2}{2} + b\chi(x)x \cdot v + \phi(x) \right) dx dv, \end{aligned}$$

which yields (4.16). In the case of equality in this above chain of inequalities, it is easy to prove that $f = \bar{f}$, see for instance [14, 15]. \square

4.2. Existence of self-similar solutions. The goal of this subsection is to prove Proposition 4.1.

Step 1: uniform bounds. Let $0 < b \leq 1$ be given. In this step, we prove that T_b is finite and that there exists $C^* > 0$, independent of b , such that all minimizing sequence $(f_n^b)_{n \in \mathbb{N}}$ of (4.5) satisfies, for n large enough,

$$\|f_n^b\|_{\varepsilon_j} \leq C^*. \quad (4.19)$$

For all $(x, v) \in \mathbb{R}^6$, we have

$$\frac{|v|^2}{2} + b\chi(x)x \cdot v \geq \frac{|v|^2}{2} - bR_\chi|v| \geq \frac{|v|^2}{4} - b^2R_\chi^2$$

and so, for all $f \in \text{Eq}(Q)$, we have

$$T_b(f) \geq \frac{1}{4} \int |v|^2 f - b^2 R_\chi^2 \|Q\|_{L^1}. \quad (4.20)$$

This shows that $T_b > -\infty$. Moreover, if $(f_n^b)_{n \in \mathbb{N}}$ is a minimizing sequence of the variational problem (4.5), then for n large enough we have

$$T_b(f_n^b) \leq 1 + T_b \leq 1 + T_b(Q) \leq 1 + C \int |v|^2 Q.$$

This, combined with (4.20) yields the existence of C^* .

Step 2. For all $b \in \mathbb{R}_+$, let $(f_n^b)_{n \in \mathbb{N}}$ be a minimizing sequence for (4.5). In this step, we show that there exists a sequence (ν_n^b) of positive numbers such that $(Q^{*b, \nu_n^b \phi_{f_n^b}})$, defined by Lemma 4.3, is also a minimizing sequence of (4.5). The interest of this new minimizing sequence is its compactness property, as it will be proved in the third step.

Lemma 4.4. *There exists $b^* > 0$ such that the following holds true. For all $b \in [0, b^*]$ and for all minimizing sequence $(f_n^b)_{n \in \mathbb{N}}$ of the variational problem (4.5), there exist $0 < \nu^- < \nu^+$ and a sequence of positive numbers $(\nu_n^b)_{n \in \mathbb{N}}$ in $[\nu^-, \nu^+]$ such that, up to a subsequence, we have $E_{\text{pot}}(Q^{*b, \nu_n^b \phi_{f_n^b}}) = E_{\text{pot}}(Q)$. Moreover, we have $T_b(Q^{*b, \nu_n^b \phi_{f_n^b}}) \leq T_b(f_n^b)$ with equality if and only if $Q^{*b, \nu_n^b \phi_{f_n^b}} = f_n^b$.*

Proof of Lemma 4.4. Let $b > 0$ be given and consider a minimizing sequence $(f_n^b)_{n \in \mathbb{N}}$ of the variational problem (4.5). From Step 1, we know that (for n large enough), this sequence satisfies the bound (4.19).

We first observe that $\nu \mapsto E_{pot}(Q^{*b, \nu \phi_{f_n^b}})$ is continuous on \mathbb{R}_+^* . Indeed, by Lemma 4.3 (iii), we know that $\nu \mapsto Q^{*b, \nu \phi_{f_n^b}}$ is continuous from \mathbb{R}_+^* to $L^1(\mathbb{R}^6) \cap L^p(\mathbb{R}^6)$. Hence, from the kinetic control (4.15) and Lemma B.2 of Appendix B, one deduces the continuity of $\nu \mapsto E_{pot}(Q^{*b, \nu \phi_{f_n^b}})$.

We claim now that, for b small enough, there exist $0 < \nu^- < \nu^+$ such that, up to a subsequence with respect of n , we have

$$E_{pot}(Q^{*b, \nu^- \phi_{f_n^b}}) < E_{pot}(Q) < E_{pot}(Q^{*b, \nu^+ \phi_{f_n^b}}). \quad (4.21)$$

Since $Q^{*b, \nu \phi_{f_n^b}} \in \text{Eq}(Q)$, we have, by (1.7),

$$0 < E_{pot}(Q^{*b, \nu \phi_{f_n^b}}) \leq C \int_{\mathbb{R}^6} |v|^2 Q^{*b, \nu \phi_{f_n^b}}(x, v) dx dv. \quad (4.22)$$

Furthermore, the control of the kinetic energy (4.15), together with (4.9), gives

$$\int |v|^2 Q^{*b, \nu \phi_{f_n^b}} \leq C(\nu^2 \|f_n^b\|_{\mathcal{E}_j}^2 + b^2) \leq C((C^* \nu)^2 + b^2),$$

where we also used (4.19). Hence from (4.22), one deduces that there exists $b_1^* \in (0, 1]$ and $\nu^- > 0$ such that for all $b \in [0, b_1^*]$ and for all n , we have

$$E_{pot}(Q^{*b, \nu^- \phi_{f_n^b}}) < E_{pot}(Q).$$

Note that b_1^* depends only on Q , and does not depend on the sequence (f_n^b) .

Let us now prove the second part of the claim (4.21). Since the sequence $(f_n^b)_{n \in \mathbb{N}}$ is bounded in \mathcal{E}_j , Lemma B.2 of Appendix B implies that there exists $f_b \in \mathcal{E}_{j, rad}$ such that up to a subsequence, as $n \rightarrow +\infty$,

$$f_n^b \rightharpoonup f_b \text{ in } L^p(\mathbb{R}^6), \quad E_{pot}(f_b) = \lim_{n \rightarrow +\infty} E_{pot}(f_n^b) = E_{pot}(Q).$$

In particular, $f_b \neq 0$ and, by Lemma 4.3 (iii), for all $\nu > 0$ we have

$$Q^{*b, \nu \phi_{f_n^b}} \rightarrow Q^{*b, \nu \phi_{f_b}} \text{ in } L^1(\mathbb{R}^6) \cap L^p(\mathbb{R}^6) \text{ as } n \rightarrow +\infty.$$

Thus, from the kinetic control (4.15), $(Q^{*b, \nu \phi_{f_n^b}})$ is bounded in \mathcal{E}_j and spherically symmetric, which implies that $E_{pot}(Q^{*b, \nu \phi_{f_n^b}})$ converges to $E_{pot}(Q^{*b, \nu \phi_{f_b}})$ as $n \rightarrow +\infty$. Consequently, to prove the claim (4.21), it is sufficient to show that, if b is small enough, there exist ν^+ such that $E_{pot}(Q^{*b, \nu^+ \phi_{f_b}}) > E_{pot}(Q)$. This result will be a consequence of the following lemma, which is proved later.

Lemma 4.5. *There exists $b_2^* > 0$ such that the following holds true. For all $f \in \mathcal{E}_{j, rad}$ satisfying*

$$E_{pot}(f) = E_{pot}(Q), \quad \|f\|_{L^1} \leq \|Q\|_{L^1}, \quad \|j(f)\|_{L^1} \leq \|j(Q)\|_{L^1} \quad (4.23)$$

and

$$T_b(f) + \frac{(bR_\chi)^2}{2} \|f\|_{L^1} \leq T_b + \frac{(bR_\chi)^2}{2} \|Q\|_{L^1}, \quad (4.24)$$

for some $b \in [0, b_2^*]$, we have

$$\limsup_{\nu \rightarrow +\infty} E_{pot}(Q^{*b, \nu \phi_f}) > E_{pot}(Q). \quad (4.25)$$

Before proving Lemma 4.5, let us use it to end the proof of Lemma 4.4. Let us check that f_b satisfies the assumptions of Lemma 4.5, for $b \leq b_2^*$. Note that b_2^* given by this lemma is independent of the function f_b . First, f_b satisfies Assumption (4.23) because of the weak convergence of (f_n^b) to (f_b) and of the strong convergence of the potential energies. To prove that f_b satisfies Assumption (4.24), we remark that

$$\forall (x, v) \in \mathbb{R}^6, \frac{|v|^2}{2} + b\chi(x)x \cdot v + \frac{(bR_\chi)^2}{2} = \frac{|v + b\chi(x)x|^2}{2} + \frac{(bR_\chi)^2 - (b\chi(x)|x|)^2}{2} \geq 0.$$

Hence, by lower semicontinuity, one has

$$T_b(f_b) + \frac{(bR_\chi)^2}{2} \|f_b\|_{L^1} \leq \liminf_{n \rightarrow +\infty} \left(T_b(f_n^b) + \frac{(bR_\chi)^2}{2} \|f_n^b\|_{L^1} \right) = T_b + \frac{(bR_\chi)^2}{2} \|Q\|_{L^1}.$$

Therefore, we may apply Lemma 4.5 and get the existence of ν^+ such that, for $b \leq b_2^*$,

$$E_{pot}(Q^{*b, \nu^+ \phi_{f_b}}) > E_{pot}(Q).$$

Hence the claim (4.21) holds true for all $0 \leq b \leq b^* = \min(b_1^*, b_2^*)$. Note that b^* is independent of the sequence (f_n^b) . One can chose $\nu_n^b \in [\nu^-, \nu^+]$ such that for all n , we have $E_{pot}(Q^{*b, \nu_n^b \phi_{f_n^b}}) = E_{pot}(Q)$.

Now, it remains to show the second part of Lemma 4.4. We have

$$\begin{aligned} T_b(Q^{*b, \nu_n^b \phi_{f_n^b}}) &= \int \left(\frac{|v|^2}{2} + b\chi(x)x \cdot v + \nu_n^b \phi_{f_n^b}(x) \right) Q^{*b, \nu_n^b \phi_{f_n^b}}(x, v) dx dv \\ &\quad - \nu_n^b \int \phi_{f_n^b}(x) Q^{*b, \nu_n^b \phi_{f_n^b}}(x, v) dx dv \\ &\leq T_b(f_n^b) + \nu_n^b \int \phi_{f_n^b}(x) f_n^b(x, v) dx dv - \nu_n^b \int \phi_{f_n^b}(x) Q^{*b, \nu_n^b \phi_{f_n^b}}(x, v) dx dv, \end{aligned}$$

from the inequality (4.16). Observing that

$$- \int \phi_{f_n^b}(x) Q^{*b, \nu_n^b \phi_{f_n^b}}(x, v) dx dv = \frac{1}{2} \left(E_{pot}(f_n^b) + E_{pot}(Q^{*b, \nu_n^b \phi_{f_n^b}}) - E_{pot}(Q^{*b, \nu_n^b \phi_{f_n^b}} - f_n^b) \right),$$

we get

$$T_b(Q^{*b, \nu_n^b \phi_{f_n^b}}) \leq T_b(f_n^b) + \frac{\nu_n^b}{2} \left(E_{pot}(Q^{*b, \nu_n^b \phi_{f_n^b}}) - E_{pot}(f_n^b) \right) - \frac{\nu_n^b}{2} E_{pot}(Q^{*b, \nu_n^b \phi_{f_n^b}} - f_n^b).$$

Since

$$E_{pot}(Q^{*b, \nu_n^b \phi_{f_n^b}}) = E_{pot}(f_n^b) = E_{pot}(Q),$$

we deduce that $T_b(Q^{*b, \nu_n^b \phi_{f_n^b}}) \leq T_b(f_n^b)$. By Lemma 4.3 (iv), this inequality becomes an equality if and only if $f_n^b = Q^{*b, \nu_n^b \phi_{f_n^b}}$. The proof of Lemma 4.4 is complete. \square

Proof of Lemma 4.5. We proceed by contradiction. We suppose that there exists a sequence b_k going to 0 as $k \rightarrow +\infty$ and a sequence (f_k) such that, for all k , the function $f_k \in \mathcal{E}_j$ satisfies (4.23), (4.24) and

$$\limsup_{\nu \rightarrow +\infty} E_{pot}(Q^{*b_k, \nu \phi_{f_k}}) \leq E_{pot}(Q). \quad (4.26)$$

From the Cauchy-Schwarz inequality, we have for all $\nu > 0$

$$- \int_{\mathbb{R}^6} \phi_{f_k} Q^{*b_k, \nu \phi_{f_k}} \leq E_{pot}(Q^{*b_k, \nu \phi_{f_k}})^{\frac{1}{2}} E_{pot}(f_k)^{\frac{1}{2}}, \quad (4.27)$$

and thus the inequality (4.26) implies, for all k ,

$$\limsup_{\nu \rightarrow +\infty} \left(- \int_{\mathbb{R}^6} \phi_{f_k} Q^{*b_k, \nu \phi_{f_k}} \right) \leq E_{pot}(Q). \quad (4.28)$$

Moreover, by Lemma 4.3 (i), for all k , we have

$$\begin{aligned} \text{Supp}(Q^{*b_k, \nu \phi_{f_k}}) &\subset \left\{ (x, v), \quad \frac{|v|^2}{2} - b_k R_\chi |v| + \nu \phi_{f_k}(x) < a_{b_k, \nu \phi_{f_k}}^{-1}(r_*) \right\} \\ &\subset \left\{ (x, v), \quad \phi_{f_k}(x) < \frac{a_{b_k, \nu \phi_{f_k}}^{-1}(r_*)}{\nu} + \frac{(b_k R_\chi)^2}{2\nu} \right\}. \end{aligned}$$

Now, from the explicit expression of $a_{b_k, \nu \phi_{f_k}}$ and for $e = a_{b_k, \nu \phi_{f_k}}^{-1}(r_*)$, we get

$$r_* = a_{b_k, \nu \phi_{f_k}}(e) \geq a_{0, \nu \phi_{f_k}}(e) = \nu^{3/2} a_{0, \phi_{f_k}}\left(\frac{e}{\nu}\right),$$

and then,

$$\frac{e}{\nu} + \frac{(b_k R_\chi)^2}{2\nu} \leq a_{0, \phi_{f_k}}^{-1}(\nu^{-3/2} r_*) + \frac{(b_k R_\chi)^2}{2\nu}. \quad (4.29)$$

Since, as $\nu \rightarrow +\infty$, the right-hand side of (4.29) goes to $a_{0, \phi_{f_k}}^{-1}(0) = -\|\phi_{f_k}\|_{L^\infty} \in [-\infty, 0[$, we deduce that

$$\limsup_{\nu \rightarrow +\infty} \left(- \int_{\mathbb{R}^6} \phi_{f_k} Q^{*b_k, \nu \phi_{f_k}} \right) \geq \|\phi_{f_k}\|_{L^\infty} \|Q\|_{L^1} \geq \|\phi_{f_k}\|_{L^\infty} \|f_k\|_{L^1} \geq E_{pot}(f_k). \quad (4.30)$$

Hence, from (4.28) and $E_{pot}(f_k) = E_{pot}(Q)$, the inequalities in (4.30) are all equalities. Thus the sequence (f_k) satisfies for all k ,

$$\|f_k\|_{L^1} = \|Q\|_{L^1} \quad \text{and} \quad \|\phi_{f_k}\|_{L^\infty} \|f_k\|_{L^1} = E_{pot}(Q). \quad (4.31)$$

Now we will prove that (f_k) is a minimizing sequence for the variational problem (1.14) with $M_1 = \|Q\|_{L^1}$ and $M_j = \|j(Q)\|_{L^1}$. First, from (4.24) and (4.31), we have $T_{b_k}(f_k) \leq T_{b_k}$. Combining it with

$$T_{b_k}(f_k) \geq \int \frac{|v|^2}{2} f_k - b_k R_\chi \int \frac{1 + |v|^2}{2} f_k \geq (1 - b_k R_\chi) \int \frac{|v|^2}{2} f_k - \frac{b_k R_\chi}{2} \|Q\|_{L^1} \quad (4.32)$$

and with

$$T_{b_k} \leq T_{b_k}(Q) = \int \frac{|v|^2}{2} Q \quad (4.33)$$

given by the definition of T_{b_k} and the radial symmetry of Q , we obtain

$$\limsup_{k \rightarrow +\infty} \int \frac{|v|^2}{2} f_k \leq \int \frac{|v|^2}{2} Q. \quad (4.34)$$

Finally, using $E_{pot}(f_k) = E_{pot}(Q)$, $\mathcal{H}(Q) = 0$ and the interpolation inequality (1.7) which gives a lower bound for $\| |v|^2 f_k \|_{L^1}$, one gets

$$\|f_k\|_{L^1} = \|Q\|_{L^1}, \quad \limsup_{k \rightarrow +\infty} \|j(f_k)\|_{L^1} \leq \|j(Q)\|_{L^1} \quad \text{and} \quad \limsup_{k \rightarrow +\infty} \frac{\mathcal{H}(f_k)}{\| |v|^2 f_k \|_{L^1}} \leq 0. \quad (4.35)$$

Thus, following the proof of Proposition 3.1, one deduces that there exists a minimizer f of the variational problem (1.14) with $M_1 = \|Q\|_{L^1}$ and $M_j = \|j(Q)\|_{L^1}$ having the same kinetic energy as Q , and such that, up to a subsequence,

$$\hat{f}_k(x, v) = f_k \left(\lambda_k x, \frac{v}{\lambda_k} \right) \rightarrow f \text{ in } \mathcal{E}_j, \quad \text{where } \lambda_k = \left(\frac{\| |v|^2 Q \|_{L^1}}{\| |v|^2 f_k \|_{L^1}} \right)^{1/2}. \quad (4.36)$$

Recall that Q is a steady state of (1.1), thus $J(M_1, M_j) = 1$. Since $\int |v|^2 f = \int |v|^2 Q$, this yields $E_{pot}(f) = E_{pot}(Q)$. Furthermore, from

$$E_{pot}(Q) = E_{pot}(f_k) = \lambda_k^2 E_{pot}(\hat{f}_k) \text{ and } E_{pot}(\hat{f}_k) \rightarrow E_{pot}(f) = E_{pot}(Q),$$

we deduce that

$$\lambda_k \rightarrow 1 \text{ as } k \rightarrow +\infty.$$

Moreover, we deduce from Theorem 1.1 that f is continuous and satisfies the expression (1.15). Therefore ϕ_f cannot be constant on $\text{Supp}(\rho_f)$, which implies

$$E_{pot}(Q) = E_{pot}(f) < \|\phi_f\|_{L^\infty} \|f\|_{L^1} = \|\phi_f\|_{L^\infty} \|Q\|_{L^1}. \quad (4.37)$$

On the other hand, from (4.31) and the rescaling inequalities of Appendix A, we get

$$\|\phi_{\hat{f}_k}\|_{L^\infty} = \lambda_k^2 \frac{E_{pot}(f)}{\|f\|_{L^1}} \rightarrow \frac{E_{pot}(f)}{\|f\|_{L^1}} \text{ as } k \rightarrow +\infty.$$

Hence, since $\phi_{\hat{f}_k}$ converges to ϕ_f in L^3 , we have

$$\|\phi_f\|_{L^\infty} \leq \lim_{k \rightarrow +\infty} \|\phi_{\hat{f}_k}\|_{L^\infty} = \frac{E_{pot}(f)}{\|f\|_{L^1}},$$

which contradicts the strict inequality (4.37). The proof of Lemma 4.5 is complete. \square

Step 3: construction of Q_b , minimizer of (4.5). Let $b \in [0, b^*]$, where b^* is defined in Lemma 4.4, and let f_n^b be a minimizing sequence of the variational problem (4.5). Then, the sequence (ν_n^b) given by Lemma 4.4 lies in a compact interval $[\nu^-, \nu^+]$. Up to a subsequence, (ν_n^b) converges to some $\bar{\nu}_b > 0$ as $n \rightarrow +\infty$. By Lemma 4.3, we have

$$Q^{*b, \nu_n^b \phi_{f_n^b}} \rightarrow Q^{*b, \bar{\nu}_b \phi_{f_b}} \text{ in } L^1 \cap L^p,$$

where $f_n^b \rightharpoonup f_b$ in L^p . Moreover, from the kinetic control (4.15), $(Q^{*b, \nu_n^b \phi_{f_n^b}})$ is bounded in $\mathcal{E}_{j, rad}$ and thus,

$$E_{pot}(Q^{*b, \bar{\nu}_b \phi_{f_b}}) = \lim_{n \rightarrow +\infty} E_{pot}(Q^{*b, \nu_n^b \phi_{f_n^b}}) = E_{pot}(Q).$$

Let us denote $Q_b := Q^{*b, \bar{\nu}_b \phi_{f_b}}$ and make another rearrangement. Applying Lemma 4.4, there exists $\nu_b > 0$ such that

$$(i) \ E_{pot}(Q^{*b, \nu_b \phi_{Q_b}}) = E_{pot}(Q).$$

$$(ii) \ T_b(Q^{*b, \nu_b \phi_{Q_b}}) \leq T_b(Q_b) \text{ with equality only if } Q^{*b, \nu_b \phi_{Q_b}} = Q_b.$$

By lower semicontinuity, we have

$$T_b \leq T_b(Q_b) \leq \liminf_{n \rightarrow +\infty} T_b(Q^{*b, \nu_n^b \phi_{f_n^b}}) \leq \lim_{n \rightarrow +\infty} T_b(f_n^b) = T_b.$$

Therefore $T_b(Q^{*b, \nu_b \phi_{Q_b}}) = T_b(Q_b) = T_b$ which implies that $Q_b = Q^{*b, \nu_b \phi_{Q_b}}$. In particular, Q_b takes the desired form (4.3) and similar arguments as in Section 2.2, Step 3, give the regularity of Q_b stated in Theorem 1.5.

Step 4. We prove here that the above constructed sequence (Q_b) converges to Q in \mathcal{E}_j , as $b \rightarrow 0$. Remark first that $Q_0 = Q$ and then $\nu_0 = 1$. Indeed, we claim that Q_0 and Q are two radially symmetric equimeasurable steady states of (1.1) (with $\delta = 0$), which minimize (1.14), and have the same kinetic energy. This enables to apply Lemma 1.2 (ii) and conclude that $Q_0 = Q$. Let us prove this claim. First, since Q is a steady state of (1.1) which minimizes (1.14), and since Q_0 is equimeasurable to Q , we have

$$K(Q_0) \geq K(Q) = 1.$$

Second, Q_0 being a minimizer of (4.5) with $b = 0$, and since $E_{pot}(Q_0) = E_{pot}(Q)$, we also have

$$K(Q) \geq K(Q_0).$$

This yields $K(Q) = K(Q_0) = 1$ and then Q and Q_0 are both minimizers of (1.14). Since these functions are equimeasurable, the claim is proved.

Now, similarly as for (4.34), one can prove that

$$\limsup_{b \rightarrow 0} \int \frac{|v|^2}{2} Q_b \leq \int \frac{|v|^2}{2} Q.$$

Moreover, since Q is a minimizer of (1.14), the function Q_b satisfies $\int |v|^2 Q_b \geq \int |v|^2 Q$ for all b . Thus, we have

$$\int \frac{|v|^2}{2} Q_b \rightarrow \int \frac{|v|^2}{2} Q \quad \text{as } b \rightarrow 0 \quad (4.38)$$

and the sequence (Q_b) satisfies

$$Q_b \in \text{Eq}(Q) \quad \text{and} \quad \frac{\mathcal{H}(Q_b)}{\| |v|^2 Q_b \|_{L^1}} \rightarrow 0.$$

Thus, by Proposition 3.1, one deduces that we have

$$Q_b \left(\lambda_b x, \frac{v}{\lambda_b} \right) \rightarrow Q \text{ in } \mathcal{E}_j, \quad \text{where } \lambda_b = \left(\frac{\| |v|^2 Q \|_{L^1}}{\| |v|^2 Q_b \|_{L^1}} \right)^{1/2}. \quad (4.39)$$

From (4.38), we finally deduce that $\lambda_b \rightarrow 1$ and that

$$Q_b \rightarrow Q \text{ in } \mathcal{E}_j \quad \text{as } b \rightarrow 0. \quad (4.40)$$

Step 5: convergence of (ν_b) as $b \rightarrow 0$. We recall that Q_b takes the form (4.3), thus satisfies the equation

$$v \cdot \nabla_x Q_b - \nu_b \nabla_x \phi_{Q_b} \cdot \nabla_v Q_b + b \chi(x) (x \cdot \nabla_x Q_b - v \cdot \nabla_v Q_b) - b(x \cdot v) \nabla_x \chi \cdot \nabla_v Q_b = 0. \quad (4.41)$$

We aim to apply Lemma C.1. Multiply the two last terms of (4.41) by $x \cdot v$ and integrate on \mathbb{R}^6 . Integrations by parts give

$$\int_{\mathbb{R}^6} (x \cdot v) b \chi(x) (x \cdot \nabla_x Q_b - v \cdot \nabla_v Q_b) dx dv = -b \int_{\mathbb{R}^6} (x \cdot v) (x \cdot \nabla \chi) Q_b dx dv$$

and

$$- \int_{\mathbb{R}^6} b(x \cdot v)^2 \nabla_x \chi \cdot \nabla_v Q_b dx dv = +2b \int_{\mathbb{R}^6} (x \cdot v) (x \cdot \nabla \chi) Q_b dx dv.$$

Then, from Lemma C.1,

$$\nu_b E_{pot}(Q) - \int_{\mathbb{R}^6} |v|^2 Q_b(x, v) dx dv = b \int_{\mathbb{R}^6} (x \cdot v)(x \cdot \nabla \chi) Q_b dx dv, \quad (4.42)$$

where

$$\left| b \int_{\mathbb{R}^6} (x \cdot v)(x \cdot \nabla \chi) Q_b dx dv \right| \leq b R_\chi^2 \|\nabla \chi\|_{L^\infty} \frac{\|Q\|_{L^1} + \||v|^2 Q_b\|_{L^1}}{2}.$$

Using (4.38), (4.42) and $\mathcal{H}(Q) = 0$, we obtain $\nu_b \rightarrow 1$ as $b \rightarrow 0$.

Step 6: choice of r_χ . Now, we seek r_χ such that, for all $b \in [0, b^*]$, $\text{Supp}(\rho_{Q_b}) \subset B(0, r_\chi)$. We have seen that Lemma 4.3 (i) gives

$$\text{Supp}(Q_b) \subset \left\{ (x, v), \nu_b \phi_{Q_b}(x) < a_{b, \nu_b \phi_{Q_b}}^{-1}(r_*) + \frac{(b^* R_\chi)^2}{2} \right\}, \quad (4.43)$$

where r_* is defined by (4.14). Remark first that from the continuity of the function $(b, \phi) \mapsto a_{b, \phi}^{-1}(r_*)$ in Lemma 4.2, we deduce

$$a_{b, \nu_b \phi_{Q_b}}^{-1}(r_*) \rightarrow a_{0, \phi_Q}^{-1}(r_*) < 0 \quad \text{as } b \rightarrow 0.$$

Let $b_3^* > 0$ small enough such that

$$\frac{a_{b, \nu_b \phi_{Q_b}}^{-1}(r_*)}{\nu_b} < \frac{a_{0, \phi_Q}^{-1}(r_*)}{2}, \quad \frac{(b^* R_\chi)^2}{2\nu_b} < \frac{|a_{0, \phi_Q}^{-1}(r_*)|}{4} \quad \text{and} \quad \|Q_b\|_{\mathcal{E}_j} \leq 2\|Q\|_{\mathcal{E}_j},$$

where we recall that $Q_b \rightarrow Q$ in \mathcal{E}_j . Then, for $b \leq \min(b^*, b_3^*)$, (4.43) yields

$$\text{Supp}(\rho_{Q_b}) \subset \left\{ x \in \mathbb{R}^3, \quad \phi_{Q_b}(x) < \frac{a_{0, \phi_Q}^{-1}(r_*)}{4} \right\}. \quad (4.44)$$

Moreover, by (4.8), the function ϕ_{Q_b} satisfies

$$\phi_{Q_b}(x) \geq -\frac{C\|Q_b\|_{\mathcal{E}_j}}{|x|^{3/2}} \geq -\frac{2C\|Q\|_{\mathcal{E}_j}}{|x|^{3/2}}, \quad (4.45)$$

where C is a universal constant. Now we set

$$r_\chi = \left(\frac{8C\|Q\|_{\mathcal{E}_j}}{a_{0, \phi_Q}^{-1}(r_*)} \right)^{2/3}. \quad (4.46)$$

From (4.44) and (4.45), renaming $b^* = \min(b^*, b_3^*)$, we deduce that, for $0 \leq b \leq b^*$, we have

$$\text{Supp}(\rho_{Q_b}) \subset \{x \in \mathbb{R}^3, |x| < r_\chi\}.$$

The proof of Proposition 4.1 is complete. \square

Appendix A. Rescalings

Let $f \in \mathcal{E}_j$ and let $\gamma > 0$, $\lambda > 0$ and $\mu > 0$. Then the rescaled function \tilde{f} defined by $\tilde{f}(x, v) = \gamma f(\frac{x}{\lambda}, \mu v)$ satisfies the following identities.

Norms

$$\|\tilde{f}\|_{L^1} = \gamma \frac{\lambda^3}{\mu^3} \|f\|_{L^1} \quad ; \quad \|j(\tilde{f})\|_{L^1} = \frac{\lambda^3}{\mu^3} \|j(\gamma f)\|_{L^1} \quad ; \quad \||v|^2 \tilde{f}\|_{L^1} = \gamma \frac{\lambda^3}{\mu^5} \||v|^2 f\|_{L^1}.$$

Functions

$$\rho_{\tilde{f}}(x) = \frac{\gamma}{\mu^3} \rho_f \left(\frac{x}{\lambda} \right) \quad ; \quad \phi_{\tilde{f}}^P(x) = \gamma \frac{\lambda^2}{\mu^3} \phi_f^P \left(\frac{x}{\lambda} \right) \quad ; \quad \phi_{\tilde{f}}^M(x) = \gamma \frac{\lambda}{\mu^3} \phi_f^M \left(\frac{x}{\lambda} \right).$$

Potential energy

$$E_{pot}^P(\tilde{f}) = \gamma^2 \frac{\lambda^5}{\mu^6} E_{pot}^P(f) \quad ; \quad E_{pot}^M(\tilde{f}) = \gamma^2 \frac{\lambda^4}{\mu^6} E_{pot}^M(f).$$

Lemma A.1. *Let $f \in \mathcal{E}_j \setminus \{0\}$ and $M_1, M_j > 0$. Then there exists an unique pair of positive constants (γ, λ) such that the rescaled function \tilde{f} defined by*

$$\tilde{f}(x, v) = \gamma f \left(\frac{\gamma^{1/3}}{\lambda^{1/3}} x, v \right) \tag{A.1}$$

satisfies $\|\tilde{f}\|_{L^1} = M_1$ and $\|j(\tilde{f})\|_{L^1} = M_j$. Moreover, γ and λ satisfy

$$\lambda = \frac{M_1}{\|f\|_{L^1}} \quad \text{and} \quad \min(\gamma^{p-1}, \gamma^{q-1}) \leq \frac{M_j \|f\|_{L^1}}{M_1 \|j(f)\|_{L^1}} \leq \max(\gamma^{p-1}, \gamma^{q-1}). \tag{A.2}$$

Proof. The rescaling (A.1) gives immediately

$$\|\tilde{f}\|_{L^1} = \lambda \|f\|_{L^1} \quad \text{and} \quad \|j(\tilde{f})\|_{L^1} = \frac{\lambda}{\gamma} \|j(\gamma f)\|_{L^1}.$$

Hence, \tilde{f} satisfies $\|\tilde{f}\|_{L^1} = M_1$ and $\|j(\tilde{f})\|_{L^1} = M_j$ as soon as

$$\lambda = \frac{M_1}{\|f\|_{L^1}} \quad \text{and} \quad \frac{\|j(\gamma f)\|_{L^1}}{\gamma \|j(f)\|_{L^1}} = \frac{M_j \|f\|_{L^1}}{M_1 \|j(f)\|_{L^1}}.$$

The first parameter λ is then uniquely determined. Notice also that (A.2) is a direct consequence of the nondichotomy condition (1.9). It remains to prove the existence of a unique suitable γ .

Consider now the function of $\gamma \in \mathbb{R}_+^*$ defined by

$$h(\gamma) = \frac{\|j(\gamma f)\|_{L^1}}{\gamma \|j(f)\|_{L^1}}.$$

From the nondichotomy condition (1.9), we have

$$\lim_{\gamma \rightarrow 0} h(\gamma) = 0, \quad \lim_{\gamma \rightarrow +\infty} h(\gamma) = +\infty.$$

Moreover, from a direct calculation, one gets

$$h'(\gamma) = \frac{\|j'(\gamma f) f\|_{L^1}}{\gamma \|j(f)\|_{L^1}} - \frac{\|j(\gamma f)\|_{L^1}}{\gamma^2 \|j(f)\|_{L^1}} \geq (p-1) \frac{\|j(\gamma f)\|_{L^1}}{\gamma^2 \|j(f)\|_{L^1}} > 0,$$

where we used Assumption (H3) on the function j . Hence, there exists a unique $\gamma \in \mathbb{R}_+^*$ such that

$$h(\gamma) = \frac{M_j \|f\|_{L^1}}{M_1 \|j(f)\|_{L^1}}$$

and the Lemma is proved. \square

Appendix B. Some properties of radially symmetric potentials

Lemma B.1. *There exists a constant $C > 0$ such that, for all $f \in \mathcal{E}_j$ spherically symmetric, we have for all $x \in \mathbb{R}^3$*

$$-\frac{C}{|x|} \|f\|_{L^1} \leq \phi_f^P(x) \leq 0. \quad (\text{B.1})$$

Moreover, for all $0 < \alpha < 1$, there exists a constant $C_\alpha > 0$ such that, for all $f \in \mathcal{E}_j$ spherically symmetric, we have for all $x \in \mathbb{R}^3$

$$-\frac{C_\alpha}{|x|^{1+\alpha}} \|f\|_{\mathcal{E}_j} \leq \phi_f^M(x) \leq 0, \quad (\text{B.2})$$

Recall that ϕ_f^P and ϕ_f^M are defined by (1.3).

Proof. Passing to the spherical coordinate $s = |y|$ and $x \cdot y = 2rs \cos \theta$ in (1.3), one gets

$$\phi_f^P(x) = - \int_0^{+\infty} \int_0^\pi \frac{\rho_f(s) \sin \theta}{2(s^2 + r^2 - 2rs \cos \theta)^{1/2}} s^2 ds d\theta = - \int_0^{+\infty} \rho_f(s) g_r^P(s) s^2 ds, \quad (\text{B.3})$$

$$\phi_f^M(x) = -\frac{1}{\pi} \int_0^{+\infty} \int_0^\pi \frac{\rho_f(s) \sin \theta}{s^2 + r^2 - 2rs \cos \theta} s^2 ds d\theta = -\frac{1}{\pi} \int_0^{+\infty} \rho_f(s) g_r^M(s) s^2 ds, \quad (\text{B.4})$$

where

$$g_r^P(s) = \frac{\mathbf{1}_{\{s < r\}}(s)}{r} + \frac{\mathbf{1}_{\{s > r\}}(s)}{s} \quad \text{and} \quad g_r^M(s) = \frac{1}{sr} \ln \left| \frac{r+s}{r-s} \right|.$$

Note that

$$g_r^P(s) = \frac{1}{r} g_1^P\left(\frac{s}{r}\right) \quad \text{and} \quad g_r^M(s) = \frac{1}{r^2} g_1^M\left(\frac{s}{r}\right).$$

Since g_1^P belongs to L^∞ , (B.3) yields directly (B.1). Next, we remark that g_1^M belongs to $L^k((0, +\infty), s^2 ds)$ for all $k \in (3, +\infty)$, which gives

$$\|g_r^M\|_{L^k((0, +\infty), s^2 ds)} \leq \frac{C}{r^{2-\frac{3}{k}}}.$$

We finally obtain (B.2) by applying the Hölder inequality to (B.4). Indeed, thanks to interpolation inequalities and under Assumption (H2), $f \in \mathcal{E}_j$ implies that $\rho_f \in L^1 \cap L^{3/2}((0, +\infty), s^2 ds)$. The proof of the lemma is complete. \square

Lemma B.2. *Let $(f_n)_{n \geq 1}$ be a bounded sequence of \mathcal{E}_j such that ρ_{f_n} is radially symmetric. Then there exists $f \in \mathcal{E}_j$ such that, up to a subsequence,*

$$\begin{cases} (i) & f_n \rightharpoonup f \text{ in } L^p(\mathbb{R}^6), \\ (ii) & E_{\text{pot}}(f_n) \rightarrow E_{\text{pot}}(f), \\ (iii) & \text{for all } \frac{3}{2} < q < \frac{3(5p-3)}{4p}, \quad \phi_{f_n}^M \rightarrow \phi_f^M \text{ in } L^q(\mathbb{R}^3). \end{cases}$$

Proof. Since $p > 1$, we have $f_n \rightharpoonup f$ in $L^p(\mathbb{R}^6)$ up to subsequence, which yields (i). Let us prove (ii). The convergence of the Poisson potential energy is well-known, see e.g. [11]. Let us prove the convergence of the Manev potential energy. We remark that

$$E_{\text{pot}}^M(f_n) = \|h_{f_n}\|_{L^2}^2 \quad \text{with} \quad h_{f_n} = (-\Delta)^{-1/4} \rho_{f_n}.$$

Hence, from (1.7), we deduce that the sequence h_{f_n} is bounded in L^2 . Moreover, by interpolation, we have that ρ_{f_n} is bounded in $L^1 \cap L^{p_0}$ with $p_0 = \frac{5p-3}{3p-1} \in (\frac{3}{2}, \frac{5}{3}]$

and then, by standard Sobolev inequalities, the sequence $((-\Delta)^\varepsilon h_{f_n})$ is bounded in $L^2(\mathbb{R}^3)$ for $\varepsilon > 0$ small enough. This yields some local compactness and we have $h_{f_n} \rightarrow h_f$ in $L^2_{loc}(\mathbb{R}^3)$. Hence, to conclude Item (ii), it suffices to prove a uniform decay at the infinity. For all $R > 0$, we have

$$\begin{aligned} \|h_{f_n}\|_{L^2(|x|>R)} &= \int_{|x|>R} |\phi_{f_n}^M(x)| |\rho_{f_n}(x)| dx \\ &\leq C \|\rho_{f_n}\|_{L^{3/2}} \left(\int_{|x|>R} |\phi_{f_n}^M(x)|^3 dx \right)^{1/3} \\ &\leq C \left(\int_{|x|>R} \frac{1}{|x|^{9/2}} dx \right)^{1/3} = \frac{C'}{R^{3/2}} \end{aligned}$$

where we used a Hölder inequality, the uniform boundedness of ρ_{f_n} in $L^{3/2}$ and (B.2) with $\alpha = 1/2$. Finally, we have proved that $h_{f_n} \rightarrow h_f$ in $L^2(\mathbb{R}^3)$, which gives in particular $E_{pot}^M(f_n) \rightarrow E_{pot}^M(f)$.

The proof of (iii) is similar. It is sufficient to remark that $\phi_{f_n}^M = (-\Delta)^{-1/2} \rho_{f_n}$ to obtain the local compactness of $(\phi_{f_n}^M)$ in $L^q(\mathbb{R}^3)$ and the uniform decay at the infinity, given by B.2, enables to conclude. \square

Appendix C. Virial identity

In this Appendix, we prove the following lemma.

Lemma C.1. *Let $f \in \mathcal{E}_j$ be a continuous and compactly supported function which satisfies*

$$v \cdot \nabla_x f - \nabla_x \phi_f^M \cdot \nabla_v f = g \quad (\text{C.1})$$

in the distributional sense, where g belongs to $L^1(\mathbb{R}^6)$. Then the following virial identity holds:

$$E_{pot}^M(f) - \int_{\mathbb{R}^6} |v|^2 f(x, v) dx dv = - \int_{\mathbb{R}^6} (x \cdot v) g(x, v) dx dv. \quad (\text{C.2})$$

Proof. First, integrations by parts give

$$\int_{\mathbb{R}^6} (x \cdot v) (v \cdot \nabla_x f) dx dv = - \int_{\mathbb{R}^6} |v|^2 f(x, v) dx dv$$

and

$$- \int_{\mathbb{R}^6} (x \cdot v) \nabla_x \phi_f^M \cdot \nabla_v f dx dv = \int_{\mathbb{R}^3} \rho_f x \cdot \nabla_x \phi_f^M dx.$$

Therefore, it remains to prove that this term is well defined and satisfies

$$\int_{\mathbb{R}^3} \rho_f x \cdot \nabla_x \phi_f^M dx = E_{pot}^M(f). \quad (\text{C.3})$$

We observe that $\rho_f \in L^1 \cap L^\infty(\mathbb{R}^3)$ since f is continuous and compactly supported. In particular, we have $(-\Delta)^{1/2} \phi_f^M = -\rho_f \in L^2(\mathbb{R}^3)$. Moreover, from (1.3) we get $\phi_f^M \in L^q(\mathbb{R}^3)$ for all $q \in [\frac{3}{2}, +\infty]$, in particular $\phi_f^M \in L^2(\mathbb{R}^3)$. We thus have $\phi_f^M \in H^1(\mathbb{R}^3)$ and the integral in (C.3) is well defined.

Let us now regularize the Manev kernel, setting for $\varepsilon > 0$

$$\phi_f^\varepsilon(x) = -(-\Delta)^{-1/2-\varepsilon/2}\rho_f = -C_\varepsilon \int_{\mathbb{R}^3} \frac{\rho_f(y)}{|x-y|^{2-\varepsilon}} dy.$$

We have clearly $\phi_f^\varepsilon \rightarrow \phi_f^M$ in $H^1(\mathbb{R}^3)$ as $\varepsilon \rightarrow 0$ and then

$$\lim_{\varepsilon \rightarrow 0} \int_{\mathbb{R}^3} \rho_f x \cdot \nabla_x \phi_f^\varepsilon dx = \int_{\mathbb{R}^3} \rho_f x \cdot \nabla_x \phi_f^M dx.$$

Moreover, we have

$$\begin{aligned} \int_{\mathbb{R}^3} \rho_f x \cdot \nabla_x \phi_f^\varepsilon dx &= (2-\varepsilon)C_\varepsilon \int_{\mathbb{R}^3} \rho_f(x)\rho_f(y) \frac{x \cdot (x-y)}{|x-y|^{4-\varepsilon}} dx dy \\ &= \frac{2-\varepsilon}{2}C_\varepsilon \int_{\mathbb{R}^3} \frac{\rho_f(x)\rho_f(y)|x-y|^2}{|x-y|^{4-\varepsilon}} dx dy. \end{aligned}$$

Passing to the limit as $\varepsilon \rightarrow 0$ yields (C.3). The proof is complete. \square

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